

Generalized mean function for n-variable

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ABSTRACT:

In this work we present the theory of an integral mean for generalized GN'-function. We will show under what conditions the mean function is a GN'-function and satisfies a Δ -condition. Moreover, we examine how the minimizing points in the definition of the mean function affect a basic property of the ordinary integral mean.

Keywords : Generalized GN'-function for n-variable, Δ -condition, Generalized mean function.

المخلص:

في هذا العمل نقدم نظرية المتوسط للتكامل للدالة - GN' لـ n من المتغيرات. وسنبين الشروط التي تجعلها دالة - GN' والتي تحقق شرط Δ . وكذلك نبين ان اصغر نقطة في تعريف الدالة القيمة المتوسطة وتأثيرها بالخواص متوسط التكامل الاعتيادي.

1.Introduction and Basic Concept:

In what follows T will denote a space of point with σ -finite measure and E^n a n-dimensional Euclidean space.

Definition1.1 Orlicz(1932)

Orlicz space $\mathcal{L}_{\mathcal{M}} = \mathcal{L}_{\mathcal{M}}(\Omega, \mu)$ is a Banach space consisting of all $f \in \mathcal{S}(\Omega, \mu)$ where $\mathcal{S}(\Omega, \mu)$ is a ring of all measurable functions on the space with bounded measure space (Ω, μ) .

such that

$$\int_{\Omega} M(|f|)d\mu < \infty,$$

With the Luxemburg Nakano norm

$$\|f\|_M = \inf\{\lambda > 0 : \int_{\Omega} M\left(\frac{|f|}{\lambda}\right)d\mu \leq 1\}$$

Orlicz spaces L_m are natural generalization of L_p space, where $L_p(I)$ consists of all the measurable functions f defined on the interval I for which

$$\left(\int_I |f|^p\right)^{\frac{1}{p}} < \infty \quad \text{Corothers(2000)}$$

They have very rich topological and geometrical structures; they may possess peculiar properties that do not occur in an ordinary L_p space.

Definition 1.2 Borwein (1997)

Let $M : I \rightarrow R$ be defined on some interval of the real line R . A function M is called convex if

$$M\left(\frac{u_1 + u_2}{2}\right) \leq \frac{1}{2}(M(u_1) + M(u_2)) \quad (1)$$

for all $u_1, u_2 \in I$

we can generalize the inequality (1) for any u_1, u_2, \dots, u_n by

$$M\left(\frac{u_1 + u_2 + \dots + u_n}{n}\right) \leq \frac{1}{n}(M(u_1) + \dots + M(u_n)) \quad (2)$$

Definition 1.3 Hassen(2007)

Let $M(t, x, y)$ be a real valued non-negative function defined on $T \times E^n \times E^n$ such that:

- (i) $M(t, x, y) = 0$ if and only if x, y are the zero vectors $x, y \in E^n, \forall t \in T$
- (ii) $M(t, x, y)$ is a continuous convex function of x, y for each t and a measurable function of t for each x, y

- (iii) For each $t \in T$, $\lim_{\substack{\|x\| \rightarrow \infty \\ \|y\| \rightarrow \infty}} \frac{M(t, x, y)}{\|x\| \|y\|} = \infty$, and

(iv) There are constants $d \geq 0$ and $d_1 \geq 0$ such that

$$\inf_t \inf_{\substack{c \geq d \\ c' \geq d_1}} k(t, c, c') > 0 \tag{1}$$

Where

$$k(t, c, c') = \frac{M(t, c, c')}{\overline{M}(t, c, c')}$$

$$\overline{M}(t, c, c') = \sup_{\substack{|x|=c \\ |y|=c'}} M(t, x, y), \underline{M}(t, c, c') = \inf_{\substack{|x|=c \\ |y|=c'}} M(t, x, y) \text{ and if } d > 0 \text{ and } d_1 > 0$$

, then $\overline{M}(t, d, d_1)$ is an integrable function of t . We call the function satisfying the properties (i)-(iv) a generalized N^* -function or a GN^* -function.

Definition 1.4:

Let $M(t, x_1, x_2, \dots, x_n)$ be a real valued non-negative function defined on $T \times E^n \times E^n \times \dots \times E^n$ such that:
 $n - \text{times}$

(i) $M(t, x_1, x_2, \dots, x_n) = 0$ if and only if x_1, x_2, \dots, x_n are the zero vectors $x_1, x_2, \dots, x_n \in E^n, \forall t \in T$

(ii) $M(t, x_1, x_2, \dots, x_n)$ is a continuous convex function of x_1, x_2, \dots, x_n for each t and a measurable function of t for each x_1, x_2, \dots, x_n ,

