

$\mathcal{ML}(\theta\mathcal{C})$ -Space in Topological Spaces

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ABSTRACT

The purpose of this paper is to introduced a new concept of spaces which is called minimal $L(\theta\mathcal{C})$ -space, namely $\mathcal{Min}L(\theta\mathcal{C})$ -space or $\mathcal{ML}(\theta\mathcal{C})$ -space, also given some properties, examples, theorems and the topological property of $\mathcal{Min}L(\theta\mathcal{C})$ -space are discussed.

KEYWORDS: θ -closed set, Lindelof, $L(\theta\mathcal{C})$ -space, $\mathcal{Min}\theta\mathcal{T}_2$ -space, $\mathcal{Min}\mathcal{K}(\theta\mathcal{C})$ -space

الخلاصة

الهدف من هذا البحث هو تقديم مفهوم جديد وهو فضاء minimal $L(\theta\mathcal{C})$ -space ونرمز له $\mathcal{Min}L(\theta\mathcal{C})$ -space او $\mathcal{ML}(\theta\mathcal{C})$ -space، وكذلك اعطينا بعض الامثلة، النظريات و الخاصية التوبولوجية نوقشت.

INTRODUCTION

The concept of Lindelof space was introduced in 1929 by Alexandrof and Urysohn [2], this space is an important in a topological space. Later, in 1979 Mukherji and Sarkar [10], provide the concept of LC -space. (A topological space \mathcal{X} is called LC -space, if every Lindelof subset of a space \mathcal{X} is a closed set). LC -space studied by many researchers such as [3].

Notices that LC -space is also know under the name L -closed such as [6, 9, 13].

The concept of θ -closed and θ -open set were first introduced by Velicko [16] in 1969. (Let $(\mathcal{X}, \mathcal{T})$ be a topological space, \mathcal{F} be a subset of \mathcal{X} and $x \in \mathcal{X}$. A point x is called θ -interior point of \mathcal{F} , if there is $\mathcal{C} \in \mathcal{T}$, such that $x \in \mathcal{C}$ and $x \in \bar{\mathcal{C}} \subseteq \mathcal{F}$. θ -interior set which denoted by $Int_{\theta}(\mathcal{F})$ is the set of all θ -interior points. A subset \mathcal{F} of \mathcal{X} is called θ -open set iff $Int_{\theta}(\mathcal{F}) = \mathcal{F}$. And (Let $(\mathcal{X}, \mathcal{T})$ be topological space, $H \subseteq \mathcal{X}$, a point $b \in \mathcal{X}$ is said to be θ -adherent point for a subset H of \mathcal{X} , if $H \cap \bar{G} \neq \emptyset$ for any open set G of \mathcal{X} and $b \in G$. The set of θ -adherent points is said to be θ -closure of H which denoted by $Cl_{\theta}(H)$. A subset H of \mathcal{X} is called θ -closed set iff $H = Cl_{\theta}(H)$). These concepts have been studied by many authors such as [8, 12]. In 2011, Al-Taai and Haider [4], study

the new term called $L(\theta\mathcal{C})$ -space. (A topological space \mathcal{X} is called $L(\theta\mathcal{C})$ -space, if every Lindelof subset of a space \mathcal{X} is θ -closed set), which is a strong than LC -space. And since the union of θ -closed set may be not θ -closed set. Encourage the author to define \mathcal{F}_{σ} - θ -closed set which is a countable union many θ -closed sets.

In 2005, H. J. Ali [3], introduce Minimal LC -space, any LC -space $(\mathcal{X}, \mathcal{T})$ is $\mathcal{Min}LC$ -space, if $\mathcal{T}^* \subset \mathcal{T}$ on \mathcal{X} , then $(\mathcal{X}, \mathcal{T}^*)$ is not LC -space studied by [14, 15].

The aim of this paper is to introduce a minimal $L(\theta\mathcal{C})$ -space (denoted by $\mathcal{Min}L(\theta\mathcal{C})$ -space), that is a space \mathcal{X} which is $L(\theta\mathcal{C})$ -space is called $\mathcal{Min}L(\theta\mathcal{C})$ -space, if $\mathcal{T}^* \subset \mathcal{T}$ on \mathcal{X} , then $(\mathcal{X}, \mathcal{T}^*)$ is not $L(\theta\mathcal{C})$ -space. Note that every $\mathcal{Min}L(\theta\mathcal{C})$ -space is $L(\theta\mathcal{C})$ -space, and study some properties of this space, also study the relation between this concept with $\mathcal{Min}\mathcal{K}(\theta\mathcal{C})$ -space and $\mathcal{Min}\theta\mathcal{T}_2$ -space. Also study some important property such as, a topological property of $\mathcal{Min}L(\theta\mathcal{C})$ -space.

PRELIMINARIES

Definition (2.1) [5]: A space \mathcal{X} is called \mathcal{R}_1 -space, if e and d have a disjoint neighborhoods, whenever $Cl(e) \neq Cl(d)$.

Remark (2.2) [5]: A space \mathcal{X} is \mathcal{T}_2 -space iff \mathcal{X} is \mathcal{R}_1 and \mathcal{T}_1 -space.

Definition (2.3) [16]: Let (X, \mathcal{T}) be a topological space, \mathcal{F} be a subset of X and $x \in X$. A point x is called θ -interior point of \mathcal{F} , if there is $\mathcal{C} \in \mathcal{T}$, such that $x \in \mathcal{C}$ and $x \in \bar{\mathcal{C}} \subseteq \mathcal{F}$. θ -interior set which denoted by $Int_\theta(\mathcal{F})$ is the set of all θ -interior points. A subset \mathcal{F} of X is called θ -open set iff $Int_\theta(\mathcal{F}) = \mathcal{F}$.

Definition (2.4) [16]: Let (X, \mathcal{T}) be topological space, $H \subseteq X$, a point $b \in X$ is said to be θ -adherent point for a subset H of X , if $H \cap \bar{G} \neq \emptyset$ for any open set G of X and $b \in G$. The set of θ -adherent points is said to be θ -closure of H which denoted by $Cl_\theta(H)$. A subset H of X is called θ -closed set iff $H = Cl_\theta(H)$.

