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## الحلول المبسطة للمعادلات الجبرية الخطية

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### المستخلص :

إن حل المعادلات الخطية المتجانسة باستخدام قاعدة كرا يمر في متناول اليد بشكل مبسط إذا كانت عدد العناصر الصفيرية أكبر ما يمكن. وقد تضمن البحث دراسة الحلول وبشكل أكثر عمومية وبساطة .  
إن ضرورة تقديم هكذا حلول مبسطة يكون إستخدامها بشكل خاص في التطبيقات الكيميائية .

Here according to Theorem 5,  $\{a_1, \dots, a_q\}$  constitutes a simplex, where  $q-1 \leq r$  (see (6)), So we may complete the linearly independent vectors  $a_1, \dots, a_{q-1}$  with,  $r-(q-1) \geq 0$  vectors:  $a_{j_1}, \dots, a_{j_{r-q+1}}$ , the new vector System  $\{a_1, \dots, a_{q-1}, a_{j_1}, \dots, a_{j_{r-q+1}}\}$  becoming hereby a basis. Consider now that of the base solutions belonging to this basis which is determine uniquely by the equation (see Definition 6 and Theorem 6):

$$x_1 a_1 + \dots + x_{q-1} a_{q-1} + x_{j_1} a_{j_1} + \dots + x_{j_{r-q+1}} a_{j_{r-q+1}} + x_q a_q = 0.$$

This solution is asserted to be S. Namely, on account of the construction,  $x_1, \dots, x_{j_{r-q+1}}$  are identically zero, Consequently the equation (15) is left over, whose unique solution is indeed the simple solution S. So S is a base solution.

### Appendix

The system of homogeneous linear equations (I) has a solution in which the unknown  $x_{j_l}$  ( $j_l = 1, 2, \dots, n$ ) is uniquely ( identically ) zero if and only if the rank of the matrix of (I) is by one greater than that of the matrix in which the  $j_l$ -th column is dropped:

$$\text{rank } [a_{j_2}, \dots, a_{j_n}] = \text{rank } [a_1, \dots, a_n] - 1 = r - 1.$$

### References

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We can now formulate our following fundamental:

**Theorem 8:**

The simple solutions are identical with the base solutions.

**Proof:**

At first we show that the base solutions are simple ones.

Consider a base solution, it is, due to Definition 6, a solution of an equation of type (11). With out loss of generality we may assume (11) to be of the following form:

$$X_1a_1 + \dots + x_r a_r + x_k a_k = 0, \text{ ----- (13),}$$

Where  $\{ a_1, \dots, a_r \}$  is a basis. Here, according to Theorem 6,  $X_k$  can not be zero; if, however, any of the unknowns  $X_1, \dots, X_r$  is zero, then it must be uniquely zero.

Thus, let the unknowns:

$X_{j_1}, \dots, X_{j_{q-1}}$  ( $2 \leq q \leq r+1$ ) be different from zero, then (13) becomes:

$$X_{j_1} a_{j_1} + \dots + X_{j_{q-1}} a_{j_{q-1}} + X_k a_k = 0, \text{ ----- (14),}$$

Where none of the unknowns can be zero any more.

Thus owing to Theorem 4, the solution of (14), i.e. the base solution considered, will be a simple one over:

$$C = \{ J_1, \dots, J_{q-1}, k \}.$$

We prove now that a simple solution is a base solution.

Consider a simple solution  $S$ , without loss of generality

Assuming it to be of the form  $[s_1, \dots, s_q, 0, \dots, 0]$ . It is, because of Definition 3, the unique solution of the equation:

$$X_1 a_1 + \dots + x_q a_q = 0, \text{ ----- (15).}$$

$$X_{j1}A_{j1} + \dots + X_{jr}A_{jr} + X_{jk}A_{jk} = 0. \quad (11).$$

Where  $\{ a_{j1}, \dots, a_{jr} \}$  is a base and  $k = r+1, \dots, n$ .

**Theorem 6:**

(11) Determines one solution  $S$ , for which also  $S_j \neq 0$ .

**Proof:**

Let us solve (11). The number of its unknowns being equal to  $r + 1$  and the rank of its matrix  $[ a_{j1}, \dots, a_{jr}, a_{jk} ]$  equal to  $r$ , its solution is unique, say  $S$  (by virtue of Definition 1) Here, moreover,  $S_j \neq 0$ , otherwise  $S_{j1} = \dots = S_{jr} = 0$  would have to hold because  $\{ a_{j1}, \dots, a_{jr} \}$  is a basis: thus (11) would have no solution though  $S$  was one.