(iii) For each $t \in T$, $\lim_{\substack{\|x_1\|=\infty \\ \|x_2\|=\infty \\ \vdots \\ \|x_n\|=\infty}} \frac{M(t, x_1, x_2, \dots, x_n)}{\|x_1\| \|x_2\| \dots \|x_n\|} = \infty$, and

(iv) There are constants $d_1 \geq 0, d_2 \geq 0, \dots, d_n \geq 0$ such that

$$\inf_t \inf_{\substack{c \geq d \\ c_1^1 \geq d_1 \\ c_2^2 \geq d_2 \\ \vdots \\ c_n^n \geq d_n}} k(t, c, c_1, c_2, \dots, c_n) > 0 \tag{1}$$

Where

$$k(t, c_1, c_2, \dots, c_n) = \frac{M(t, c_1, c_2, \dots, c_n)}{\overline{M}(t, c_1, c_2, \dots, c_n)},$$

$$\overline{M}(t, x_1, c_2, \dots, c_n) = \sup_{\substack{x_1 = c_1 \\ x_2 = c_2 \\ \dots \\ x_n = c_n}} M(t, x_1, x_2, \dots, x_n),$$

$$\underline{M}(t, c_1, c_2, \dots, c_n) = \inf_{\substack{x_1 = c_1 \\ x_2 = c_2 \\ \dots \\ x_n = c_n}} M(t, x_1, x_2, \dots, x_n)$$

and if $d_1 > 0, d_2 > 0, \dots, d_n > 0$, then $\overline{M}(t, d_1, d_2, \dots, d_n)$ is an integrable function of t . We call the function satisfying the properties (i)-(iv) a generalized N'-function or a GN'-function.

Definition 1.5 Hassen (2010)

We say that a GN*-function $M(t, x, y)$ satisfies a Δ -condition if there exists a constant $K \geq 2$ and non-negative measurable functions $\delta_1(t)$ and $\delta_2(t)$ such that the function $M(t, 2\delta_1(t), 2\delta_2(t))$ is integrable over the domain T and such that for almost all t in T we have

$$M(t, 2x, 2y) \leq KM(t, x, y) \tag{1}$$

for all x and y satisfying $|x| \geq \delta_1(t)$ and $|y| \geq \delta_2(t)$.

We say that a GN*-function satisfies a Δ_0 -condition if it satisfies a Δ -condition with $\delta_1(t) = 0$ and $\delta_2(t) = 0$ for almost all t in T .

In Definition 1.5 we could have used any constant $\tau > 1$ in place of the scalar 2 in (1).

Definition 1.6:

We say that a GN'-function $M(t, x_1, x_2, \dots, x_n)$ satisfies a Δ -condition if there exists a constant $K \geq 2$ and non-negative measurable functions $\delta_1(t), \delta_2(t), \dots,$

$\delta_n(t)$ such that the function $M(t, 2\delta_1(t), 2\delta_2(t), \dots, 2\delta_n(t))$ is integrable over the domain T and such that for almost all t in T we have

$$M(t, 2x_1, 2x_2, \dots, 2x_n) \leq KM(t, x_1, x_2, \dots, x_n) \tag{1}$$

for all x_1, x_2, \dots, x_n satisfying $|x_1| \geq \delta_1(t), |x_2| \geq \delta_2(t), \dots, |x_n| \geq \delta_n(t)$.

Thus, according to this definition, the statement above can be formulated as:

We say that a GN'-function satisfies a Δ_0 – condition if it satisfies a Δ – condition with $\delta_1(t) = 0, \delta_2(t) = 0, \dots, \delta_n(t) = 0$ for almost all t in T .

In Definition 1.6 we could have used any constant $\tau > 1$ in place of the scalar 2 in (1).

Definition 1.7 Hassen (2007)

For each t in T and $h > 0$ let

$$M_h(t, x, y) = \int_{E^n} \int_{E^n} M(t, x+z, y+w) J_h(z) J_h(w) dz dw,$$

where $J_h(z)$ and $J_h(w)$ are non negative, C^∞ function with compact

support in a ball of a radius h such that $\int_{E^n} \int_{E^n} J_h(z) J_h(w) dt dz = 1$.

Moreover, let x_0 and y_0 are any two points (depending on h, t) which satisfy the inequality

$$M_h(t, x_0, y_0) \leq M_h(t, x, y)$$

for all x and y in E^n . Then the function $\hat{M}_h(t, x, y)$ defined for each t in T and $h > 0$ by

$$\hat{M}_h(t, x, y) = M_h(t, x + x_0, y + y_0) - M_h(t, x_0, y_0)$$

is called a **mean function** for $M(t, x, y)$ relative to the minimizing point x_0 and y_0 .