Example (2.5): Any subset of a discrete space $(\mathcal{R}, \mathcal{D})$ on a real numbers \mathcal{R} is θ -closed set and θ -open set.

Remark (2.6) [16]: Every θ -closed (resp. θ -open) set is a closed (resp. open) set.

Lemma (2.7) [3]: Let \mathcal{Y} be a subspace of a space X . If \mathcal{P} is θ -closed in X then \mathcal{P} is θ -closed in \mathcal{Y} , whenever $\mathcal{P} \subseteq \mathcal{Y}$.

Definition (2.8) [1, 4]: A subset \mathcal{F} of a space X is said to be \mathcal{F}_σ - θ -closed, if it is a countable union of θ -closed sets. The complement of \mathcal{F}_σ - θ -closed is said to be G_δ - θ -open set.

Remark (2.9) [1]: Every θ -closed set is \mathcal{F}_σ - θ -closed set. But the converse need not be true.

Example (2.10): Let $(\mathcal{R}, \mathcal{T}_U)$ be a usual topology on a real line \mathcal{R} , and $G_n = [1/n, 1]$, where $(n = 2, 3, 4, \dots)$, be a θ -closed sets, then $\bigcup_{n=2}^{\infty} G_n = (0, 1]$ is \mathcal{F}_σ - θ -closed, but neither closed nor θ -closed.

Definition (2.11) [1, 3, 4]: A space X is said to be:

1. θP -space, if every \mathcal{F}_σ - θ -closed is θ -closed.
2. $\mathcal{K}(\theta\mathcal{C})$ -space, if every compact subset of X is θ -closed set.
3. $L(\theta\mathcal{C})$ -space, if every Lindelof subset of X is θ -closed set.

Example (2.12): Let (Z, \mathcal{T}_D) be a topological space where \mathcal{T}_D be a discrete topology on an integer numbers Z , (Z, \mathcal{T}_D) is $L(\theta\mathcal{C})$ -space.

Definition (2.13) [4]: A subset \mathcal{A} of a space X is said to be θ -dense, if $Cl_\theta(\mathcal{A}) = X$.

Proposition (2.14) [3]: The property of $L(\theta\mathcal{C})$ -space is a topological property.

Proposition (2.15) [3]: The property of $L(\theta\mathcal{C})$ -space is a hereditary property.

Theorem (2.16) [4]:

1. If a space X is θL_1 -space and θL_3 -space, then X is $L(\theta\mathcal{C})$ -space.
2. Every θP -space is θL_1 -space.

Definition (2.17) [7]: A space X is called $\theta\mathcal{T}_1$ (resp. \mathcal{T}_1)-space, if every two distinct points a, b belong to X , there is two θ -open (resp. open) sets each one contain one point but not contain the other.

Theorem (2.18) [7]: A space X is called $\theta\mathcal{T}_1$ -space if and only if every singleton set is θ -closed set.

Definition (2.19) [7]: A space X is called $\theta\mathcal{T}_2$ (resp. \mathcal{T}_2)-space, if every two points a, b belong to X , $a \neq b$ there is two disjoint θ -open (resp. open) sets M and N containing a and b respectively.

Remarks (2.20):

1. Every $L(\theta\mathcal{C})$ -space is $\theta\mathcal{T}_1$ -space.
2. Every $\theta\mathcal{T}_1$ -space is \mathcal{T}_1 -space.
3. Every $L(\theta\mathcal{C})$ -space is \mathcal{T}_1 -space.

Proof:

1. Let $\{x\}$ be a Lindelof subset of a space X , for each $x \in X$, which is $L(\theta\mathcal{C})$ -space, so $\{x\}$ is θ -closed set, then from Theorem (2.37), a space X is $\theta\mathcal{T}_1$ -space.

2. Let a, b be two distinct point in a space X which is $\theta\mathcal{T}_1$ -space, so there exist two θ -open sets G and H containing a, b respectively with $a \notin H$ and $b \notin G$, from Remark 2.21, G and H are open set in X , containing a, b respectively with $a \notin H$ and $b \notin G$, that means X is \mathcal{T}_1 -space.

3. Let a space X be $L(\theta\mathcal{C})$ -space, from part (1) of this Remark, X is $\theta\mathcal{T}_1$ -space and from part (2), X is \mathcal{T}_1 -space.

Definition (2.21) [11]: A space X is called $\theta\mathcal{R}_1$ -space, if e and d have a disjoint θ -neighbourhood, whenever $Cl_\theta(e) \neq Cl_\theta(d)$.

Remark (2.22) [11]: A space X is $\theta\mathcal{T}_2$ -space iff X is $\theta\mathcal{R}_1$ and $\theta\mathcal{T}_1$ -space.

Definition (2.23) [8]: Let (X, \mathcal{T}) and (Y, \mathcal{T}') be two topological space and $f: (X, \mathcal{T}) \rightarrow (Y, \mathcal{T}')$ be a function. Then f is called:

1. θ -closed function [1], if $f(F)$ is θ -closed set in Y for each closed subset F of X .
2. Closed function [10], if $f(F)$ is closed set in Y for each closed subset F of X .

Remark (2.24) [1]: Every θ -closed function is closed function.

Definition (2.25) [11]: Let (X, \mathcal{T}) be $\mathcal{K}(\theta\mathcal{C})$ -space, a space X is said to be $Min\mathcal{K}(\theta\mathcal{C})$ -space, if $\mathcal{T}^* \subset \mathcal{T}$ on X , then (X, \mathcal{T}^*) is not $\mathcal{K}(\theta\mathcal{C})$ -space.

Example (2.26): Let $(\mathcal{R}, \mathcal{T}_U)$ be a usual topology defined on the real numbers, $(\mathcal{R}, \mathcal{T}_U)$ is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Theorem (2.27) [11]: If a space X is compact $\mathcal{K}(\theta\mathcal{C})$ -space, then it is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proposition (2.28) [11]: If a space X is Locally compact, $\mathcal{K}(\theta\mathcal{C})$ -space then X is $\theta\mathcal{T}_2$ -space.

