

Existence and Uniqueness Solution of fractional Nonlinear Integro-Differential Equation of Order (2α) with Boundary Conditions

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Abstract

In this paper we study the existence and uniqueness solution of fractional nonlinear integro-differential equation of order (2α) with boundary conditions, by using the Picard approximation method which is given by [3]. and we extend some results gained by [2].

Introduction

Many Arthur's discussed solving of differential and integral equation of fractional order. Here we refer to some of the works done in this area [2,5].

In this paper we set some definitions and lemmas to be used in the proof of the main theorem, for references [1,4].

Definition 1:

Let f be a function which is defined a. e. (almost every where) on $[a, b]$. For $\alpha > 0$, we define:

$$I_a^\alpha f = \frac{1}{\Gamma(\alpha)} \int_a^b (b-s)^{\alpha-1} f(s) ds$$

Provided this integral (Lebesgue) exists.

Definition 2:

If $\alpha > 0$, then camma's function is denote by (Γ)

and defined by the form: $\Gamma(\alpha) = \int_0^\infty e^{-s} s^{\alpha-1} ds$

Lemma 1:

If $\{f_n\}_{n=1}^\infty$ is a sequences of functions is defined on the set $E \subseteq R$ such that $|f_n| \leq M_n$, where M_n is a positive number, then $\sum_{n=1}^\infty f_n$ is uniformly convergent

on E if $\sum_{n=1}^\infty M_n$.

Lemma 2:

Let $E_\alpha(m, x) = \sum_{m=1}^\infty \frac{m^{n-1} x^{n\alpha-1}}{\Gamma(n\alpha)}$, where $m=R$, then:

1. the series converges for $x \neq 0$ and $\alpha > 0$.
2. the series converges everywhere when $\alpha \geq 0$.
3. if $\alpha = 0$, then $E_1(m, x) = \exp(mx)$.

For the proof see [1].

Lemma 3:

If K_1 and K_2 be a positive constant, and f be a continuous function on $a \leq t \leq b$, such that:

$$f(t) \leq K_1 + K_2 \int_a^t f(s) ds$$

Then

$$f(t) \leq K_1 \exp(K_2(t-a))$$

Now we are using the Picard approximation method for studying the solution of fractional second order nonlinear integro-differential equations, as the form:

$$x^{2\alpha}(t) = f\left(t, x(t), \dot{x}(t), \int_{-\infty}^t w(t, s)g(s, x(s), \dot{x}(s))ds\right), \dots \quad (1)$$

$$x^{(\alpha-1)}(0) = x_0, \quad 0 < \alpha \leq 1$$

with boundary conditions

$$x(a) = A, \quad x(b) = B \quad \dots \quad (2)$$

where the function $f(t, x, \dot{x}, y)$ is a continuous in t, x, \dot{x} and defined on the domain:

$$(t, x, \dot{x}, y) \in [0, T] \times G_\alpha \times G_{1\alpha} \times G_{2\alpha} \dots \quad (3)$$

Where $x \in G_\alpha \subseteq [0, T]$, $\dot{x} \in G_{1\alpha} \subseteq [0, T]$ and $G_{1\alpha}, G_{2\alpha}$ are closed and bounded domains and A, B are positive constants.

Suppose that the function $f(t, x, \dot{x}, y)$ satisfies the following inequalities:

$$\|f(t, x, \dot{x}, y)\| \leq M, \quad \dots \quad (4)$$

$$\|f(t, x_1, \dot{x}_1, y_1) - f(t, x_2, \dot{x}_2, y_2)\| \leq K_1 \|x_1 - x_2\|, \dots \quad (5)$$

$$+ K_2 \|\dot{x}_1 - \dot{x}_2\| + K_3 \|y_1 - y_2\|$$

$$\|g(t, x_1, \dot{x}_1) - g(t, x_2, \dot{x}_2)\| \quad \dots \quad (6)$$

$$\leq L_1 \|x_1 - x_2\| + L_2 \|\dot{x}_1 - \dot{x}_2\|$$

for all $t \in [0, T]$ and $x, x_1, x_2 \in G_\alpha$, $\dot{x}, \dot{x}_1, \dot{x}_2 \in G_{1\alpha}$ and $y, y_1, y_2 \in G_{2\alpha}$, where $M, K_1, K_2, K_3, L_1, L_2$, are positive constants and

$$y(t, x, \dot{x}) = \int_{-\infty}^t w(t, s)g(s, x(s), \dot{x}(s))ds.$$

The kernel function $w(t, s)$ was defined and continuous in $-\infty < 0 \leq a \leq \tau \leq s \leq t \leq b \leq T < \infty$, $\|w(t, s)\| \leq \delta e^{-\gamma(t-s)}$, where γ, δ be a positive constants.