Definition 1.8:

For each t in T and $h > 0$ let

$$M_h(t, x_1, x_2, \dots, x_n) =$$

$$\int_{E^n} \int_{E^n} \dots \int_{E^n} M(t, x_1 + y_1, x_2 + y_2, \dots, x_n + y_n) J_h(y_1) J_h(y_2) \dots J_h(y_n) dy_1 dy_2 \dots dy_n$$

where $J_h(y_1), J_h(y_2), \dots, J_h(y_n)$ are non-negative, C^∞ functions with compact support in a ball of radius h such that

$$\int_{E^n} \int_{E^n} \dots \int_{E^n} J_h(y_1) J_h(y_2) \dots J_h(y_n) dt_1 dt_2 \dots dt_n = \Gamma. \quad \text{Moreover, let } x_{01},$$

x_{02}, \dots, x_{0n} are any points (depending on h, t) which satisfy the inequality

$$M_h(t, x_{01}, x_{02}, \dots, x_{0n}) \leq M_h(t, x_1, x_2, \dots, x_n)$$

for all x_1, x_2, \dots, x_n in E^n . Then the function $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ defined for each t in T and $h > 0$ by

$$\hat{M}_h(t, x_1, x_2, \dots, x_n) = M_h(t, x_1 + x_{01}, x_2 + x_{02}, \dots, x_n + x_{0n}) - M_h(t, x_{01}, x_{02}, \dots, x_{0n})$$

is called a **mean function** for $M(t, x_1, x_2, \dots, x_n)$ relative to the minimizing points

$x_{01}, x_{02}, \dots, x_{0n}$.

Theorem 1.9 Hassen (2007)

If $M(t, x, y)$ is a GN*-function for which $\overline{M}(t, c, c')$ is integrable in t for each c and c' , then $\hat{M}_h(t, x, y)$ is a GN*-function.

Theorem 1.10 Hassen (2007)

If $M(t, x, y)$ is a GN*-function satisfying a Δ -condition and for which $\overline{M}(t, c, c')$ is integrable in t for each c and c' , then $\hat{M}_h(t, x, y)$

satisfies a Δ -condition.

Theorem 1.11 Hassen (2007)

For each $h > 0$ let x_0^h and y_0^h be the minimizing point of $M_h(t, x, y)$

defining $\hat{M}_h(t, x, y)$. Then for each t in T and each x, y in E^n , there exists $K(t, x, y)$ such that

$$\lim_{h=0} \hat{M}_h(t, x, y) = M(t, x, y) + K(t, x, y) \lim_{h=0} |x_0^h| \lim_{h=0} |y_0^h|$$

Corollary 1.12 Hassen (2007)

Suppose $M(t, x, y)$ is a GN*-function such that $M(t, x, y) = M(t, -x, -y)$.

Then for each t in T and x, y in E^n , we have

$$\lim_{h=0} M_h(t, x, y) = \hat{M}(t, x, y)$$

Theorem 1.13 Hassen (2007)

The sets B and A_h are closed convex sets.

Theorem 1.14 Hassen (2007)

Let $B_e = \{(x, y) : M(t, x, y) < e\}$ for each t in T . Then for given any $e > 0$,

there is a constant $h_0 > 0$. such that $A_h \subset B_e$ for each $h \leq h_0$.

Theorem 1.15 Hassen (2007)

Suppose $M(t, x, y)$ is a GN*-function which is strictly convex in x and y

for each t . Then $A_h = \{(0, 0)\}$ for each h .

Theorem 1.16 Hassen (2013)

A necessary and sufficient condition that (1.5.1) holds is that if

$$|x_1| \leq |y_1|, |x_2| \leq |y_2|, \dots, |x_n| \leq |y_n| \text{ then there exists constants } K \geq 1, d_1 \geq 0, d_2 \geq 0$$

,

$\dots, d_n \geq 0$ such that $M(t, x_1, x_2, \dots, x_n) \leq KM(t, y_1, y_2, \dots, y_n)$ for each t in T ,

$$|x_1| \geq d_1, |x_2| \geq d_2, \dots, |x_n| \geq d_n$$

Theorem 1.17 Hassen (2010)

A GN'-function $M(t, x_1, x_2, \dots, x_n)$ satisfies a Δ -condition if and only if

given any $\tau > 1$ there exists a constant $K_\tau \geq 2$ and a non-negative measurable functions $\delta_1(t), \delta_2(t), \dots, \delta_n(t)$ such that $\overline{M}(t, 2\delta_1(t), 2\delta_2(t), \dots, 2\delta_n(t))$ is integrable over T and such that for almost all t in T we have

$$M(t, \tau x_1, \tau x_2, \dots, \tau x_n) \leq K_\tau M(t, x_1, x_2, \dots, x_n), \quad (1)$$

whenever $|x_1| \geq \delta_1(t), |x_2| \geq \delta_2(t), \dots, |x_n| \geq \delta_n(t)$.

