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|----------|-----|----|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 40 | 8 | 0.8555 | 0.8677 | 0.9042 | 0.7982 | 0.8095 | 0.8436 | 0.8274 | 0.839 | 0.874 |
| | | 10 | 0.8293 | 0.8649 | 0.872 | 0.7737 | 0.8069 | 0.8061 | 0.802 | 0.8363 | 0.8435 |
| | 100 | 10 | 0.878 | 0.9051 | 0.936 | 0.8192 | 0.8444 | 0.8733 | 0.849 | 0.8753 | 0.9051 |
| | | 20 | 0.8667 | 0.874 | 0.881 | 0.8087 | 0.8153 | 0.8217 | 0.8381 | 0.8451 | 0.852 |
| g_{ML} | 10 | 3 | 0.811 | 0.8317 | 0.860 | 0.7565 | 0.7760 | 0.8376 | 0.7842 | 0.8042 | 0.8317 |
| | | 5 | 0.795 | 0.8166 | 0.8572 | 0.7416 | 0.762 | 0.8000 | 0.7686 | 0.7900 | 0.829 |
| | 40 | 8 | 0.8628 | 0.8751 | 0.9119 | 0.805 | 0.8165 | 0.8510 | 0.8345 | 0.8462 | 0.8817 |
| | | 10 | 0.8364 | 0.8723 | 0.880 | 0.7803 | 0.8138 | 0.813 | 0.809 | 0.8435 | 0.8507 |
| | 100 | 10 | 0.8855 | 0.9128 | 0.944 | 0.8262 | 0.8517 | 0.8808 | 0.8562 | 0.8827 | 0.9128 |
| | | 20 | 0.8741 | 0.8814 | 0.8883 | 0.8156 | 0.8223 | 0.8287 | 0.8453 | 0.8523 | 0.859 |
| g_M | 10 | 3 | 0.5695 | 0.584 | 0.604 | 0.5313 | 0.545 | 0.5883 | 0.5508 | 0.5648 | 0.5841 |
| | | 5 | 0.5582 | 0.5735 | 0.602 | 0.5208 | 0.535 | 0.5617 | 0.5332 | 0.5546 | 0.5821 |
| | 40 | 8 | 0.606 | 0.6146 | 0.6405 | 0.5654 | 0.5734 | 0.5976 | 0.5861 | 0.5943 | 0.6192 |
| | | 10 | 0.5874 | 0.6126 | 0.618 | 0.5480 | 0.5716 | 0.5710 | 0.5681 | 0.5924 | 0.5975 |
| | 100 | 10 | 0.622 | 0.6411 | 0.663 | 0.5803 | 0.5982 | 0.6186 | 0.6013 | 0.6200 | 0.6411 |
| | | 20 | 0.614 | 0.619 | 0.624 | 0.573 | 0.5775 | 0.582 | 0.5937 | 0.5986 | 0.6033 |
| g_{MK} | 10 | 3 | 0.774 | 0.7938 | 0.8208 | 0.7221 | 0.7406 | 0.80 | 0.7485 | 0.7676 | 0.7938 |
| | | 5 | 0.759 | 0.7794 | 0.8181 | 0.7078 | 0.7271 | 0.7633 | 0.7336 | 0.7537 | 0.7911 |
| | 40 | 8 | 0.8235 | 0.8352 | 0.8704 | 0.7684 | 0.7793 | 0.8121 | 0.7965 | 0.8077 | 0.8415 |
| | | 10 | 0.7983 | 0.833 | 0.84 | 0.7448 | 0.7768 | 0.7759 | 0.7720 | 0.8050 | 0.812 |
| | 100 | 10 | 0.8451 | 0.8713 | 0.901 | 0.7886 | 0.8129 | 0.8406 | 0.8172 | 0.8425 | 0.8713 |
| | | 20 | 0.8343 | 0.8413 | 0.848 | 0.7785 | 0.7849 | 0.7910 | 0.8068 | 0.8135 | 0.82 |
| g^* | 10 | 3 | 0.859 | 0.881 | 0.911 | 0.8014 | 0.8220 | 0.8873 | 0.8307 | 0.8519 | 0.881 |
| | | 5 | 0.842 | 0.865 | 0.908 | 0.7856 | 0.807 | 0.8472 | 0.8142 | 0.8365 | 0.878 |
| | 40 | 8 | 0.914 | 0.927 | 0.966 | 0.8528 | 0.8649 | 0.9013 | 0.8840 | 0.8964 | 0.934 |
| | | 10 | 0.886 | 0.924 | 0.932 | 0.8266 | 0.8621 | 0.8612 | 0.8568 | 0.8935 | 0.9012 |
| | 100 | 10 | 0.938 | 0.967 | 0.978 | 0.8752 | 0.9022 | 0.9330 | 0.9070 | 0.9351 | 0.967 |
| | | 20 | 0.926 | 0.9337 | 0.941 | 0.8640 | 0.8711 | 0.8779 | 0.8954 | 0.9029 | 0.9100 |