We define the non-empty sets as follows:

$$\left. \begin{aligned} G_{\alpha f} &= G_\alpha - \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M \\ G_{1\alpha f} &= G_{1\alpha} - \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \\ G_{2\alpha f} &= G_{2\alpha} - \frac{\delta}{\gamma} \left[L_1 \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} + L_2 \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \right] M \end{aligned} \right\} \dots \quad (7)$$

where $\|.\| = \max |.|$.

Furthermore, we suppose that the greatest eigen value of the following matrix:

$$H_{0\alpha} = \begin{pmatrix} \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)t^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_2 \\ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \end{pmatrix}$$

is less than unity. i.e.

$$h_{\max}(H_{0\alpha}) < 1 \dots (8)$$

Existence Solution

The study of the existence solution of the problem (1), (2) will be introduced by the following:

Theorem 1:

Let the function $f(t, x, \dot{x}, y)$ be defined in the domain (3), continuous in t, x, \dot{x} and satisfy the inequalities (4), (5) and (6), then the sequence of functions:

$$x_{m+1}(t, x_0, \dot{x}_0, y_0) = \frac{[A + (t-a)\dot{x}_m(a)]t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t [(t-s)f(s, x_0, \dot{x}_0, y_0)(t-s)^{\alpha-1}] ds \dots (9)$$

.. (9) with

$$x_0 = A + \frac{(t-a)(B-A)}{(b-a)}, \dot{x}_0(t) = \frac{(B-A)}{(b-a)}, m = 0, 1, 2, \dots$$

converges uniformly on the domain:

$$(t, x_0, \dot{x}_0, y_0) \in [0, T] \times G_\alpha \times G_{1\alpha} \times G_{2\alpha} \dots (10)$$

to the limit function $x_\infty(t, x_0, \dot{x}_0, y_0)$ which is satisfying the integral equation:

$$x(t, x_0, \dot{x}_0, y_0) = \frac{[A + (t-a)\dot{x}(a)]t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t [(t-s)f(s, x(s), \dot{x}(s), y(s))(t-s)^{\alpha-1}] ds \dots (11)$$

... (11) provided that:

$$\|x_\infty(t, x_0, \dot{x}_0, y_0) - x_0\| \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M \dots (12)$$

$$\|\dot{x}_\infty(t, x_0, \dot{x}_0, y_0) - \dot{x}_0\| \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \dots (13)$$

and

$$\left(\begin{array}{l} \|x_\infty(t, x_0, \dot{x}_0, y_0) - x_m(t, x_0, \dot{x}_0, y_0)\| \\ \|\dot{x}_\infty(t, x_0, \dot{x}_0, y_0) - \dot{x}_m(t, x_0, \dot{x}_0, y_0)\| \end{array} \right) \dots (14)$$

$$\leq H_{0\alpha}^m (E - H_{0\alpha})^{-1} \Psi_{0\alpha}$$

for $t \in [0, T]$, $x_0 \in G_{\alpha f}$,

$$\dot{x}_0 \in G_{1\alpha f}, y_0 \in G_{2\alpha f}$$

where

$$H_{0\alpha} = \begin{pmatrix} \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)t^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_2 \\ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \end{pmatrix},$$

$$\Psi_{0\alpha} = \begin{pmatrix} \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M \\ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \end{pmatrix},$$

$$q_1 = K_1 + K_3 \frac{\delta}{\gamma} L_1, q_2 = K_2 + K_3 \frac{\delta}{\gamma} L_2.$$

Where E is identity matrix.