2. Generalized mean function:

Theorem 2.1:

If $M(t, x_1, x_2, \dots, x_n)$ is a GN'-function for which $\overline{M}(t, c_1, c_2, \dots, c_n)$ is integrable in t for each c_1, c_2, \dots, c_n , then $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ is a GN'-function.

Proof:

We will show this result by justifying conditions (i)-(iv) of the definition 3.1.1. By hypothesis and the choice of $x_{01}, x_{02}, \dots, x_{0n}$, we have for each h , $\hat{M}_h(t, x_1, x_2, \dots, x_n) \geq 0$ and $\hat{M}_h(t, 0, 0, \dots, 0) = 0$. On the other hand, if $x_1 \neq 0, x_2 \neq 0, \dots, x_n \neq 0$, then $M(t, x_1, x_2, \dots, x_n) > 0$, and hence there are constants $h_{01}, h_{02}, \dots, h_{0n}$ such that

$$a = \inf_{\substack{|w_i| \leq h_{0i} \\ 1 \leq i \leq n}} M(t, x_1 + w_1, x_2 + w_2, \dots, x_n + w_n) > 0$$

However, since $M(t, x_1, x_2, \dots, x_n) = 0$ if and only if $x_1 = 0, x_2 = 0, \dots, x_n = 0$, the minimizing points x_{01} tends to zero, x_{02} tends to zero, ..., x_{0n} tends to zero as h tends to zero. Therefore, we can choose $g_{01} \leq h_{01}, g_{02} \leq h_{02}, \dots, g_{0n} \leq h_{0n}$ such that if $h \leq g_{01}, h \leq g_{02}, \dots, h \leq g_{0n}$ then $M(t, x_{01} + y_{01}, x_{02} + y_{02}, \dots, x_{0n} + y_{0n}) < a$ for all $y_{01}, y_{02}, \dots, y_{0n}$ for which $|x_{01} + y_{01}| < h, |x_{02} + y_{02}| < h, \dots, |x_{0n} + y_{0n}| < h$ for this $g_{01}, g_{02}, \dots, g_{0n}$ we obtain the inequality

$$M(t, x_1 + x_{01} + y_{01}, x_2 + x_{02} + y_{02}, \dots, x_n + x_{0n} + y_{0n}) \geq \inf_{\substack{|w_i| \leq g_{0i} \\ 1 \leq i \leq n}} M(t, x_1 + w_1, x_2 + w_2, \dots, x_n + w_n) \geq a > M(t, x_{01} + y_{01}, x_{02} + y_{02}, \dots, x_{0n} + y_{0n})$$

whenever $|x_{01} + y_{01}| \leq g_{01}, |x_{02} + y_{02}| \leq g_{02}, \dots, |x_{0n} + y_{0n}| \leq g_{0n}$. This means for some $h \leq g_{01}, h \leq g_{02}, \dots, h \leq g_{0n}$ we have

$$M(t, x_1 + x_{01} + y_{01}, x_2 + x_{02} + y_{02}, \dots, x_n + x_{0n} + y_{0n}) > M(t, x_{01} + y_{01}, x_{02} + y_{02}, \dots, x_{0n} + y_{0n}) > M_h(t, x_1 + x_{01}, x_2 + x_{02}, \dots, x_n + x_{0n}) > M_h(t, x_{01}, x_{02}, \dots, x_{0n})$$

or $\hat{M}_h(t, x_1, x_2, \dots, x_n) > 0$ if $x_1 \neq 0, x_2 \neq 0, \dots, x_n \neq 0$ which proves property (i).

Properties (ii) and (iii) for $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ follow easily from the same properties for $M(t, x_1, x_2, \dots, x_n)$. Let us now show (iv). By assumption, there are constants $d_1 \geq 0, d_2 \geq 0, \dots, d_n \geq 0$ such that

$$\tau(t) \overline{M}(t, c_1, c_2, \dots, c_n) \leq \underline{M}(t, c_1, c_2, \dots, c_n) \tag{1}$$

for all $c_1 \geq d_1, c_2 \geq d_2, \dots, c_n \geq d_n$. Furthermore, it is not difficult to show that for all c and c' we have

$$\bar{M}(t, c_1, c_2, \dots, c_n) \geq \sup_{\substack{|x_i| \leq c_i \\ 1 \leq i \leq n}} M(t, x_1, x_2, \dots, x_n) \quad (2)$$

and for some fixed w_1, w_2, \dots, w_n

$$\inf_{\substack{|x_i| \geq c \\ 1 \leq i \leq n}} M(t, x_1 + w_1, x_2 + w_2, \dots, x_n + w_n) \leq \inf_{\substack{|x_i| = c \\ 1 \leq i \leq n}} M(t, x_1 + w_1, x_2 + w_2, \dots, x_n + w_n) \quad (3)$$