Table (1) : Empirical significant levels of \mathcal{G}^* , \mathcal{G}_{MH} , \mathcal{G}_{MK} , \mathcal{G}_{BP} , and \mathcal{G}_M statistics

| T | m | $\lambda = 0.5$ | | | | | | $\lambda = 1$ | | | $\lambda = 1.1$ | | |
|---------------------|--------------------|-----------------|-----------------|----------------|-----------------|-----------------|----------------|-----------------|-----------------|-----------------|-----------------|-----------------|----------------|
| | | $\alpha = 0.01$ | | | $\alpha = 0.05$ | | | $\alpha = 0.1$ | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.1$ |
| | | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.1$ | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.1$ | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.1$ | $\alpha = 0.01$ | $\alpha = 0.05$ | $\alpha = 0.1$ |
| الاحصاء الاختصار | \mathcal{G}_{BP} | 10 | 3 | 0.0068 | 0.0289 | 0.057 | 0.0055 | 0.0287 | 0.0601 | 0.00763 | 0.0285 | 0.0571 | |
| | | | 5 | 0.0066 | 0.0284 | 0.0552 | 0.0051 | 0.0294 | 0.058 | 0.00513 | 0.0297 | 0.0551 | |
| | | | 8 | 0.00689 | 0.0299 | 0.0604 | 0.0085 | 0.0282 | 0.0621 | 0.00815 | 0.0281 | 0.058 | |
| | | 40 | 10 | 0.00647 | 0.0283 | 0.0585 | 0.0078 | 0.0289 | 0.0599 | 0.0055 | 0.02923 | 0.0561 | |
| | | | 10 | 0.00668 | 0.0296 | 0.0614 | 0.0068 | 0.028 | 0.0632 | 0.0086 | 0.0298 | 0.06 | |
| | | 100 | 20 | 0.0061 | 0.028 | 0.059 | 0.0066 | 0.0286 | 0.061 | 0.0058 | 0.02877 | 0.0581 | |
| \mathcal{G}_{LB} | 10 | 3 | 0.01234 | 0.058 | 0.1093 | 0.0158 | 0.0594 | 0.1121 | 0.01302 | 0.06211 | 0.1068 | | |
| | | 5 | 0.01481 | 0.05881 | 0.1129 | 0.0188 | 0.0640 | 0.1162 | 0.0193 | 0.06474 | 0.1105 | | |
| | | 8 | 0.0121 | 0.05777 | 0.1076 | 0.0148 | 0.0615 | 0.1101 | 0.01233 | 0.06115 | 0.1030 | | |
| | 40 | 10 | 0.01452 | 0.05857 | 0.1111 | 0.0177 | 0.0629 | 0.1141 | 0.01831 | 0.0637 | 0.1066 | | |
| | | 10 | 0.01142 | 0.0572 | 0.1014 | 0.0125 | 0.0610 | 0.1065 | 0.01153 | 0.06019 | 0.1013 | | |
| | 100 | 20 | 0.0137 | 0.058 | 0.1048 | 0.0149 | 0.0624 | 0.1104 | 0.01713 | 0.06271 | 0.1047 | | |
| \mathcal{G}_{ML} | 10 | 3 | 0.0119 | 0.0523 | 0.1091 | 0.0152 | 0.0536 | 0.1119 | 0.01254 | 0.05322 | 0.1066 | | |
| | | 5 | 0.01427 | 0.05303 | 0.1127 | 0.0182 | 0.0548 | 0.1160 | 0.01859 | 0.05549 | 0.1103 | | |
| | | 8 | 0.01166 | 0.05209 | 0.1074 | 0.0143 | 0.0527 | 0.1099 | 0.01188 | 0.0524 | 0.1029 | | |
| | 40 | 10 | 0.014 | 0.05281 | 0.1109 | 0.0170 | 0.0539 | 0.1139 | 0.01764 | 0.0546 | 0.1064 | | |
| | | 10 | 0.011 | 0.05158 | 0.1012 | 0.0121 | 0.0523 | 0.1063 | 0.01111 | 0.05158 | 0.1011 | | |
| | 100 | 20 | 0.0132 | 0.0523 | 0.1046 | 0.0144 | 0.0535 | 0.1102 | 0.0165 | 0.05374 | 0.1045 | | |
| \mathcal{G}_M | 10 | 3 | 0.0054 | 0.021 | 0.051 | 0.0058 | 0.0215 | 0.0537 | 0.00675 | 0.0216 | 0.0510 | | |
| | | 5 | 0.0045 | 0.02071 | 0.0494 | 0.0049 | 0.021 | 0.0518 | 0.00455 | 0.02071 | 0.0493 | | |
| | | 8 | 0.00472 | 0.0212 | 0.0541 | 0.0069 | 0.0217 | 0.0555 | 0.00722 | 0.02192 | 0.0519 | | |
| | 40 | 10 | 0.00477 | 0.02092 | 0.0524 | 0.0058 | 0.0212 | 0.0536 | 0.00486 | 0.02104 | 0.0501 | | |
| | | 10 | 0.00584 | 0.0213 | 0.0549 | 0.0074 | 0.022 | 0.0566 | 0.00761 | 0.0223 | 0.0538 | | |
| | 100 | 20 | 0.00486 | 0.021 | 0.0532 | 0.0062 | 0.0215 | 0.0546 | 0.00513 | 0.02137 | 0.052 | | |

