

Abstract

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Better Quantile Contour for Constructing Growth Charts

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construct a better contours.

In this paper we going to comparison using Mean Absolute Error

(MAE), among three nonparametric methods: Nadaraya-Watson (NW),

B-Splines (BS) and Smoothing Spline (SS) which use to estimate

quantile functions depending on the model of time-varying coefficient

under the concept of depth in the bivariate case, to prepare for

We used simulation study for construct two stages: first stage is to

construct the simulation models for the three nonparametric methods

and then comparison among them by using MAE, where the method that

gives the least MAE is the best method, and the second stage is to plot

Where it was concluded that the BS is the best method because it's given

a suitable contouring shape and less MAE which equal to 0.048 which

the best method which given the best contour shape.

will be used to plot best bivariate growth charts.

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Introduction

They regression analysis, it's a technique which has become widely used and applied in many areas of academic and applied sciences such as social sciences, medical researches, biology, meteorology, psychology, chemistry and economics. So, depending on the regression, a number of researchers have resorted to using the quantile regression models to constructing the growth charts in univariate case. So the researcher decided to develop the quantile regression from univariate to multivariate used combining the two concepts (time-varying coefficient) and (depth) by construct a new model (time-varying coefficient with depth) which depending on a proposed generalization equation to find quantile functions, then use nonparametric methods (Nadaraya-Watson (NW), B-Splines (BS) with nodes (0.5, 1, 1.5, 2 and 2.5) and Smoothing Spline (SS)) to estimate those functions and find the best method. But first we have to explain why a model was used the model of time-varying coefficient with depth?

To rank the data points in the high dimension (multidimensional space), it used depth to benefit for contours is to provide a reasonable concept of quantile contours, and it was added with

(A)

that concept the concept of the time-varying coefficient which can transform the linear regression or non-linear parametric regression to linear regression since it describes the effect of variables as a constant correlation coefficient. Hence the final model used of multivariate quantile regression depending on the model of time-varying coefficient with depth.

In this paper, we applied in the bivariate case in order to obtain the contours and thus obtain the bivariate growth charts because the difficulty of generalization and programming as well as for compatibility between methods when using nonparametric methods and applied under condition dimensional for each of the models.

Theoretical and Dynamic side

First, we have to review the two stratified quantile regression models which will be to study[4]:

The marginal model
$$Q_{Y_1}(q)$$
 of $Y_{t,1} = y_1$, where:
 $Q_q(Y_{i,j,1}) = g_1(q; t_{i,j}, X_{i,j})$
(1)
And

The conditional models $Q_{Y_2}(q)$ of $Y_{t,2}$ given $Y_{t,1}$, where:

 $Q_q(Y_{i,j,2}) = g_2(q; t_{i,j}, \boldsymbol{X}_{i,j}, Y_{i,j,1})$ (2) Then, we write the models as:

$$Q_q(Y_{i,j,1}) = \alpha_1(q; t_{i,j}) + \sum_{k=1}^d \gamma_{1k}(q; t_{i,j}) X_{i,j,k}$$
(3)

Where

$$\widehat{g}_{n1}(q) = \operatorname{argmin}\sum_{i,j} \rho_q \left(Y_{i,j,1} - g_1(t_{i,j}, \boldsymbol{X}_{i,j}) \right)$$

And

$$Q_{q}(Y_{i,j,2}) = \alpha_{2}(q;t_{i,j}) + \beta_{2}(q;t_{i,j})Y_{i,j,1} + \sum_{k=1}^{a} \gamma_{2k}(q;t_{i,j}) \mathbf{X}_{i,j,k}$$
(5)

Where

$$\widehat{g}_{n2}(q) = \operatorname{argmin} \sum_{i,j} \rho_q \left(Y_{i,j,2} - g_2(t_{i,j}, \boldsymbol{X}_{i,j}, Y_{i,j,1}) \right)$$
(6)

Then the researcher proposed equation for $Y \in \mathbb{R}^p$ can be written as the general model for timevarying coefficient models as the following:

$$Q_{q}(Y_{i,j,p}) = \sum_{L=1}^{p} \beta(q; t_{i,j}) Y_{i,j,p-1} + \sum_{k=1}^{d} \gamma_{pk}(q; t_{i,j}) X_{i,j,k}$$
(7)
Where

Where

 $\boldsymbol{\beta} = (\beta_{p_1}, \beta_{p_2}, \dots, \beta_{p_p})$, and $L = 1, \dots, p$, if L = 1 that means the marginal model and if $L \ge 2$ that means the conditional model, the researcher sought to build a comprehensive equation. Note that, the solution of the conditional sequence became more difficult in high dimensions.