By using (2), we obtain (for each t in T) that

$$\begin{aligned} \tau(t) \sup_{\substack{|x_i| = c \\ 1 \leq i \leq n}} M(t, w_1, w_2, \dots, w_n) &\leq \tau(t) \sup_{\substack{|r_i| < c + |x_i + x_{0i}| \\ 1 \leq i \leq n}} M(t, r_1, r_2, \dots, r_n) \quad (4) \\ &\leq \tau(t) \sup_{\substack{|r_i| = c + |x_i + x_{0i}| \\ 1 \leq i \leq n}} M(t, r_1, r_2, \dots, r_n) \end{aligned}$$

where $w_i = x_i + x_{0i} + r_i$ for $i=1$ to n . On the other hand, by (1) and (3), we achieve

$$\begin{aligned} \tau(t) \sup_{\substack{|w_i| = c + |x_{0i} + x_{i1}| \\ 1 \leq i \leq n}} M(t, w_1, w_2, \dots, w_n) &\leq \inf_{\substack{|w_i| = c + |x_{0i} + x_{i1}| \\ 1 \leq i \leq n}} M(t, w_1, w_2, \dots, w_n) \quad (5) \\ &< \inf_{\substack{|x_i| \geq c \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n). \end{aligned}$$

$$\begin{aligned} &< \inf_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n). \end{aligned}$$

If we combine (4) and (5), then for all $c_i \geq d_i$ for $i=1$ to n and we arrive at

$$\tau(t) \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n) \leq$$

$$\inf_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n)$$

From this inequality, we obtain

$$\begin{aligned} \inf_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} \hat{M}_h(t, x_1, x_2, \dots, x_n) &\geq \int_{E^n} \int_{E^n} \dots \int_{E^n} \inf_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} \{M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n) \\ &- M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n)\} J_h(r_1) J_h(r_2) \dots J_h(r_n) dr_1 dr_2 \dots dr_n \\ &\geq \int_{E^n} \int_{E^n} \int_{E^n} \{\tau(t) \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n) \\ &- M(t, x_{01} + r_1, x_{02} + r_2, \dots, x_{0n} + r_n)\} J_h(r_1) J_h(r_2) \dots J_h(r_n) dr_1 dr_2 \dots dr_n, \end{aligned} \tag{6}$$

and

$$\begin{aligned} \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} \hat{M}_h(t, x_1, x_2, \dots, x_n) &\leq \int_{E^n} \dots \int_{E^n} \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, \\ &x_n + x_{0n} + r_n) J_h(r_1) J_h(r_2) \dots J_h(r_n) dr_1 dr_2 \dots dr_n. \end{aligned} \tag{7}$$

Moreover, since $\lim_{\substack{c_i \rightarrow \infty \\ 1 \leq i \leq n}} \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n) = \infty$

for fixed x_{0i}, r_i for $1 \leq i \leq n$ such that $|r_i| \leq h_i$ for $1 \leq i \leq n$ given

$$K_1(t) = 2 \sup_{\substack{|r_i| \leq h_i \\ 1 \leq i \leq n}} M(t, x_{01} + r_1, x_{02} + r_2, \dots, x_{0n} + r_n) / \inf_t \tau(t)$$

there are $d_i > 0, 1 \leq i \leq n$ such that if $c_i \geq d_i', 1 \leq i \leq n$, then

$$\sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n) \geq K_1.$$

Therefore, by using (3.3.8) and (3.3.9), we achieve the inequalities

$$\frac{\inf_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} \hat{M}_h(t, x_1, x_2, \dots, x_n)}{\sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} \hat{M}_h(t, x_1, x_2, \dots, x_n)} \geq \tau(t) - \frac{\sup_{\substack{|r_i| \leq h_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n)}{\inf_{\substack{|r_i| \leq h_i \\ 1 \leq i \leq n}} \sup_{\substack{|x_i| = c_i \\ 1 \leq i \leq n}} M(t, x_1 + x_{01} + r_1, x_2 + x_{02} + r_2, \dots, x_n + x_{0n} + r_n)} \geq \tau(t) - \frac{1}{2} \inf_t \tau(t)$$

(8)

for all $c_i \geq d_{0i} = \max(d_i, d_i', |x_{0i}|)$. Taking the infimum of both sides of (2.1.8)

over t , shows the first part of the property (iv). To show the latter part, assume

$d_{0i} > 0, 1 \leq i \leq n$ and . Then $\sup_{\substack{|x_i| = d_{0i} \\ 1 \leq i \leq n}} \hat{M}_h(t, x_1, x_2, \dots, x_n)$ is integrable over t in T since

it is bounded by the integrable function $\bar{M}(t, d_{21}, d_{22}, \dots, d_{2n})$ where

$d_{2i} = d_{0i} + |x_{0i}| + h$. This proves property (iv) and

the theorem. ■

In the next theorem we show under what condition $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ satisfies a

Δ – condition.