Definition (2.29) [11]: A space X is $\theta\mathcal{T}_2$ -space, we say that X is $Min\theta\mathcal{T}_2$ -space, if there is $\mathcal{T}^* \subset \mathcal{T}$ on X , then (X, \mathcal{T}^*) is not $\theta\mathcal{T}_2$ -space.

Theorem (2.30) [11]: If a space X is $\theta\mathcal{T}_2$ and $Min\mathcal{K}(\theta\mathcal{C})$ -space then X is $Min\theta\mathcal{T}_2$ -space.

$MinL(\theta\mathcal{C})$ -Spaces

Definition (3.1): Let (X, \mathcal{T}) be $L(\theta\mathcal{C})$ -space, a space X is said to be $MinL(\theta\mathcal{C})$ -space, if $\mathcal{T}^* \subset \mathcal{T}$ on X , then (X, \mathcal{T}^*) is not $L(\theta\mathcal{C})$ -space.

Example (3.2): Let (X, \mathcal{T}_D) be a discrete topology defined on countable set X , (X, \mathcal{T}_D) is $MinL(\theta\mathcal{C})$ -space, since, if we take any subset \mathcal{H} of a space X , which is countable then \mathcal{H} is countable, so \mathcal{H} is Lindelof, let $x \notin \mathcal{H}$, also $\{x\}$ is open set containing x , also $\overline{\{x\}} \cap \mathcal{H} = \emptyset$, so \mathcal{H} is θ -closed set and then X is $L(\theta\mathcal{C})$ -space, also since $\mathcal{T}_{ind} \subset \mathcal{T}_D$, but \mathcal{T}_{ind} is not $L(\theta\mathcal{C})$ -space. Therefore X is $MinL(\theta\mathcal{C})$ -space.

Theorem (3.3): If a space X is Lindelof $L(\theta\mathcal{C})$ -space, then it is $MinL(\theta\mathcal{C})$ -space.

Proof: Let (X, \mathcal{T}) be $L(\theta\mathcal{C})$ -space and suppose X is not $MinL(\theta\mathcal{C})$ -space, that is there is a topology $\mathcal{T}^* \subset \mathcal{T}$ on X and (X, \mathcal{T}^*) is $L(\theta\mathcal{C})$ -space. Let $I_x: (X, \mathcal{T}) \rightarrow (X, \mathcal{T}^*)$ be the identity function on X . Now I_x is continuous, bijective and θ -closed function since (if \mathcal{N} is a closed subset of X , and X is Lindelof, so \mathcal{N} is Lindelof), also I_x is continuous, then $I_x(\mathcal{N})$ is Lindelof subset of (X, \mathcal{T}^*) which is $L(\theta\mathcal{C})$ -space, hence $I_x(\mathcal{N})$ is θ -closed and then I_x is θ -closed function, by Remark 2.24, I_x is a closed function that is I_x is homeomorphism function, so $\mathcal{T}^* \cong \mathcal{T}$ and this is contradiction, so X is $MinL(\theta\mathcal{C})$ -space.

Example (3.4): Let $X = \mathcal{R}$ be a real numbers, and $\mathcal{T}_{Exc} = \{ \mathcal{U} \subseteq \mathcal{R} : x \notin \mathcal{U}, \text{ for some } x \in \mathcal{R} \} \cup \{ \mathcal{R} \}$, be excluded point topology, $(\mathcal{R}, \mathcal{T}_{Exc})$ is

not $Min\mathcal{K}(\theta\mathcal{C})$ -space, since $(\mathcal{R}, \mathcal{T}_{Exc})$ is compact, so $(\mathcal{R}, \mathcal{T}_{Exc})$ is Lindelof, but not $L(\theta\mathcal{C})$ -space because, if we take $x = 5$ and $\mathcal{C} = \{ \{x\} \}_{x \neq 5} \cup \mathcal{R}$ is an open cover to \mathcal{R} , then we can reduce to just \mathcal{R} that is $(\mathcal{R}, \mathcal{T}_{Exc})$ is Lindelof, also $\{1, 5\}$ is finite set, then it is countable, so it is Lindelof set and $2 \notin \{1, 5\}$, so there is open set $\{2\}$ in \mathcal{R} and $\overline{\{2\}} = \{2, 5\} \cap \{1, 5\} \neq \emptyset$, then $2 \in \theta$ -adherent point, that is $\{1, 5\}$ is not θ -closed set, hence $(\mathcal{R}, \mathcal{T}_{Exc})$ is not $L(\theta\mathcal{C})$ -space and from Theorem 3.3, this topological space is not $MinL(\theta\mathcal{C})$ -space.

Corollary (3.5): Every compact and $L(\theta\mathcal{C})$ -space is $MinL(\theta\mathcal{C})$ -space.

Proof: From Theorem 3.3. And every compact space is Lindelof space.

Remark (3.6): The continuous image of $MinL(\theta\mathcal{C})$ is not necessarily $MinL(\theta\mathcal{C})$, the following example explain this Remark:

Example (3.7): Let $f: (\mathcal{R}, \mathcal{T}_D) \rightarrow (\mathcal{R}, \mathcal{T}_{ind})$ be a function from a discrete topology \mathcal{T}_D into indiscrete topology \mathcal{T}_{ind} , defined by $f(x) = x, \forall x \in \mathcal{R}$, so f is continuous and $(\mathcal{R}, \mathcal{T}_D)$ is $MinL(\theta\mathcal{C})$, also $\mathcal{T}_{ind} \subset \mathcal{T}_D$, but $(\mathcal{R}, \mathcal{T}_{ind})$ is not $L\mathcal{C}$, implies that, it is not $L(\theta\mathcal{C})$. Therefore $(\mathcal{R}, \mathcal{T}_{ind})$ is not $MinL(\theta\mathcal{C})$ -space.

Proposition (3.8): The property of being $MinL(\theta\mathcal{C})$ -space is a topological property.