We will used combining the two concepts (time-varying coefficient and depth) to construct a new concept (time-varying coefficient with depth) but first we must study the regression case which is the second definition of Koenker-Bassett methods when the linear regression is an extension for covariates in dimension $d \ge 1$, so in this method, pairs will be dealt with which is denoted as $(X^{\mathsf{T}}, Y^{\mathsf{T}})$ where $(X, Y) \in \mathbb{R}^d \times \mathbb{R}^p$.

Let have the random vector of covariates $X := (X_1, ..., X_d)^{\mathsf{T}}$

And, let $\boldsymbol{Y} := (Y_1, ..., Y_p)^{\mathsf{T}} \in \mathbb{R}^p$ and the marginal quantiles $q_{q,j}$, j = 1, 2, ..., p where are obtained by projecting \boldsymbol{P} which characterized through the p marginal distribution functions on, then $\boldsymbol{q}_{q_1,...,q_p} := (q_{q_1,1,...}, q_{q_p,p})^{\mathsf{T}}$

Where it's coordinate wise multivariate quantile. And if studying the empirical case for any observed it can be written the empirical marginal distributions P_n for n as $Y_1, ..., Y_n$.

Note that, this projecting P be on p mutually orthogonal straight lines, where it's distinguished by canonical orthonormal basis $u_1, ..., u_p$ direct by many origins. Where to facilitate the process to see the projections over all unit vectors where $u \in S^{p-1}$ as previously mentioned, are direct by many origins.

For each direction u it can be got a good quantile q_{qu} of order $q \in (0,1)$ from the univariate distribution of $u^{\mathsf{T}}Y$.

The directional q -quantile hyperplane Π_{qu} , where $(a, b^{\mathsf{T}}, \beta^{\mathsf{T}})^{\mathsf{T}} \in \mathbb{R}^{d+p}$ become as the equation: $u^{\mathsf{T}}y = b_{qu}^{\mathsf{T}}\Gamma_{u}^{\mathsf{T}}y + \beta_{qu}^{\mathsf{T}}x + a_{qu}$ (8)

Then the estimates of q or written as $(a_{qu}, \boldsymbol{b}_{qu}^{\mathsf{T}}, \boldsymbol{\beta}_{qu}^{\mathsf{T}})^{\mathsf{T}}$ can be obtained by minimizing the quantile regression of the objective function q as:

$$\left(a_{q\boldsymbol{u}},\boldsymbol{b}_{q\boldsymbol{u}}^{\mathsf{T}},\boldsymbol{\beta}_{q\boldsymbol{u}}^{\mathsf{T}}\right)^{\mathsf{T}} = \underset{(a,\boldsymbol{b}^{\mathsf{T}},\boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}}\in\mathbb{R}^{d+p}}{\operatorname{argmin}} E\left[\rho_{q}(\boldsymbol{Y}_{\boldsymbol{u}}-\boldsymbol{b}^{\mathsf{T}}\boldsymbol{Y}_{\boldsymbol{u}}^{\mathsf{L}}-\boldsymbol{\beta}^{\mathsf{T}}\boldsymbol{X}-a)\right]$$
(9)

And for the empirical distribution the minimizing become as:

$$\left(a_{q\boldsymbol{u}}^{(n)}, \boldsymbol{b}_{q\boldsymbol{u}}^{(n)^{\mathsf{T}}}, \boldsymbol{\beta}_{q\boldsymbol{u}}^{(n)^{\mathsf{T}}}\right)^{\mathsf{T}} = \underset{(a,\boldsymbol{b}^{\mathsf{T}},\boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}}\in\mathbb{R}^{d+p}}{\operatorname{argmin}} \sum_{i=1}^{n} \rho_q \left(\boldsymbol{Y}_{i,\boldsymbol{u}} - \boldsymbol{b}^{\mathsf{T}} \boldsymbol{Y}_{i,\boldsymbol{u}}^{\perp} - \boldsymbol{\beta}^{\mathsf{T}} \boldsymbol{X} - a\right)$$
(10)

The empirical distribution for the directional q –quantile hyperplane Π_{qu} , where $(a, b^{\mathsf{T}}, \beta^{\mathsf{T}})^{\mathsf{T}} \in \mathbb{R}^{d+p}$ become as the equation:

$$\boldsymbol{u}^{\mathsf{T}}\boldsymbol{y} = \boldsymbol{b}_{q\boldsymbol{u}}^{(n)\mathsf{T}}\boldsymbol{\Gamma}_{\boldsymbol{u}}^{\mathsf{T}}\boldsymbol{y} + \boldsymbol{\beta}_{q\boldsymbol{u}}^{(n)\mathsf{T}}\boldsymbol{x} + a_{q\boldsymbol{u}}^{(n)}$$
(11)