Q.E.D.

The base solution of equation (3) are obtained when solving it by Gramer's rule. More exactly there holds the following:

**Theorem 7:**

Let us solve (3) according to Gramer's rule. As known, choosing a basis  $\{ a_{j1}, \dots, a_{jr} \}$ , the general solution becomes:

$$S = \sum_{k=r+1}^n X_{jk} S_{jk}. \quad (12).$$

Where  $X_{jk}$  are so-called free variables. Consider now all the general solutions of type (12) belonging to the possible bases among  $a_1, a_2, \dots, a_n$  and consider the set of the different  $S_{jk}$  in these solutions. As a trivial consequence of Definition 6 we may assert that by these  $S_{jk}$  all the base solutions of (3) are represented.

**theorem 4 holds consequently if and only if  $\{ a_{j1}, \dots, a_{jq} \}$  form a simplex.**

Proof:

At first we show that, if  $\{ a_{j1}, \dots, a_{jq} \}$  forms a simplex if, the solution of (4) is unique and (8) is also fulfilled. The solution of (4) is unique, the number of the unknowns,  $q$ , being by one greater than  $\text{rank} [ a_{j1}, \dots, a_{jq} ] = q-1$  (see (9)). **F**

Consider now the ( unique ) solution of (4) :

$S = [s_1, \dots, s_n]$ , Were any  $S_{jt}$  ( $1 \leq t < q$ ) zero here, (4)

without the term corresponding to  $a$  would have no solution (see (10) and Definition 1), not with Standing that  $S$  was the solution of (4). Thus (8) must be true.

Now we show that, if the solution of (4) is unique and (8) also holds, the vectors  $a_{j1}, \dots, a_{jq}$  form a simplex.

Owing to the uniqueness (9) holds. Here, omitting any vector  $a$  ( $1 \leq t \leq q$ ), the remaining ones linearly independent ; otherwise

$X_j$  would namely be uniquely in (4), which contradicts (8). Thus (10) holds too.

**Q.E.D.**

## 2- Construction of the simple solutions :

In the foregoing it has not yet been mentioned how the simple solutions of (3) can be found . A few theorems with respect to this question will now be proved.

Definition 6:

A solution  $S$  of (3) is called a base solution if it is a solution of an equation of the form :

that if a solution is not simple ,one can always find another just as good one.

Let  $S$  be a not simple solution over  $C=\{j_1, \dots, j_q\}$ , then (4)

has also another solution ,say  $S'$  . Let us now form the solution

$S + \epsilon S'$ , where  $\epsilon > 0$  is a real number . If  $\epsilon$  is small enough , the non-zero elements of  $S$  vary hereby only a little, that is ,do not become zero, Therefore  $S + \epsilon S'$  will be a solution just as good as  $S$ .

Q.E.D.

**Theorem 4:**

Let a combination  $C = \{ j_1, \dots, j_q \}$  be given.

A simple solution over  $C$  exist if and only if the solution of (4) ,say  $S$  , is unique, moreover:

$$\prod_{t=1}^q S_{jt} \neq 0. \text{ ----- (8)}$$

This theorem is a trivial consequence of Definitions 2 and 3.

**Theorem 5:**

The Statement of the previous theorem holds if and only if;

$$\text{Rank } [a_{j1} \dots a_{jq}] = q-1 \text{ ----- (9). ,}$$

$$\text{Rank } [a_{j1}, \dots, a_{jt+1}, \dots, a_{jq}] = q-1. \text{ -----(10).}$$

$$t = 1, 2, \dots, q$$

A System of linearly dependent vectors should be called a simplex if ,by omitting any of them ,the remaining vectors become linearly independent .The Statement of

**Proof:**

The condition is trivially necessary on the basis of Definition (3). To show that the condition is sufficient we will prove that ,if a solution is not simple, one can always find a better solution.

Let S be a not simple solution over  $C = \{J_1, \dots, J_q\}$ , then according to Definition (3) :

$$\text{Rank } [a_j, \dots, a_{jq}] \leq q-2 .$$

Setting e.g.  $X_j$  in (4) equal to zero ,the new equation :

$$\sum_{t=1}^{q-1} X_{jt}, A_{jt} = 0. \text{ ----- (7).}$$

Becomes such that unchanged ,rank  $[a_{j1}, \dots, a_{jq-1}] \leq q - 2$ .

Therefore,(7) will still have a solution  $S'$  over some  $C^1$

such that  $C^1 \subset C^2$

So  $S'$  is a better solution. Q.E.D.