Proof: Let (X, \mathcal{T}) be $MinL(\theta\mathcal{C})$ -space, $f: (X, \mathcal{T}) \rightarrow (Y, \mathcal{T}')$ is a homeomorphism function, to prove (Y, \mathcal{T}') is $MinL(\theta\mathcal{C})$ -space. Now from Proposition 2.14, (Y, \mathcal{T}') is $L(\theta\mathcal{C})$ -space, suppose (Y, \mathcal{T}') is not $MinL(\theta\mathcal{C})$ -space, then there is a topology $\mathcal{T}^* \subset \mathcal{T}'$ on Y , implies (Y, \mathcal{T}^*) is $L(\theta\mathcal{C})$ -space.

Define $\mathcal{T}_1 = \{ f^{-1}(\mathcal{U}) : \mathcal{U} \in \mathcal{T}^* \}$, so (X, \mathcal{T}_1) is a topology on (X, \mathcal{T}) and $\mathcal{T}_1 \subset \mathcal{T}$ and (X, \mathcal{T}_1) is $L(\theta\mathcal{C})$ -space, (let \mathcal{S} be a Lindelof subset of X , to prove \mathcal{S} is θ -closed in X , since f is continuous and then we have $f(\mathcal{S})$ is Lindelof set in Y which is $L(\theta\mathcal{C})$ -space, then $f(\mathcal{S})$ is θ -closed in (Y, \mathcal{T}^*) , to show \mathcal{S} is θ -closed set, that is to show $\mathcal{S} = Cl_\theta(\mathcal{S})$, since $\mathcal{S} \subseteq Cl_\theta(\mathcal{S})$, let $s \in Cl_\theta(\mathcal{S})$ and $s \notin \mathcal{S}$, since f is injective, then $f(s) \notin f(\mathcal{S})$ and f is surjective, so $w \notin f(\mathcal{S})$ where $w = f(s)$, but $f(\mathcal{S})$ is θ -closed in Y , then there is open set \mathcal{W} in Y with $w \in \mathcal{W}$ and $\overline{\mathcal{W}} \cap f(\mathcal{S}) = \emptyset$, so $f^{-1}(\overline{\mathcal{W}} \cap f(\mathcal{S})) = f^{-1}(\emptyset) = \emptyset$, and $f^{-1}(\overline{\mathcal{W}}) \cap f^{-1}(f(\mathcal{S})) = \emptyset$, then $f^{-1}(\overline{\mathcal{W}}) \cap \mathcal{S} = \emptyset$, since f is

homeomorphism, then $\overline{f^{-1}(\mathcal{W})} \cap \mathcal{S} = \emptyset$, we have s is not θ -adherent point to \mathcal{S} . Therefore \mathcal{S} is θ -closed in \mathcal{X} , which is contradiction, since \mathcal{X} is $MinL(\theta\mathcal{C})$ -space. Hence $(\mathcal{Y}, \mathcal{T}')$ is $MinL(\theta\mathcal{C})$ -space.

Lemma (3.9): In Lindelof space, any θ -closed set is Lindelof set.

Proof: Let \mathcal{X} be a Lindelof space and \mathcal{A} be θ -closed subset of \mathcal{X} . From Remark 2.6, \mathcal{A} is a closed subset of \mathcal{X} . Then \mathcal{A} is Lindelof set.

Proposition (3.10): Let $(\mathcal{Y}, \mathcal{T})$ be a subspace of a Lindelof $L(\theta\mathcal{C})$ -space $(\mathcal{X}, \mathcal{T})$, \mathcal{Y} is Lindelof iff \mathcal{Y} is θ -closed.

Proof: Suppose \mathcal{Y} is Lindelof subspace of \mathcal{X} , since \mathcal{X} is $L(\theta\mathcal{C})$ -space, then \mathcal{Y} is θ -closed. Conversely, suppose \mathcal{Y} is θ -closed in \mathcal{X} , which is Lindelof, then by Lemma 3.9, \mathcal{Y} is Lindelof.

Example (3.11): The discrete topology \mathcal{T}_D on an integer numbers \mathcal{Z} , $(\mathcal{Z}, \mathcal{T}_D)$ is Lindelof $L(\theta\mathcal{C})$ -space, also subspace $(\mathcal{N}, \mathcal{T}_D)$ is Lindelof and θ -closed, where \mathcal{N} is a natural number.

Proposition (3.12): If $(\mathcal{X}, \mathcal{T})$ is a Lindelof $L(\theta\mathcal{C})$ -space, then every θ -closed subspace of \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{Y} be θ -closed in \mathcal{X} , but \mathcal{X} is Lindelof, then by Proposition 3.10, \mathcal{Y} is Lindelof. Now let \mathcal{N} be a Lindelof subset of \mathcal{Y} , then \mathcal{N} is Lindelof in \mathcal{X} , but \mathcal{X} is $L(\theta\mathcal{C})$ -space, so \mathcal{N} is θ -closed in \mathcal{X} . Now $\mathcal{N} = \mathcal{N} \cap \mathcal{Y}$, since $\mathcal{N} \subseteq \mathcal{Y}$, by Lemma 2.7, \mathcal{N} is θ -closed in \mathcal{Y} , hence \mathcal{Y} is $L(\theta\mathcal{C})$ -space and by Theorem 3.3, \mathcal{Y} is $MinL(\theta\mathcal{C})$ -space.

Lemma (3.13): A subset \mathcal{H} of a space \mathcal{X} is G_δ - θ -open set if and only if every point in \mathcal{H} is G_δ - θ -interior point to \mathcal{H} .

Proof: Suppose \mathcal{H} is G_δ - θ -open set and $x \in \mathcal{H}$, then there exists $\mathcal{A} = \bigcap_{i \in \mathbb{N}} \mathcal{A}_i$ which is G_δ - θ -open set and $x \in \mathcal{A} = \mathcal{H} \subseteq \mathcal{H}$, so x is G_δ - θ -interior point to \mathcal{H} , but x is an arbitrary point, so any point in \mathcal{A} is G_δ - θ -interior point to \mathcal{A} . Conversely, suppose any point in \mathcal{H} is G_δ - θ -interior point to \mathcal{H} , that is, for each $x_i \in \mathcal{H}$, there is \mathcal{A}_{x_i} is G_δ - θ -open subset of \mathcal{H} , we get $\mathcal{H} = \bigcup_{x_i \in \mathcal{H}} \mathcal{A}_{x_i}$, then \mathcal{H} is G_δ - θ -open set.