Estimation by using quantile technique

We estimate the two quantile function by used three of nonparametric methods: kernel regression (Nadaraya-Watson), B-splines and Smoothing splines depending on the concept of time-varying coefficient with directional Koenker-Bassett quantile regression. Now, it will study the estimation of the directional q -quantile hyperplane Π_{qu} , under the nonparametric case with the distribution P of Y conditional on X = x, where $Y := (Y_1, ..., Y_p)^{\mathsf{T}} \in \mathbb{R}^p$ and $X := (X_1, ..., X_d)^{\mathsf{T}}$, which is possible to apply this concept only for $d + p \leq 3$ where d = 1, p = 2, the general model is

$$Q_q(\mathbf{Y}_{i,j,p}) = q_p \tag{12}$$

The directional q -quantile hyperplane Π_{qu} , under location case where $(a, \mathbf{b}^{\mathsf{T}}, \boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}} \in \mathbb{R}^{d+p}$ is: $Q_q(\mathbf{Y}_{i,j,p}) = q_p = \mathbf{u}^{\mathsf{T}} \mathbf{y} = \mathbf{b}_{qu}^{\mathsf{T}} \mathbf{\Gamma}_u^{\mathsf{T}} \mathbf{y} + a_{qu}$ (13) The directional q -quantile hyperplane Π_{qu} , under the nonparametric case where $(a, \mathbf{b}^{\mathsf{T}}, \boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}} \in$

The directional q –quantile hyperplane Π_{qu} , under the nonparametric case where $(a, b^{\dagger}, \beta^{\dagger})^{\dagger} \in \mathbb{R}^{d+p}$ is:

$$Q_q(\boldsymbol{Y}_p) = q_p = \boldsymbol{u}^{\mathsf{T}} \boldsymbol{y} = \boldsymbol{b}_{q\boldsymbol{u}}^{\mathsf{T}} \boldsymbol{\Gamma}_{\boldsymbol{u}}^{\mathsf{T}} \boldsymbol{y} + \boldsymbol{\beta}_{q\boldsymbol{u}}^{\mathsf{T}} \boldsymbol{x} + a_{q\boldsymbol{u}}$$
(14)

Then, the estimates of q or written as $(a_{qu}, \mathbf{b}_{qu}^{\mathsf{T}}, \boldsymbol{\beta}_{qu}^{\mathsf{T}})$ can be obtained by minimizing the quantile regression of the objective function q as:

$$\left(a_{q\boldsymbol{u}},\boldsymbol{b}_{q\boldsymbol{u}}^{\mathsf{T}},\boldsymbol{\beta}_{q\boldsymbol{u}}^{\mathsf{T}}\right)^{\mathsf{T}} = \underset{(a,\boldsymbol{b}^{\mathsf{T}},\boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}}\in\mathbb{R}^{d+p}}{\operatorname{argmin}} E\left[\rho_{q}(\boldsymbol{Y}_{\boldsymbol{u}}-\boldsymbol{b}^{\mathsf{T}}\boldsymbol{Y}_{\boldsymbol{u}}^{\perp}-\boldsymbol{\beta}^{\mathsf{T}}\boldsymbol{X}-a)\right]$$
(15)

Now, we will write the above equations under the concept of time-varying coefficient with directional Koenker-Bassett (depth) quantile regression

First method: it will to using Nadaraya-Watson method [5], depending on the concept of directional Koenker-Bassett quantile regression we get the following equation [3]:

$$\hat{q}_{(NW-dir)}(q) = \underset{(a,\boldsymbol{b}^{\mathsf{T}},\boldsymbol{\beta}^{\mathsf{T}})^{\mathsf{T}}\in\mathbb{R}^{d+p}}{\operatorname{argmin}} \sum \rho_q \left(\boldsymbol{Y} - (\boldsymbol{b}^{\mathsf{T}}\boldsymbol{Y}_{\boldsymbol{u}}^{\perp} + \boldsymbol{\beta}^{\mathsf{T}}\boldsymbol{X} + a) \right) K \left(\frac{t-T}{h} \right)$$
(16)

Second method (proposal 1): it will to suggest B-spline in a linear space \mathbb{G}_{ℓ} of spline • function on T with а fixed degree and with Knot sequence а depending on the concept of time-varying coefficient with directional Koenker-Bassett quantile regression as:

$$\hat{q}_{(BS-dir)M}(q) = \arg\min\sum_{i=1}^{n} W_i \sum \left(\rho_q \left(\mathbf{Y} - (\mathbf{b}^{\mathsf{T}} \mathbf{Y}_{\mathbf{u}}^{\mathsf{L}} + \boldsymbol{\beta}^{\mathsf{T}} \mathbf{X} + a) \right) \right)^2$$
(17)