Proof:

Set $m=0$ and use (9), we get:

$$\begin{aligned} \|x(t, x_0, \dot{x}_0, y_0) - x_0\| &= \left\| \frac{[A + (t-a)\dot{x}_0(a)]t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)f(s, x_0, \dot{x}_0, y_0)(t-s)^{\alpha-1} ds - \frac{[A + (t-a)\dot{x}_0(a)]t^{\alpha-1}}{\Gamma(\alpha)} \right\| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_a^t |(t-a)f(s, x_0, \dot{x}_0, y_0)|(t-s)^{\alpha-1} ds \leq (T-a) \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \leq \frac{1}{\Gamma(\alpha)} \int_a^t |(t-s)f(s, x_0, \dot{x}_0, y_0)(t-s)^{\alpha-1}| ds \\ &\leq (T-a) \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \|x_1(t, x_0, \dot{x}_0, y_0) - x_0\| \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M \dots (15) \end{aligned}$$

Moreover on differentiating $x_1(t, x_0, \dot{x}_0, y_0)$, we find:

$$\begin{aligned} \|\dot{x}_1(t, x_0, \dot{x}_0, y_0) - \dot{x}_0\| &= \left\| \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_0, \dot{x}_0, y_0)(t-s)^{\alpha-1} ds - \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} \right\| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_a^t M (t-s)^{\alpha-1} ds = \frac{1}{\Gamma(\alpha)} M (t-s)^\alpha \Big|_a^t = \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \end{aligned}$$

so that

$$\|\dot{x}_1(t, x_0, \dot{x}_0, y_0) - \dot{x}_0\| \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \dots (16)$$

So that from (6), (15) and (16), we find

$$\begin{aligned} \|y_1(s, x_0, \dot{x}_0) - y_0(s)\| &= \left\| y_1(s, x_0, \dot{x}_0) - \int_{-\infty}^s \left[f\left(s, \int_{w(t,s)}^s \dot{x}_1(s), y_1(s)\right) ds \right] \left(\int_{w(t,s)}^s ds \right)^{\alpha-1} g(s, x_0, \dot{x}_0) ds \right\| \\ &\leq \int_{-\infty}^t \|w(t, s)\| \|g(s, x_1(s), \dot{x}_1(s)) - g(s, x_0, \dot{x}_0)\| ds \\ &\leq \int_{-\infty}^t \delta e^{-\gamma(t-s)} [L_1 \|x_1(s) - x_0\| + L_2 \|\dot{x}_1(s) - \dot{x}_0\|] ds \end{aligned}$$

so

$$\begin{aligned} \|y_1(s, x_0, \dot{x}_0) - y_0(s)\| &\leq \frac{\delta}{\gamma} \dots (17) \\ &\left[L_1 \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} + L_2 \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \right] M \end{aligned}$$

from (15), (16), (17) and the condition (8), we get

$$x_1(t, x_0, \dot{x}_0, y_0) \in G_\alpha,$$

$$\dot{x}_1(t, x_0, \dot{x}_0, y_0) \in G_{1\alpha} \text{ for all } t \in [0, T],$$

$$x_0 \in G_{\alpha f}, \dot{x}_0 \in G_{1\alpha f},$$

$$y_0(s) = \int_{-\infty}^s w(t, s) g(s, x_0, \dot{x}_0) ds \in G_{2\alpha f}.$$

Suppose that $x_{m-1}(t, x_0, \dot{x}_0, y_0) \in G_\alpha$, $\dot{x}_{m-1}(t, x_0, \dot{x}_0, y_0) \in G_{1\alpha}$, we have

$$\|x_m(t, x_0, \dot{x}_0, y_0) - x_0\| \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M$$

$$\|\dot{x}_m(t, x_0, \dot{x}_0, y_0) - \dot{x}_0\| \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M$$

$$\|y_m(s, x_0, \dot{x}_0) - y_0(s)\| \leq \frac{\delta}{\gamma} \left[L_1 \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} + L_2 \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \right] M$$

where $x_1(t, x_0, \dot{x}_0, y_0) \in G_\alpha$,

$\dot{x}_1(t, x_0, \dot{x}_0, y_0) \in G_{1\alpha}$ for all $t \in [0, T]$, $x_0 \in G_{\alpha f}$,

$\dot{x}_0 \in G_{1\alpha f}$, $y_0(s) \in G_{2\alpha f}$.