Proposition (3.14): Every Lindelof set in $\theta\mathcal{T}_2$ -space is \mathcal{F}_σ - θ -closed set.

Proof: Let \mathcal{A} be a Lindelof subset of a space \mathcal{X} , and $p \notin \mathcal{A}$, then for each $q \in \mathcal{A}$, $p \neq q$ and $p, q \in \mathcal{X}$, since \mathcal{X} is $\theta\mathcal{T}_2$ -space, then there exist two θ -open sets \mathcal{U} and \mathcal{V} , with $q \in \mathcal{U}$, $p \in \mathcal{V}$ and $\mathcal{U} \cap \mathcal{V} = \emptyset$. Let $\bigcup_{q \in \mathcal{A}} \mathcal{U}_q$ is θ -open cover to \mathcal{A} , then it is open cover to \mathcal{A} which is Lindelof, so

$\mathcal{A} \subseteq \bigcup_{i \in \mathbb{N}} \mathcal{U}_{q_i}$, then $\mathcal{U}^* = \bigcup_{i \in \mathbb{N}} \mathcal{U}_{q_i}$ is open and $\mathcal{V}^* = \bigcap_{i \in \mathbb{N}} \mathcal{V}_{q_i}(p)$, since \mathcal{V}^* is the intersection of countable many θ -open set, then \mathcal{V}^* is G_δ - θ -open set and $\mathcal{V}^* \cap \mathcal{U}^* = \emptyset$, so $p \in \mathcal{V}^* \subseteq \mathcal{A}^c$, then p is G_δ - θ -interior point to \mathcal{A}^c , from Lemma 3.13, \mathcal{A}^c is G_δ - θ -open set. Therefore \mathcal{A} is \mathcal{F}_σ - θ -closed set.

Proposition (3.15): Every \mathcal{F}_σ - θ -closed set in Lindelof space is Lindelof.

Proof: Let \mathcal{H} be \mathcal{F}_σ - θ -closed subset of a space \mathcal{X} , that is $\mathcal{H} = \bigcup_{i \in \mathbb{N}} \mathcal{F}_i$, where \mathcal{F}_i is θ -closed set in \mathcal{X} , but \mathcal{X} is Lindelof space, so by Lemma 3.9, \mathcal{F}_i , $i \in \mathbb{N}$, is Lindelof. Now, $\bigcup_{i \in \mathbb{N}} \mathcal{F}_i$ is Lindelof and $\mathcal{H} = \bigcup_{i \in \mathbb{N}} \mathcal{F}_i$, so \mathcal{H} is Lindelof.

Remark (3.16): Let $(\mathcal{R}, \mathcal{T}_D)$ be a discrete topology on a real numbers \mathcal{R} . Every singleton set is θ -closed, then it is \mathcal{F}_σ - θ -closed set and Lindelof, but $(\mathcal{R}, \mathcal{T}_D)$ is not Lindelof.

Theorem (3.17): Let a space \mathcal{X} is $\theta\mathcal{T}_2$, Lindelof space, then \mathcal{X} is $MinL(\theta\mathcal{C})$ -space iff \mathcal{X} is θP -space.

Proof: Let \mathcal{X} be $MinL(\theta\mathcal{C})$ -space, to prove \mathcal{X} is θP -space. Let \mathcal{A} be \mathcal{F}_σ - θ -closed subset in \mathcal{X} , which is Lindelof, by Proposition 3.15, \mathcal{A} is Lindelof subset of \mathcal{X} , which is $L(\theta\mathcal{C})$ -space, then \mathcal{A} is θ -closed set in \mathcal{X} , Therefore \mathcal{X} is θP -space. Conversely, suppose \mathcal{X} is θP -space, to prove \mathcal{X} is $MinL(\theta\mathcal{C})$ -space, let \mathcal{H} be a Lindelof subset of \mathcal{X} , but \mathcal{X} is $\theta\mathcal{T}_2$ -space, then by Proposition 3.14, \mathcal{H} is \mathcal{F}_σ - θ -closed set, also \mathcal{X} is θP -space, then \mathcal{H} is θ -closed subset of \mathcal{X} , that means \mathcal{X} is $L(\theta\mathcal{C})$ -space and it is Lindelof, so from Theorem 3.3, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proposition (3.18): Every $\theta\mathcal{T}_2$ -space and θP -space is $L(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{M} be a Lindelof subset of \mathcal{X} , but \mathcal{X} is $\theta\mathcal{T}_2$ -space, so by Proposition 3.14, \mathcal{M} is \mathcal{F}_σ - θ -closed set in \mathcal{X} , which is θP -space, hence \mathcal{M} is θ -closed set in \mathcal{X} , therefore \mathcal{X} is $L(\theta\mathcal{C})$ -space.

Theorem (3.19): Every Lindelof $\theta\mathcal{T}_2$ and θP -space is $MinL(\theta\mathcal{C})$ -space.

Proof: Let a space \mathcal{X} be $\theta\mathcal{T}_2$ and θP -space, by Proposition 3.18, \mathcal{X} is $L(\theta\mathcal{C})$ -space and it is Lindelof, so by Theorem 3.3, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proposition (3.20): Every $L(\theta\mathcal{C})$ -space is $\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{B} be a compact subset of a space \mathcal{X} , then \mathcal{B} is Lindelof in \mathcal{X} , but \mathcal{X} is $L(\theta\mathcal{C})$ -space, so \mathcal{B} is θ -closed. Hence \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space.

The convers of Proposition 3.20, is not true as shown by the following example.