Theorem 2.2:

If $M(t, x_1, x_2, \dots, x_n)$ is a GN'-function satisfying a Δ -condition and for which $\overline{M}(t, c_1, c_2, \dots, c_n)$ is integrable in t for each c_1, c_2, \dots, c_n then $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ satisfies a Δ -condition.

Proof:

It suffices to show that $M_h(t, x_1, x_2, \dots, x_n)$ satisfies a Δ -condition.

For, $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ is the sum of a constant and a translation of $M_h(t, x_1, x_2, \dots, x_n)$ and neither of these operations affects the growth condition. Let us observe first that if $|x_i| \geq 2$ for $1 \leq i \leq n$, $|z_i| \leq h \leq 1$ for $1 \leq i \leq n$ then $|2x_i + z_i| \leq 3|x_i + z_i|$ for $1 \leq i \leq n$. Hence, by Theorem (1.16), there are constants $K \geq 1$ and $d_1 \geq 0$ such that

$$M_h(t, 2x_1, 2x_2, \dots, 2x_n) \leq k \int_{E^n} \dots \int_{E^n} M(t, 3(x_1 + z_1), 3(x_2 + z_2), \dots, 3(x_n + z_n)) \\ K_3 M_h(t, x_1, x_2, \dots, x_n) J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n$$

for all x_i for $1 \leq i \leq n$ such that $|x_i| \geq d_2$ for $1 \leq i \leq n$ and $d_2 = \max(d_1, 2)$. On the other hand, by theorem (1.17),

$$\int_{E^n} \dots \int_{E^n} M(t, 3(x_1 + z_1), 3(x_2 + z_2), \dots, 3(x_n + z_n)) J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n \leq \\ K_3 M_h(t, x_1, x_2, \dots, x_n)$$

there is a constant $K_3 \geq 2$, $\delta_i(t) \geq 0$ for $1 \leq i \leq n$ such that for almost all t in T for all

x_i, z_i for $1 \leq i \leq n$ such that $|x_i + z_i| \geq \delta_i(t)$ for $1 \leq i \leq n$ where $|z_i| \leq h_i$ for $1 \leq i \leq n$

.By combining the above two inequalities, we achieve

$$M_h(t, 2x_1, 2x_2, \dots, 2x_n) \leq KK_3 M_h(t, x_1, x_2, \dots, x_n)$$

for all $\left| x_i \right| > \max(d_{2i}, \delta_i(t) + h) = \delta'_i(t)$ Since $\overline{M}(t, 2\delta_1(t), 2\delta_2(t), \dots, 2\delta_n(t))$ is integrable over T , this yields the integrability of $\overline{M}_h(t, 2\delta'_1(t), 2\delta'_2(t), \dots, 2\delta'_n(t))$ which proves the theorem. ■

For each t in T and x_1, x_2, \dots, x_n in E^n it is known that

$$\lim_{h=0} M_h(t, x_1, x_2, \dots, x_n) = M(t, x_1, x_2, \dots, x_n).$$

However, the same property does not hold in general for $\hat{M}_h(t, x_1, x_2, \dots, x_n)$

. This is the point of the next theorem.

Theorem 2.3:

For each $h > 0$ let x_{0i}^h for $1 \leq i \leq n$ be the minimizing point of $M_h(t, x_1, x_2, \dots, x_n)$ defining $\hat{M}_h(t, x_1, x_2, \dots, x_n)$. Then for each t in T and each x_i for $1 \leq i \leq n$ in E^n , there exists $K(t, x_1, x_2, \dots, x_n)$ such that

$$\lim_{h=0} \hat{M}_h(t, x_1, x_2, \dots, x_n) = M(t, x_1, x_2, \dots, x_n) + K(t, x_1, x_2, \dots, x_n) \prod_{i=1}^n \lim_{h=0} \left| x_{0i}^h \right|$$

Proof:

By the definition of $\hat{M}_h(t, x_1, x_2, \dots, x_n)$ we can write

$$\begin{aligned} & \left| \hat{M}_h(t, x_1, x_2, \dots, x_n) - M(t, x_1, x_2, \dots, x_n) \right| \leq \\ & \int_{E^n} \int_{E^n} \dots \int_{E^n} \left| M(t, x_1 + x_{01}^h + z_1, x_2 + x_{02}^h + z_2, \dots, x_n + x_{0n}^h + z_n) - \right. \\ & \left. M(t, x_{01}^h + z_1, x_{02}^h + z_2, \dots, x_{0n}^h + z_n) - M(t, x_1, x_2, \dots, x_n) \right| J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n \end{aligned} \quad (1)$$