We prove now that the sequence (9) is uniformly convergent in (10). From (9), when $m=1$ we get:

$$\begin{aligned}
& \|x_2(t, x_0, \dot{x}_0, y_0) - x_1(t, x_0, \dot{x}_0, y_0)\| = \\
& \left\| \frac{[A + (t-a)\dot{x}_1(a)]t^{\alpha-1}}{\Gamma(\alpha)} + \right. \\
& \quad \left. \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) f(s, x_1(s), \dot{x}_1(s), y_1(s)) (t-s)^{\alpha-1} ds \right. \\
& \quad \left. - \frac{[A + (t-a)\dot{x}_0(a)]t^{\alpha-1}}{\Gamma(\alpha)} \right. \\
& \quad \left. - \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) f(s, x_0, \dot{x}_0, y_0) (t-s)^{\alpha-1} ds \right\| \\
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_1(a) - \dot{x}_0\| + \frac{1}{\Gamma(\alpha)} \\
& \quad \int_a^t (t-s) \|f(s, x_1(s), \dot{x}_1(s), y_1(s)) - f(s, x_0, \dot{x}_0, y_0)\| \\
& \quad (t-s)^{\alpha-1} ds \\
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_1(a) - \dot{x}_0\| + \\
& \quad \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) [K_1 \|x_1(s) - x_0\| + K_2 \|\dot{x}_1(s) - \dot{x}_0\| + K_3 \|y_1(s) - y_0\|] (t-s)^{\alpha-1} ds \\
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_1(t) - \dot{x}_0\| + \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|\dot{x}_1(t) - \dot{x}_0\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_1(t) - \dot{x}_0\| \right] \\
& = \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|\dot{x}_1(t) - \dot{x}_0\| + \left[\frac{(t-a)^{\alpha-1}}{\Gamma(\alpha)} + \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \right] \|\dot{x}_1(t) - \dot{x}_0\|
\end{aligned}$$

therefore

$$\begin{aligned}
& \|x_2(t, x_0, \dot{x}_0, y_0) - x_1(t, x_0, \dot{x}_0, y_0)\| \\
& \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_1(t) - x_0\| + \\
& \quad + \left[\frac{(T-a)^{\alpha+1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \right] \|\dot{x}_1(t) - \dot{x}_0\|
\end{aligned}$$

and

$$\begin{aligned}
& \|\dot{x}_2(t, x_0, \dot{x}_0, y_0) - \dot{x}_1(t, x_0, \dot{x}_0, y_0)\| = \left\| \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_1(s), \dot{x}_1(s), y_1(s)) (t-s)^{\alpha-1} ds - \right. \\
& \quad \left. - \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} - \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_0, \dot{x}_0, y_0) (t-s)^{\alpha-1} ds \right\| \\
& \leq \frac{1}{\Gamma(\alpha)} \int_a^t \|f(s, x_1(s), \dot{x}_1(s), y_1(s)) - f(s, x_0, \dot{x}_0, y_0)\| (t-s)^{\alpha-1} ds \\
& \leq \frac{1}{\Gamma(\alpha)} \int_a^t [K_1 \|x_1(s) - x_0\| + K_2 \|\dot{x}_1(s) - \dot{x}_0\| + K_3 \|y_1(s) - y_0\|] (t-s)^{\alpha-1} ds \\
& \leq \frac{(t-s)^\alpha}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_1(t) - x_0\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_1(t) - \dot{x}_0\| \right]
\end{aligned}$$