Example (3.21): Let $(\mathcal{R}, \mathcal{T}_U)$ be a usual topology on a real numbers \mathcal{R} . The compact subset of this space is only finite sets or closed interval, also they are θ -closed. Therefore, $(\mathcal{R}, \mathcal{T}_U)$ is $\mathcal{K}(\theta\mathcal{C})$ -space. Also, the rational numbers \mathbb{Q} is Lindelof but not θ -closed. Hence $(\mathcal{R}, \mathcal{T}_U)$ is not $L(\theta\mathcal{C})$ -space.

Theorem (3.22): If a space \mathcal{X} is compact and θP -space, then \mathcal{X} is $Min\theta\mathcal{T}_2$ -space iff \mathcal{X} is $\theta\mathcal{T}_2$ -space and $MinL(\theta\mathcal{C})$ -space.

Proof: Suppose a space \mathcal{X} is $Min\theta\mathcal{T}_2$ -space, then \mathcal{X} is $\theta\mathcal{T}_2$ -space, by Proposition 3.18, \mathcal{X} is $L(\theta\mathcal{C})$ -space. Also \mathcal{X} is compact, then \mathcal{X} is Lindelof, hence by Theorem 3.3, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space. Conversely, suppose \mathcal{X} is $\theta\mathcal{T}_2$ -space and $MinL(\theta\mathcal{C})$ -space, so \mathcal{X} is $\theta\mathcal{T}_2$ -space and $L(\theta\mathcal{C})$ -space, by Proposition 3.20, \mathcal{X} is $\theta\mathcal{T}_2$ -space and $\mathcal{K}(\theta\mathcal{C})$ -space, and since \mathcal{X} is compact $\mathcal{K}(\theta\mathcal{C})$ -space, so from Theorem 2.27, \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space, and by Theorem 2.30, \mathcal{X} is $Min\theta\mathcal{T}_2$ -space.

Corollary (3.23): If a space \mathcal{X} is compact and $MinL(\theta\mathcal{C})$ -space, then \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Suppose \mathcal{X} is compact and $MinL(\theta\mathcal{C})$ -space, so \mathcal{X} is compact and $L(\theta\mathcal{C})$ -space, by Proposition 3.20, \mathcal{X} is compact and $\mathcal{K}(\theta\mathcal{C})$ -space, so from Theorem 2.27, we have \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.24): If a space \mathcal{X} is compact and $L(\theta\mathcal{C})$ -space, then \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Suppose \mathcal{X} is compact and $L(\theta\mathcal{C})$ -space, by Proposition 3.20, \mathcal{X} is compact and $\mathcal{K}(\theta\mathcal{C})$ -space, so from Theorem 2.27, \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.25): Every countably compact, Lindelof and $L(\theta\mathcal{C})$ -space is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Suppose \mathcal{X} is countably compact and Lindelof space, then \mathcal{X} is compact, from Corollary 3.24, \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Theorem (3.26): If a space \mathcal{X} is compact and $L(\theta\mathcal{C})$ -space, then a closed subspace of \mathcal{X} is $MinL(\theta\mathcal{C})$ -space and $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{Y} be a closed subspace of a compact space \mathcal{X} , so \mathcal{Y} is compact set in \mathcal{X} , then \mathcal{Y} is Lindelof. Also, \mathcal{X} is $L(\theta\mathcal{C})$ -space, so by Proposition 2.15, \mathcal{Y} is $L(\theta\mathcal{C})$ -space. Hence from Theorem 3.3, \mathcal{Y} is $MinL(\theta\mathcal{C})$ -space. Now, from Proposition 3.20, \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space, so from Theorem 2.27, \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.27): If a space \mathcal{X} is Lindelof and $L(\theta\mathcal{C})$ -space, then a closed subspace of \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{Y} be a closed subset of a Lindelof space \mathcal{X} , then \mathcal{Y} is Lindelof in \mathcal{X} , and then by Proposition 2.15, \mathcal{Y} is $L(\theta\mathcal{C})$ -space, from Theorem 3.3, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Corollary (3.28): If a space \mathcal{X} is Lindelof and $L(\theta\mathcal{C})$ -space, then a θ -closed subspace of \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Corollary (3.29): If a space \mathcal{X} is hereditarily Lindelof and $L(\theta\mathcal{C})$ -space, then any subspace of \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{Y} be a subspace of a space \mathcal{X} , since \mathcal{X} is hereditarily Lindelof, so \mathcal{Y} is Lindelof, also by Proposition 2.15, \mathcal{Y} is $L(\theta\mathcal{C})$ -space, from Theorem 3.3, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Theorem (3.30): If a space \mathcal{X} is compact θP -space, then \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space if and only if \mathcal{X} is $MinL(\theta\mathcal{C})$ -space.

Proof: Suppose \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space, that means \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space and by hypothesis \mathcal{X} is compact, so \mathcal{X} is locally compact space and then from Proposition 2.28, \mathcal{X} is $\theta\mathcal{T}_2$ -space, also \mathcal{X} is Lindelof. Therefore, by Theorem 3.19, \mathcal{X} is $MinL(\theta\mathcal{C})$ -space. Conversely, suppose \mathcal{X} is $MinL(\theta\mathcal{C})$ -space, so \mathcal{X} is $L(\theta\mathcal{C})$ -space, by Proposition 3.20, \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space and it is compact, hence from Theorem 2.27, \mathcal{X} is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Definition (3.31): A space \mathcal{X} is said to be θQ -set space, if any subset of \mathcal{X} is \mathcal{F}_σ - θ -closed set in \mathcal{X} .

Proposition (3.32):

1. Every θQ -set space is θL_3 -space.
2. Every θQ -set space and θL_1 -space is $L(\theta\mathcal{C})$ -space.
3. Every θQ -set space and θP -space is $L(\theta\mathcal{C})$ -space.
4. Every Lindelof θL_1 -space is θP -space.
5. Every θP -space and θL_3 -space is $L(\theta\mathcal{C})$ -space.

Proof:

1. Let \mathcal{H} be a Lindelof subset of θQ -set space \mathcal{X} , then \mathcal{H} is \mathcal{F}_σ - θ -closed set in \mathcal{X} . Therefore, \mathcal{X} is θL_3 -space.
2. Let \mathcal{X} be a θQ -set space \mathcal{X} , by part(1), \mathcal{X} is θL_3 -space, and from Theorem 2.16 part (1), \mathcal{X} is $L(\theta\mathcal{C})$ -space.