However, we know that

$$\begin{aligned} & \left| M(t, x_1 + x_{01}^h + z_1, x_2 + x_{02}^h + z_2, \dots, x_n + x_{0n}^h + z_n) - \right. \\ & \left. M(t, x_{01}^h + z_1, x_{02}^h + z_2, \dots, x_{0n}^h + z_n) - M(t, x_1, x_2, \dots, x_n) \right| \quad (2) \\ & \leq \left| M(t, x_1 + x_{01}^h + z_1, x_2 + x_{02}^h + z_2, \dots, x_n + x_{0n}^h + z_n) - M(t, x_1, x_2, \dots, x_n) \right| \\ & + \left| M(t, x_{01}^h + z_1, x_{02}^h + z_2, \dots, x_{0n}^h + z_n) - M(t, z_1, z_2, \dots, z_n) \right| + \left| M(t, z_1, z_2, \dots, z_n) \right|. \end{aligned}$$

Moreover , since $M(t, x_1, x_2, \dots, x_n)$ is a convex function, it satisfies a Lipschitz

condition on compact subsets of E^n (see[Skaiff (1968),Th.5.1]).Therefore ,there exists

$K_1(t, x_1, x_2, \dots, x_n)$ and $K_2(t, x_1, x_2, \dots, x_n)$ such that

$$\begin{aligned} & \left| M(t, x_1 + x_{01}^h + z_1, x_2 + x_{02}^h + z_2, \dots, x_n + x_{0n}^h + z_n) - M(t, x_1, x_2, \dots, x_n) \right| \leq \\ & K_1(t, x_1, x_2, \dots, x_n) \left| x_{01}^h + z_1 \right| \left| x_{02}^h + z_2 \right| \dots \left| x_{0n}^h + z_n \right|. \quad (3) \end{aligned}$$

and

$$\left| M(t, x_{01}^h + z_1, x_{02}^h + z_2, \dots, x_{0n}^h + z_n) - M(t, z_1, z_2, \dots, z_n) \right| \leq K_2(t, x_1, x_2, \dots, x_n) \left| x_{01}^h \right| \left| x_{02}^h \right| \dots \left| x_{0n}^h \right| \quad (4)$$

If we combine (3) and (4) with (2) and if we substitute the resulting expression into (1), we achieve the inequality

$$\begin{aligned} & \left| \hat{M}_h(t, x_1, x_2, \dots, x_n) - M(t, x_1, x_2, \dots, x_n) \right| \leq \prod_{i=1}^n \left| x_{0i}^h \right| \left(K_1(t, x_1, x_2, \dots, x_n) + K_2(t, x_1, x_2, \dots, x_n) \right) + \\ & \sum_{i=1}^n \int_{E^n} \int_{E^n} \dots \int_{E^n} \left| x_{0i}^h \right| K_1(t, x_1, x_2, \dots, x_n) \left| z_i \right| J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n + \\ & \int_{E^n} \int_{E^n} \dots \int_{E^n} K(t, x_1, x_2, \dots, x_n) \prod_{i=1}^n \left| z_i \right| J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n + \\ & \int_{E^n} \int_{E^n} \dots \int_{E^n} M(t, z_1, z_2, \dots, z_n) J_h(z_1) J_h(z_2) \dots J_h(z_n) dz_1 dz_2 \dots dz_n \end{aligned}$$

Since the last four integrals on the right side tend to zero as h tends to zero, we prove the theorem by setting

$$K(t, x_1, x_2, \dots, x_n) = K_1(t, x_1, x_2, \dots, x_n) + K_2(t, x_1, x_2, \dots, x_n)$$

Corollary 2.4:

Suppose $M(t, x_1, x_2, \dots, x_n)$ is a GN'-function such that

$$M(t, x_1, x_2, \dots, x_n) = M(t, -x_1, -x_2, \dots, -x_n).$$

Then for each t in T and x_i in E^n for $i=1$ to n , we have

$$\lim_{h=0} M_h(t, x_1, x_2, \dots, x_n) = \hat{M}(t, x_1, x_2, \dots, x_n)$$

Proof:

This result is clear since $\lim_{h=0} |x_{0i}^h| = 0$ for $i=1$ to n

if $M_h(t, x_1, x_2, \dots, x_n) = M(t, -x_1, -x_2, \dots, -x_n)$. In fact, if $M(t, x_1, x_2, \dots, x_n)$ is even in (x_1, x_2, \dots, x_n) then the $x_{0i}^h = 0$ for $i=1$ to n for all h . ■