then

$$\begin{aligned}
& \|\dot{x}_2(t, x_0, \dot{x}_0, y_0) - \dot{x}_1(t, x_0, \dot{x}_0, y_0)\| \\
& \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|\dot{x}_1(t) - \dot{x}_0\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_1(t) - \dot{x}_0\| \right] \\
& \quad \|\dot{y}_2(s, x_0, \dot{x}_0) - \dot{y}_1(s, x_0, \dot{x}_0)\| = \\
& \quad \left\| \int_{-\infty}^t w(t, s) g(s, x_2(s), \dot{x}_2(s)) ds - \int_{-\infty}^t w(t, s) g(s, x_1(s), \dot{x}_1(s)) ds \right\| \\
& \leq \int_{-\infty}^t \|w(t, s)\| \|g(s, x_2(s), \dot{x}_2(s)) - g(s, x_1(s), \dot{x}_1(s))\| ds \\
\text{so } & \|y_2(s, x_0, \dot{x}_0) - y_1(s, x_0, \dot{x}_0)\| \\
& \leq \frac{\delta}{\gamma} [L_1 \|x_2(t) - x_1(t)\| + L_2 \|\dot{x}_2(t) - \dot{x}_1(t)\|]
\end{aligned}$$

Now when m=2 in (9) we get the following:

$$\begin{aligned}
& \|x_3(t, x_0, \dot{x}_0, y_0) - x_2(t, x_0, \dot{x}_0, y_0)\| = \\
& \left\| \frac{[A + (t-a)\dot{x}_2(a)]t^{\alpha-1}}{\Gamma(\alpha)} + \right. \\
& \quad \left. \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) f(s, x_2(s), \dot{x}_2(s), y_2(s)) (t-s)^{\alpha-1} ds \right. \\
& \quad \left. - \frac{[A + (t-a)\dot{x}_2(a)]t^{\alpha-1}}{\Gamma(\alpha)} - \right. \\
& \quad \left. \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) f(s, x_1(s), \dot{x}_1(s), y_1(s)) (t-s)^{\alpha-1} ds \right\| \\
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_2(a) - \dot{x}_1(a)\| + \\
& \quad \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) \|f(s, x_2(s), \dot{x}_2(s), y_2(s)) - f(s, x_1(s), \dot{x}_1(s), y_1(s))\| \\
& \quad (t-s)^{\alpha-1} ds
\end{aligned}$$

(t-s)^{\alpha-1} ds

$$\begin{aligned}
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_2(a) - \dot{x}_1(a)\| + \\
& \quad \frac{1}{\Gamma(\alpha)} \int_a^t (t-s) \|f(s, x_2(s), \dot{x}_2(s), y_2(s)) - f(s, x_1(s), \dot{x}_1(s), y_1(s))\| \\
& \quad (t-s)^{\alpha-1} ds
\end{aligned}$$

therefore

$$\begin{aligned}
& \|x_3(t, x_0, \dot{x}_0, y_0) - x_2(t, x_0, \dot{x}_0, y_0)\| \\
& \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_2(t) - x_1(t)\| + \\
& \quad + \left[\frac{(T-a)^{\alpha+1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \right] \|\dot{x}_2(t) - \dot{x}_1(t)\|
\end{aligned}$$

and

$$\begin{aligned}
& \|\dot{x}_3(t, x_0, \dot{x}_0, y_0) - \dot{x}_2(t, x_0, \dot{x}_0, y_0)\| = \left\| \frac{\dot{x}_1 t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_2(s), \dot{x}_2(s), y_2(s)) (t-s)^{\alpha-1} ds - \right. \\
& \quad \left. - \frac{\dot{x}_1 t^{\alpha-1}}{\Gamma(\alpha)} - \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_0, \dot{x}_0, y_0) (t-s)^{\alpha-1} ds \right\| \\
& \leq \frac{1}{\Gamma(\alpha)} \int_a^t \|f(s, x_2(s), \dot{x}_2(s), y_2(s)) - f(s, x_0, \dot{x}_0, y_0)\| (t-s)^{\alpha-1} ds \\
& \leq \frac{(t-a)t^{\alpha-1}}{\Gamma(\alpha)} \|\dot{x}_2(t) - \dot{x}_1(t)\| + \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|\dot{x}_2(t) - \dot{x}_1(t)\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_2(t) - \dot{x}_1(t)\| \right] \\
& = \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|\dot{x}_2(t) - \dot{x}_1(t)\| + \left[\frac{(t-a)^{\alpha-1}}{\Gamma(\alpha)} + \frac{(t-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \right] \|\dot{x}_2(t) - \dot{x}_1(t)\|
\end{aligned}$$