3. Let L be a Lindelof subset of θQ -set space \mathcal{X} , then L is \mathcal{F}_σ - θ -closed set in \mathcal{X} which is θP -space, then L is θ -closed set in \mathcal{X} . Therefore, \mathcal{X} is $L(\theta\mathcal{C})$ -space.
4. Let \mathcal{K} be \mathcal{F}_σ - θ -closed set in a Lindelof space \mathcal{X} , then $\mathcal{K} = \bigcup_{i \in \mathbb{N}} \mathcal{H}_i$, where \mathcal{H}_i is θ -closed set in a space \mathcal{X} , for each $i \in \mathbb{N}$, by Lemma 3.9, \mathcal{H}_i is Lindelof, so \mathcal{K} is Lindelof and \mathcal{F}_σ - θ -closed set, since \mathcal{X} is θL_1 -space, then \mathcal{K} is θ -closed set. Therefore, \mathcal{X} is θP -space.
5. Suppose \mathcal{X} is θP -space, by Theorem 2.16, part(2), \mathcal{X} is θL_1 -space and it is θL_3 -space, so by Theorem 2.16, part(1), \mathcal{X} is $L(\theta\mathcal{C})$ -space.

Proposition (3.33):

1. Every Lindelof θL_1 -space and θL_3 -space is $\text{Min}L(\theta\mathcal{C})$ -space.
2. Every Lindelof θL_1 -space and θT_2 -space is $\text{Min}L(\theta\mathcal{C})$ -space.
3. Every Lindelof θQ -set and θL_1 -space is $\text{Min}L(\theta\mathcal{C})$ -space.

Proof:

1. Let a space \mathcal{X} is θL_1 -space and θL_3 -space, the by Theorem 2.16, part(1), \mathcal{X} is $L(\theta\mathcal{C})$ -space and it is Lindelof, so from Theorem 3.3, \mathcal{X} is $\text{Min}L(\theta\mathcal{C})$ -space.
2. Let a space \mathcal{X} is Lindelof θL_1 -space, the by Proposition 3.32 part(4), \mathcal{X} is θP -space, and from Proposition 3.18, \mathcal{X} is $L(\theta\mathcal{C})$ -space, also from Theorem 3.3, \mathcal{X} is $\text{Min}L(\theta\mathcal{C})$ -space.
3. Let a space \mathcal{X} is Lindelof θL_1 -space, the by Proposition 3.32, part (4), \mathcal{X} is θP -space, and from Proposition 3.32, part (3), \mathcal{X} is $L(\theta\mathcal{C})$ -space, also from Theorem 3.3, \mathcal{X} is $\text{Min}L(\theta\mathcal{C})$ -space.

Theorem (3.34): Every $L(\theta\mathcal{C})$ -space having θ -dense Lindelof subset is $\text{Min}L(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{A} be a θ -dense Lindelof subset of a space \mathcal{X} , but \mathcal{X} is $L(\theta\mathcal{C})$ -space, then \mathcal{A} is θ -closed, then $\mathcal{A} = Cl_\theta(\mathcal{A}) = \mathcal{X}$, hence \mathcal{X} is Lindelof and it is $L(\theta\mathcal{C})$ -space, so from Theorem 3.3, \mathcal{X} is $\text{Min}L(\theta\mathcal{C})$ -space.

Proposition (3.35): Every Lindelof θQ -set space and θP -space is $\text{Min}L(\theta\mathcal{C})$ -space.

Proof: From Proposition 3.32, part(3) and Theorem 3.3.

Proposition (3.36): Every compact θQ -set space and θP -space is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let a space \mathcal{X} is θQ -set space and θP -space, then from Proposition 3.32, part(3), \mathcal{X} is $L(\theta\mathcal{C})$ -space and by proposition 3.20, \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space, since \mathcal{X} is compact and $\mathcal{K}(\theta\mathcal{C})$ -space so by Theorem 2.27, \mathcal{X} is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Theorem (3.37): Every compact θQ -set space and θL_1 -space is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let a space \mathcal{X} be θQ -set space and θL_1 -space, so by Proposition 3.32 part (3), \mathcal{X} is $L(\theta\mathcal{C})$ -space, and from Proposition 3.20, \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space, so we have a space \mathcal{X} is compact $\mathcal{K}(\theta\mathcal{C})$ -space, hence by Theorem 2.27, \mathcal{X} is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.38): Every compact θL_1 -space and θL_3 -space is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} be θL_1 and θL_3 -space, from Proposition 2.16, part(1), \mathcal{X} is $L(\theta\mathcal{C})$ -space, also by Proposition 3.20, \mathcal{X} is $\mathcal{K}(\theta\mathcal{C})$ -space and from Theorem 2.27, \mathcal{X} is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.39): Every compact θP -space and θL_3 -space is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} be θP -space, from Theorem 2.16, part(2), \mathcal{X} is θL_1 -space and from Corollary 3.38, \mathcal{X} is $\text{Min}\mathcal{K}(\theta\mathcal{C})$ -space.

Theorem (3.40): If \mathcal{X} and \mathcal{Y} are T_2 -spaces, $L(\theta\mathcal{C})$ -spaces, then $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space.