For each t in T let A_h denote the set of minimizing points of

$M_h(t, x_1, x_2, \dots, x_n)$ and let B represents the null space of $M(t, x_1, x_2, \dots, x_n)$

relative to points in $E^n \times E^n \times \dots \times E^n$, i.e.,

$$B = \{(x_1, x_2, \dots, x_n) \text{ in } E^n \times E^n \times \dots \times E^n : M(t, x_1, x_2, \dots, x_n) = 0\}.$$

If $M(t, x_1, x_2, \dots, x_n)$ is a GN'-function, then $B = \{(0, 0, \dots, 0)\}$. For the sake of argument, let us suppose that $M(t, x_1, x_2, \dots, x_n)$ has all the properties of a GN'-function except that $M(t, x_1, x_2, \dots, x_n) = 0$ need not imply $x_i = 0$ for $i = 1$ to n .

We will show the relationships that exist between A_h and B . This is the content of the next few theorems.

Theorem 2.5:

The sets B and A_h are closed convex sets.

Proof:

This result follows from the convexity and continuity of $M(t, x_1, x_2, \dots, x_n)$ in x_i for $i=1$ to n for each t in T . ■

Theorem 2.6:

Let $B_e = \{(x_1, x_2, \dots, x_n) : M(t, x_1, x_2, \dots, x_n) < e\}$ for each t in T . Then given any $e > 0$,

there is a constant $h_0 > 0$. such that $A_h \subset B_e$ for each $h \leq h_0$.

Proof:

Since $B \subseteq B_e$, we can choose h_0 sufficiently small so that if (x_1, x_2, \dots, x_n) is in B then $(x_1 + z_1, x_2 + z_2, \dots, x_n + z_n)$ is in B_e for all (z_1, z_2, \dots, z_n) such that $|z_i| \leq h_0$ for $i=1$ to n . Let $(z_{01}, z_{02}, \dots, z_{0n})$ be arbitrary but fixed points in $A_h, h \leq h_0$. Then

$$M_h(t, z_{01}, z_{02}, \dots, z_{0n}) \leq M_h(t, x_1, x_2, \dots, x_n) \text{ for all } x_i \text{ for } i=1 \text{ to } n.$$

Therefore, if (x_1, x_2, \dots, x_n) in B , we have $M_h(t, z_{01}, z_{02}, \dots, z_{0n}) < e$ by our choice of h_0 . Letting h tend to zero yields $M(t, z_{01}, z_{02}, \dots, z_{0n}) < e$, i.e., $(z_{01}, z_{02}, \dots, z_{0n})$ in B_e .

We have commented above that $A_h = \{(0, 0, \dots, 0)\}$

$$M(t, x_1, x_2, \dots, x_n) = M(t, -x_1, -x_2, \dots, -x_n).$$

It is also true if $M(t, x_1, x_2, \dots, x_n)$ is strictly convex in x for each t in T .

Theorem 2.7:

Suppose $M(t, x_1, x_2, \dots, x_n)$ is a GN*-function which is strictly convex in x_i for

$i = 1$ to n for each t . Then $h, A_h = \{(0, 0, \dots, 0)\}$ for each h .

Proof:

Suppose that there exists $z_{0i} \neq x_{0i}$ for $1 \leq i \leq n$ such that z_{0i}, x_{0i} for $1 \leq i \leq n$ are in A_h . Let $z_i = \frac{(x_{0i} + z_{0i})}{2}$ for $1 \leq i \leq n$. Then, since $M(t, x_1, x_2, \dots, x_n)$ is strictly convex, $M_h(t, x_1, x_2, \dots, x_n)$ is strictly convex in x_1, x_2, \dots, x_n , therefore, we have

$$M_h(t, z_1, z_2, \dots, z_n) < \frac{1}{2} M_h(t, x_{01}, x_{02}, \dots, x_{0n}) + \frac{1}{2} M_h(t, z_{01}, z_{02}, \dots, z_{0n}). \quad (1)$$

However, $(x_{01}, x_{02}, \dots, x_{0n}), (z_{01}, z_{02}, \dots, z_{0n})$ are in A_h reduces (1) to the inequality $M_h(t, z_1, z_2, \dots, z_n) < M_h(t, x_1, x_2, \dots, x_n)$ for all x_i for $i = 1$ to n .

This means z_1, z_2, \dots and z_n are in A_h and are $(x_{01}, x_{02}, \dots, x_{0n}), (z_{01}, z_{02}, \dots, z_{0n})$

not in A_h which is a contradiction. Hence, $x_{0i} = z_{0i}$ for $i = 1$ to n . Since

$M(t, x_1, x_2, \dots, x_n)$ is a GN'-function, $B = \{(0, 0, \dots, 0)\}$. In this case $x_{0i} = z_{0i} = 0$ for $i = 1$ to n .

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