therefore

$$\begin{aligned}
& \|x_3(t, x_0, \dot{x}_0, y_0) - x_2(t, x_0, \dot{x}_0, y_0)\| \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_2(t) - x_1(t)\| + \\
& \quad + \left[\frac{(T-a)^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \right] \|\dot{x}_2(t) - \dot{x}_1(t)\|
\end{aligned}$$

and

$$\begin{aligned}
& \|\dot{x}_3(t, x_0, \dot{x}_0, y_0) - \dot{x}_2(t, x_0, \dot{x}_0, y_0)\| = \left\| \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_2(s), \dot{x}_2(s), y_2(s)) (t-s)^{\alpha-1} ds - \right. \\
& \quad \left. - \frac{\dot{x}_0 t^{\alpha-1}}{\Gamma(\alpha)} - \frac{1}{\Gamma(\alpha)} \int_a^t f(s, x_1(s), \dot{x}_1(s), y_1(s)) (t-s)^{\alpha-1} ds \right\|
\end{aligned}$$

$$\begin{aligned} &\leq \frac{1}{\Gamma(\alpha)} \int_a^t \|f(s, x_2(s), \dot{x}_2(s), y_2(s)) - f(s, x_1(s), \dot{x}_1(s), y_1(s))\| (t-s)^{\alpha-1} ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_a^t [K_1 \|x_2(s) - x_1(s)\| + K_2 \|\dot{x}_2(s) - \dot{x}_1(s)\| + K_3 \|y_2(s) - y_1(s)\|] (t-s)^{\alpha-1} ds \\ &= \frac{(t-a)^\alpha}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_2(t) - x_1(t)\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_2(t) - \dot{x}_1(t)\| \right] \end{aligned}$$

then

$$\begin{aligned} &\|\dot{x}_3(t, x_0, \dot{x}_0, y_0) - \dot{x}_2(t, x_0, \dot{x}_0, y_0)\| \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \left[\left(K_1 + K_3 \frac{\delta}{\gamma} L_1 \right) \|x_2(t) - x_1(t)\| + \left(K_2 + K_3 \frac{\delta}{\gamma} L_2 \right) \|\dot{x}_2(t) - \dot{x}_1(t)\| \right] \\ &\|y_3(s, x_0, \dot{x}_0) - y_2(s, x_0, \dot{x}_0)\| = \left\| \int_{-\infty}^s w(t, s) g(s, x_3(s), \dot{x}_3(s)) ds - \int_{-\infty}^s w(t, s) g(s, x_2(s), \dot{x}_2(s)) ds \right\| \\ &\leq \int_{-\infty}^t \|w(t, s)\| \|g(s, x_3(s), \dot{x}_3(s)) - g(s, x_2(s), \dot{x}_2(s))\| ds \end{aligned}$$

so

$$\|y_3(s, x_0, \dot{x}_0) - y_2(s, x_0, \dot{x}_0)\| \leq \frac{\delta}{\gamma}$$

$$[L_1 \|x_3(t) - x_2(t)\| + L_2 \|\dot{x}_3(t) - \dot{x}_2(t)\|]$$

By induction we have:

$$\begin{aligned} &\|x_{m+1}(t, x_0, \dot{x}_0, y_0) - x_m(t, x_0, \dot{x}_0, y_0)\| \\ &\leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 \|x_m(t) - x_{m-1}(t)\| + \\ &+ \left[\frac{(T-a)^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_2 \right] \|\dot{x}_m(t) - \dot{x}_{m-1}(t)\| \dots (18) \end{aligned}$$

$$\begin{aligned} &\|\dot{x}_{m+1}(t, x_0, \dot{x}_0, y_0) - \dot{x}_m(t, x_0, \dot{x}_0, y_0)\| \\ &\leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_1 \|x_m(t) - x_{m-1}(t)\| \\ &+ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \|\dot{x}_m(t) - \dot{x}_{m-1}(t)\| \dots (19) \end{aligned}$$