Proof: Let L be a Lindelof subset of $\mathcal{X} \times \mathcal{Y}$, and let $(x_o, y_o) \notin L$, for each $(x, y) \in L$, then there exists open neighbourhoods \mathcal{U}_x and \mathcal{V}_y of x and y respectively, such that $(x_o, y_o) \notin \overline{\mathcal{U}_x \times \mathcal{V}_y}$, since $L \subseteq \bigcup \{ \mathcal{U}_x \times \mathcal{V}_y : (x, y) \in L \}$, we have $L \subseteq \bigcup \{ \mathcal{U}_{x_n} \times \mathcal{V}_{y_n} : n \in \mathbb{Z}^+, \text{ for some } (x_n, y_n) \in L, n \in \mathbb{Z}^+ \}$. Now, let $E_1 = \{ n \in \mathbb{Z}^+ : x_o \notin \overline{\mathcal{U}_{x_n}} \}$ and $E_2 = \{ n \in \mathbb{Z}^+ : y_o \notin \overline{\mathcal{V}_{y_n}} \}$, then $E_1 \cup E_2 = \mathbb{Z}^+$. And, if $L_1 = \bigcup \{ L \cap (\overline{\mathcal{U}_{x_n}} \times \overline{\mathcal{V}_{y_n}}) : n \in E_1 \}$ and $L_2 = \bigcup \{ L \cap (\overline{\mathcal{U}_{x_n}} \times \overline{\mathcal{V}_{y_n}}) : n \in E_2 \}$, then L_1 and L_2 are Lindelof subset of $\mathcal{X} \times \mathcal{Y}$, such that $L_1 \cup L_2 = L$. Clearly $x_o \notin \pi_1(L_1)$ and since L_1 is Lindelof and π_1 is continuous, then $\pi_1(L_1)$ is Lindelof in \mathcal{X} , and since \mathcal{X} is $L(\theta\mathcal{C})$ -space, then $\pi_1(L_1)$ is θ -closed, by Remark 2.6, $\pi_1(L_1)$ is closed in \mathcal{X} , so there is an open neighbourhood $G \subseteq \mathcal{X}$ of x_o , with $G \cap \pi_1(L_1) = \emptyset$. In the same way, since $y_o \notin \pi_2(L_2)$ and L_2 is Lindelof in \mathcal{Y} , with π_2 is continuous, so $\pi_2(L_2)$ is Lindelof in \mathcal{Y} , and since \mathcal{Y} is $L(\theta\mathcal{C})$ -space, then $\pi_2(L_2)$ is θ -closed, so $\pi_2(L_2)$ is closed in \mathcal{Y} , so there is an

open neighbourhood $H \subseteq \mathcal{Y}$ of x_0 , with $H \cap \pi_2(L_2) = \emptyset$, we now claim $(G \times H) \cap L = \emptyset$, since $(x, y) \in L$, suppose $(x, y) \in (G \times H)$, then $x \in G$, but $G \cap \pi_1(L_1) = \emptyset$, then $x \notin \pi_1(L_1)$, so $(x, y) \notin L_1$, also $y \notin \pi_2(L_2)$, hence $(x, y) \notin L_2$, since $L_1 \cup L_2 = L$ That is $(x, y) \notin L$ and this is contradiction, so $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space.

Corollary (3.41): If \mathcal{X} and \mathcal{Y} are compact \mathcal{T}_2 -spaces and $L(\theta\mathcal{C})$ -spaces, then $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space and $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} and \mathcal{Y} are compact \mathcal{T}_2 -spaces and $L(\theta\mathcal{C})$ -space, then by Theorem 3.40, $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space and then $\mathcal{X} \times \mathcal{Y}$ is compact, also $\mathcal{X} \times \mathcal{Y}$ is Lindelof and $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space, by Theorem 3.3, $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space. Now, by Proposition 3.20, $\mathcal{X} \times \mathcal{Y}$ is $\mathcal{K}(\theta\mathcal{C})$ -space and it is compact, then by Theorem 2.27, $\mathcal{X} \times \mathcal{Y}$ is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Corollary (3.42): If \mathcal{X} and \mathcal{Y} are Lindelof \mathcal{T}_2 -spaces and $L(\theta\mathcal{C})$ -space, then $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} and \mathcal{Y} are compact \mathcal{T}_2 -spaces and $L(\theta\mathcal{C})$ -spaces, then by Theorem 3.40, $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space and from hypothesis $\mathcal{X} \times \mathcal{Y}$ is Lindelof, and the by Theorem 3.3, $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space.

Proposition (3.43): If \mathcal{X} and \mathcal{Y} are \mathcal{R}_1 , $L(\theta\mathcal{C})$ -spaces, then $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} and \mathcal{Y} are $L(\theta\mathcal{C})$ -spaces, by Remarks 2.20, part (3), \mathcal{X} and \mathcal{Y} are \mathcal{T}_1 -spaces, but \mathcal{X} and \mathcal{Y} are \mathcal{R}_1 -spaces, then \mathcal{X} and \mathcal{Y} are \mathcal{T}_2 -space and by Theorem 3.40, $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space.

Theorem (3.44) If \mathcal{X} and \mathcal{Y} are compact \mathcal{R}_1 and $L(\theta\mathcal{C})$ -space, then $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space and $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Proof: Let \mathcal{X} and \mathcal{Y} are \mathcal{R}_1 , $L(\theta\mathcal{C})$ -space, then by Proposition 3.43, $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space. Also, \mathcal{X} and \mathcal{Y} are compact spaces, so $\mathcal{X} \times \mathcal{Y}$ is compact and then $\mathcal{X} \times \mathcal{Y}$ is Lindelof. Therefore from Theorem 3.3, $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space. Now, from Proposition 3.20, $\mathcal{X} \times \mathcal{Y}$ is $\mathcal{K}(\theta\mathcal{C})$ -space and it is compact, then by Theorem 2.27, $\mathcal{X} \times \mathcal{Y}$ is $Min\mathcal{K}(\theta\mathcal{C})$ -space.

Theorem (3.45) If \mathcal{X} and \mathcal{Y} are Lindelof \mathcal{R}_1 and $L(\theta\mathcal{C})$ -spaces, then $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space

Proof: Let \mathcal{X} and \mathcal{Y} are \mathcal{R}_1 , $L(\theta\mathcal{C})$ -spaces, then by Proposition 3.43, $\mathcal{X} \times \mathcal{Y}$ is $L(\theta\mathcal{C})$ -space, also \mathcal{X} and \mathcal{Y} are Lindelof spaces, so $\mathcal{X} \times \mathcal{Y}$ is

Lindelof. Hence from Theorem 3.3, $\mathcal{X} \times \mathcal{Y}$ is $MinL(\theta\mathcal{C})$ -space.

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