**Corollary:**

The number of the non-zero elements in a simple solution is at least 2 according to (6). Thus, a solution with 2 non-zero elements if existing is certainly simple because of the former theorem.

**Theorem 3:**

A solution is simple if and only if there does not exist any Other just as good one.

**Proof:**

The condition is trivially necessary, on the basis of Definition (3) . The sufficiency will be proved in the form

**Theorem 1:**

For the number of the non-zero Elements in a simple solution the inequality holds :

$$2 \leq q \leq r+1, r = \text{rank } A. \text{----- (6) .}$$

**Proof:**

Since the trivial solution of (3) has been disregarded due to Definition 1, no solution with  $q = 0$  exist. Nor does a solution exist with  $q = 1$ , A having no column with only zero elements .

Thus, for every solution of (3) , consequently for the simple ones as well,  $2 \leq q$  holds.

On the other hand, the inequality  $\text{rank } [a_{j1}, \dots, a_{jq}] \leq r$  is always true , hence, owing to (5) :

$$q = \text{rank}[a_{j1}, \dots, a_{jq} ] + 1 \leq r + 1 .$$

Q.E.D.

**Definition 4:**

Let  $S^1$  be a solution over  $C^1$  and  $S^2$  be a solution over  $C^2$  .

The solution  $S^1$  is said better than  $S^2$  if  $C^1$  is a proper sub- set of  $C^2$  ( $C^1 \subset C^2$  ) .

**Definition 5:**

The solution  $S^1$  is said just as good as  $S^2$  if they are solutions over the same  $C$  .

**Theorem 2:**

A solution is simple if and only if there does no exist any better one.

over C.

**Remark:**

Consider now a solution  $S=[s_1, \dots, s_n]$  of the set of equations:

$$\sum_{j=1}^n X_j A_j = 0, \quad X_{j_{q+1}} = \dots = X_{j_n} = 0.$$

where  $\{j_{q+1}, \dots, j_n\}$  is the complementary set of C in

**Definition 2.** Let it agreed that in this case one says, for the sake

of shortness, S to be a solution of equation :

$$\sum_{t=1}^q X_{j_t} A_{j_t} = 0. \text{-----} (4)$$

Consequently, if S is a solution over  $C = \{j_1, \dots, j_q\}$ , S is a solution of (4),

**Definition 3:**

Let S be a solution over  $C = \{j_1, \dots, j_q\}$ , S will be said simple if it is the only solution of (4) . under consideration of

**Definition 1,** S is simple if and only if:

$$\text{Rank } [a_1 \dots a_q] = q-1. \text{-----}(5).$$

$$\sum_{j=1}^n X_j A_{ij} = 0, \quad i = 1, 2, \dots, m. \quad \text{----- (1)}$$

Introducing the column vectors  $A_j = [A_{1j}, \dots, A_{mj}]$ ,  
 ( $j=1, \dots, n$ ), instead of (1):

$$\sum_{j=1}^n X_j A_j = 0. \quad \text{----- (2)}$$

can be written . Defining the matrix  $A = [a_1, \dots, a_n]$   
 and

the column vector  $X = [x_1, \dots, x_n]$ , (1) resp. (2) have the  
 form:

$$AX = 0 \quad \text{----- (3)}$$

We will assume  $A$  to have no column and no row  
 consisting of  
 pure zero elements.

**Definition 1:** In the set of the solutions  $S = [s_1, \dots, s_n]$   
 of (3):

- (a)- The trivial solution should be disregarded, and
- (b)- Two solutions  $S$  and  $a$ ,  $a \neq 0$  being a real number  
 , should be considered as a single solution .

So the number of the linearly independent solutions of  
 (3)  
 is  $n-r$ , where  $r = \text{rank } A$ .

**Definition 2:** Let the non-zero elements of the solutions

$$S = [s_1, \dots, s_n] \text{ be } S_{j_1}, \dots, S_{j_q} \text{ where}$$

$C = \{J_1, \dots, J_q\}$  is a combination of the numbers

$1, 2, \dots, n$  taken  $q \leq n$  at a time. Then  $S$  is said a  
 solution

# On The Simple Solutions Of Algebraic Homogeneous Linear Equations

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## Abstract

On solving algebraic homogeneous linear equation by Gramers rule, solutions can automatically be obtained in which the number of zero elements is maximal..In the present Communication, those so-called "simple" solutions are defined more simply ,in a combinatorial manner,and their properties are formulated more generally. The necessity of introducing simple solutions emerged originally in connection with a chemical problem.

## 1-Definitions of simple solutions and several criteria for their existence:

Let us consider the set of homogeneous Linear equations:

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