Rewrite inequalities (18) and (19) in vector from:

$$\Psi_{m+1}(t, x_0, \dot{x}_0, y_0) \leq H(t) \Psi_m(t, x_0, \dot{x}_0, y_0) \dots (20)$$

$$\Psi_{m+1}(t, x_0, \dot{x}_0, y_0) =$$

$$H(t) = \begin{pmatrix} \left\| x_{m+1}(t, x_0, \dot{x}_0, y_0) - x_m(t, x_0, \dot{x}_0, y_0) \right\| \\ \left\| \dot{x}_{m+1}(t, x_0, \dot{x}_0, y_0) - \dot{x}_m(t, x_0, \dot{x}_0, y_0) \right\| \end{pmatrix}$$

$$\begin{pmatrix} \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_2 \\ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_1 & \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \end{pmatrix}$$

$$\Psi_m(t, x_0, \dot{x}_0, y_0) =$$

$$\begin{pmatrix} \left\| x_m(t, x_0, \dot{x}_0, y_0) - x_{m-1}(t, x_0, \dot{x}_0, y_0) \right\| \\ \left\| \dot{x}_m(t, x_0, \dot{x}_0, y_0) - \dot{x}_{m-1}(t, x_0, \dot{x}_0, y_0) \right\| \end{pmatrix}$$

It follows from inequality (20) that:

$$\Psi_{m+1}(t) \leq H_{0\alpha} \Psi_m(t) \dots (21)$$

where

$$H_{0\alpha} = \max_{t \in [0, T]} H(t)$$

By iterating inequality (21), we have

$$\Psi_{m+1}(t) \leq H_{0\alpha}^m \Psi_m(t) \dots (22)$$

where

$$\Psi_{0\alpha} = \begin{cases} \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} M \\ \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} M \end{cases}$$

this leads to the estimation:

$$\sum_{i=1}^m \Psi_i \leq \sum_{i=1}^m H_{0\alpha}^{i-1} \Psi_{0\alpha} \dots (23)$$

since the matrix H_0 has eigenvalues:

$$h_{\max}(H_{0\alpha}) = \frac{1}{2} \left[\frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 + \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 + \sqrt{\left(\frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 + \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \right)^2 + 4 \frac{(T-a)^{\alpha+1} t^{\alpha-1}}{\Gamma(\alpha) \Gamma(\alpha+1)} q_1} \right]$$

then the series (9) is uniformly convergent in (10), i.e.

$$\lim_{m \rightarrow \infty} \sum_{i=1}^m H_{0\alpha}^{i-1} \Psi_{0\alpha} = \sum_{i=1}^{\infty} H_{0\alpha}^{i-1} \Psi_{0\alpha} = (E - H_{0\alpha})^{-1} \Psi_{0\alpha} \dots (24)$$

The limiting relation (24) signifies a uniform convergent of the sequence $x_m(t, x_0, \dot{x}_0, y_0)$,

$$\dot{x}_m(t, x_0, \dot{x}_0, y_0)$$

$$\left. \begin{array}{l} \lim_{m \rightarrow \infty} x_m(t, x_0, \dot{x}_0, y_0) = x_\infty(t, x_0, \dot{x}_0, y_0) \\ \lim_{m \rightarrow \infty} \dot{x}_m(t, x_0, \dot{x}_0, y_0) = \dot{x}_\infty(t, x_0, \dot{x}_0, y_0) \end{array} \right\} \dots (25)$$

By inequality (25), the estimation:

$$\left. \begin{array}{l} \left\| x_\infty(t, x_0, \dot{x}_0, y_0) - x_m(t, x_0, \dot{x}_0, y_0) \right\| \\ \left\| \dot{x}_\infty(t, x_0, \dot{x}_0, y_0) - \dot{x}_m(t, x_0, \dot{x}_0, y_0) \right\| \end{array} \right\} \dots (26)$$

$$\leq H_{0\alpha}^m (E - H_{0\alpha})^{-1} \Psi_{0\alpha}$$

is true for $m=1, 2, 3, \dots$

Thus $x_\infty(t, x_0, \dot{x}_0, y_0)$ is a solution of integro-differential equations (1), (2).

Uniqueness solution

The study of the uniqueness solution of the problem (1), (2) will be introduced by the following:

Theorem 2:

Let all assumptions and conditions of theorem 1 be given then the problem (1), (2) has a unique solution $x = x_\infty(t, x_0, \dot{x}_0, y_0)$ on the domain (10).