(proposal Third method 2): it will to suggest smoothing spline • depending on the concept of time-varying coefficient with directional Koenker-Bassett quantile regression [2] as:

$$\hat{q}_{(SS-dir)M}(q) = \arg\min\sum_{i,j} \rho_q \left(\mathbf{Y} - (\mathbf{b}^{\mathsf{T}} \mathbf{Y}_{u}^{\perp} + \boldsymbol{\beta}^{\mathsf{T}} X + a) \right)^2 + \lambda \|m''\|_2^2$$
(18)

Simulation study

We used simulation study in two stages:

First stage which represented by a comparison nonparametric methods (Nadaraya-Watson (NW), B-Splines (BS) with nodes (0.5, 1, 1.5, 2 and 2.5) and Smoothing Spline (SS)), which used to estimation the quantile functions for the models under the concept (time-varying coefficient with depth), then we chose the methods which gave least MAE in the different sample sizes (10, 30, 50), so it was excluded (NW) see the table below [4]: Т

MAE	NW (T & d	lirectional)	BS (T & d	irectional)	SS (T & d	lirectional)	Min
Q n	$Q_q(Y_1)$	$Q_q(Y_2)$	$Q_q(Y_1)$	$Q_q(Y_2)$	$Q_q(Y_1)$	$Q_q(Y_2)$	171111
10	13.5007416	4.77627179	194.541118	8.08919566	5.59156263	2.96445351	2.96E+00
30	15.7056731	20.7030898	260.283264	197.869744	3.84958012	5.94649665	3.85E+00
50	3.12250646	21.0582218	0.28432887	820.911835	0.83553168	8.72855374	2.84E -01

able 1.	Represent	the	MAE	for	first stage

• Second stage which represented to find the best contour shape from the best methods chosen from the first stage which gaves the best quantiles and with the least MAE).

It was noted that the best method is B-splines (BS) for the time-varying coefficient with directional Koenker-Bassett which achieved the lowest MAE, as shown in the table and figures below:

Model	First stage	Second stage	Figure
A.2.b SS	4.84E-01	0.87	Given acceptable contours and good MAE.
A.2.b BS	0.28432887	0.048	Given good contours and good MAE because it's less MAE.

Table 2: Represent the MAE for first and second stages with degree of quantiles

Practical application

We will be used real data to plotting standard growth charts for children under the age of five years from Iraq Multiple Indicator Cluster Survey (MICS-4) 2011 for all governorates of Iraq and applied on the model that gave best method chosen in the Simulation study [1, 6]. For example: class (0-5 month) was taken as an applied example, see the illustrate figure below:



Figure 1: Represent the Analysis bivariate growth charts

Conclusion

in this paper, we discussed the bivariate case by used combining the two concepts (time-varying coefficient) and (depth) by construct a new model (time-varying coefficient with depth) which depending on a proposed generalization equation to find quantile functions, then use nonparametric methods (Nadaraya-Watson (NW), B-Splines (BS) with nodes (0.5, 1, 1.5, 2 and 2.5) and Smoothing Spline (SS)) to estimate those functions and find the best method. As it was found that model B gave less MAE = 0.048, note that we using the nonparametric method (B-spline). Then applied real data by using the best model, see the figure 1.

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افضل تقسيمات كونتورية لبناء مخططات النمو

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المستخلص

تناول البحث اجراء مقارنة باستخدام متوسط الخطأ المطلق (MAE) بين ثلاث طرق لامعلمية وهي (NW) Nadaraya-Watson، (BS) (BS)، و Smoothing Spline (SS) والتي تستخدم لتقدير الدوال التقسيمية اعتمادًا على نموذج معامل متغير بمرور الوقت في ظل مفهوم العمق في حالة ثنائي المتغير، للتحضير لبناء أفضل شكل كونتوري. استخدمنا در اسة المحاكة لبناء مرحلتين: المرحلة الأولى هي بناء نماذج المحاكاة للطرق الثلاثة اللامعلمية ومن ثم المقارنة فيما بينها باستخدام متوسط الخطأ المطلق MAE، حيث أن الطريقة التي تعطي أقل MAE هي الطريقة الأفضل، والمرحلة الثانية هي رسم أفضل طريقة تعطي أفضل شكل كونتوري.

حيث تم التوصل إلى أن طريقة BS هي الطريقة الأفضل لأنها تعطى شكل كونتور مناسب وبأقل MAE والذي بلغت قيمته 0.048 والتي سيتم استخدامها لرسم أفضل مخططات النمو ثنائية المتغير.

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الانحدار التقسيمي؛ Nadaraya-Watson B-Splines (BS) Smoothing (NW) (NW) معامل متغير بمرور الوقت؛ العمق؛ متوسط الخطأ المطلق، شكل كونتوري ومخططات النمو ثنائية المتغير.

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