Proof:

We have to show to that $x(t, x_0, \dot{x}_0, y_0)$ is a unique solution of problem (1), (2). On the contrary, we suppose that there is at least two different solutions $x(t, x_0, \dot{x}_0, y_0)$ and $\hat{x}(t, x_0, \dot{x}_0, y_0)$ of the problem (1), (2).

From (11) the following inequalities are holds:

$$\|x(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \leq \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_1 \|x(t) - \hat{x}(t)\| \dots (27)$$

$$+ \left[\frac{(T-a)t^{\alpha-1}}{\Gamma(\alpha)} + \frac{(T-a)^{\alpha+1}}{\Gamma(\alpha+1)} q_2 \right] \|\dot{x}(t) - \hat{x}(t)\|$$

on differentiating (27) we should also obtain:

$$\|\dot{x}(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \leq \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} \dots (28)$$

$$q_1 \|x(t) - \hat{x}(t)\| + \frac{(T-a)^\alpha}{\Gamma(\alpha+1)} q_2 \|\dot{x}(t) - \hat{x}(t)\|$$

Inequalities (27) and (28) would lead to the estimation:

$$\left\| \begin{array}{l} \|x(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \\ \| \dot{x}(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0) \| \end{array} \right\| \leq H_{0\alpha} \left(\begin{array}{l} \|x(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \\ \| \dot{x}(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0) \| \end{array} \right)$$

By iterating we should find that:

$$\left\| \begin{array}{l} \|x(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \\ \| \dot{x}(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0) \| \end{array} \right\| \leq H_{0\alpha}^m \left(\begin{array}{l} \|x(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0)\| \\ \| \dot{x}(t, x_0, \dot{x}_0, y_0) - \hat{x}(t, x_0, \dot{x}_0, y_0) \| \end{array} \right)$$

But $H_{0\alpha}^m \rightarrow 0$ as $m \rightarrow \infty$, hence proceeding in the last inequality to the limit we should obtain the equalities $x(t, x_0, \dot{x}_0, y_0) = \hat{x}(t, x_0, \dot{x}_0, y_0)$ and $\dot{x}(t, x_0, \dot{x}_0, y_0) = \hat{x}(t, x_0, \dot{x}_0, y_0)$ which proves the solution is a unique and this completes the proof of the theorem.

Stability solution

The study of the stability solution of the problem (1), will be introduced by the following theorem:

Theorem 3:

If the inequalities (4), (5) and (6), were satisfied, and $z(t, x_0, y_0)$, which was defined bellow as different solutions for the equation (1), then the solution was stable if satisfy the inequality:

$$|x_0(0, x_0, y_0) - z(0, x_0, y_0)| < \delta, \quad \delta < 0$$

Where

$$\begin{aligned} x(t, x_0, \dot{x}_0, y_0) &= \frac{[A + (t-a)\dot{x}_0]t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \\ &\int_a^t [(t-s)f(t, x(s), \dot{x}(s), y(s))] [t-s]^{\alpha-1} ds \\ z(t, x_0, \dot{x}_0, y_0) &= \frac{[A + (t-a)\dot{z}_0]t^{\alpha-1}}{\Gamma(\alpha)} + \frac{1}{\Gamma(\alpha)} \\ &\int_a^t [(t-s)f(t, z(s), \dot{z}(s), y(s))] [t-s]^{\alpha-1} ds \end{aligned}$$

proof:

$$\|x(t, x_0, \dot{x}_0, y_0) - z(t, x_0, \dot{x}_0, y_0)\| =$$

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وجود وحدانية الحل لمعادلة تكاملية-تفاضلية لخطية من الرتبة الكسرية (2α)

مع شروط حدودية

غادة شكر جميل

قسم الرياضيات ، كلية التربية ، جامعة الموصل ، الموصل ، العراق

الملخص

يتضمن البحث دراسة وجود وحدانية الحل لمعادلة تكاملية-تفاضلية لخطية من الرتبة الكسرية (2α) مع شروط حدودية وذلك باستخدام طريقة بيكارد للتقرير المعطاة في المرجع [3]. إذ استطعنا من خلال هذه الدراسة توسيع بعض النتائج المعطاة في المرجع [2].