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- 3) The values of T are taken to be 10 (small sample size) , 40 (moderate sample size) and 100 (large sample size) .
- 4) All simulation experiments were based on $R=1000$ replications .
- 5) The a_i 's generated as zero mean , unit variance white noise .
- 6) The values of significant level α are taken to be 0.1 , 0.05 and 0.01 .
- 7) The values of m are taken to be $m=3,5$ for $(T=10)$, $m=8,10$ for $(T=40)$ and $m=10,20$ for $(T=100)$.

In order to obtain some information concerning the validity of the asymptotic performance of \mathcal{G}_{BP} , \mathcal{G}_{LB} , \mathcal{G}_{ML} , \mathcal{G}_M , \mathcal{G}_{MK} and \mathcal{G}^* test statistics , a Visual Basic program was written by the author to calculate empirical significance levels and empirical powers of the test statistics under consideration .

Our results are reported in table (1) and table (2) respectively .

Our main conclusions are :

- 1) As is it to be expected , as sample size increases , the performance of the different test statistics improve dramatically .
- 2) If the series obeys to the random walk process ($\lambda = 1$) , the performance of the different test statistics will be less than their performance for stationary and non stationary models .
- 3) The performance of the different test statistics for stationary models better than their performance for non stationary models .
- 4) The goodness of performance of the test statistics under consideration , are as follows , respectively , \mathcal{G}^* , \mathcal{G}_{ML} , \mathcal{G}_{LB} , \mathcal{G}_{MK} , \mathcal{G}_{BP} , and finally \mathcal{G}_M .

where $\hat{F}_a(w) = \frac{1}{\eta}(\text{number of } w_i \text{ less than or equal to } w)$ and $\eta = 2\pi / \varepsilon$ represent the number of points which will be taken , to calculate $\hat{F}_a(w)$, i.e. $i = 1, 2, \dots, \eta$ and ε an arbitrary number , like 0.01 .

Now, to test the hypothesis in (11) , we can use the kolmogorov - smirnov one sample test , with the following test statistic ,

$$D = \text{Max} \left| \hat{F}_a(w_i) - F_a(w_i) \right| , i = 1, 2, \dots, \eta \quad \text{--- (12)}$$

where the sampling distribution of D under H_0 is known [10] , and a lot of references give critical values from that sampling distribution .

Intuitively , There are some advantages for the above procedure :

- 1) It deal with the frequency domain , which provides an alternative way of viewing the process . For some applications , the frequency domain analysis may be more illuminating than the time domain analysis [3] .
- 2) Since the test based on non parametric statistic , then the advantages of non Parametric statistical tests will be risen .

III- An Empirical study

A monte Carlo study was conducted to generate sets of observations from the Markov model $y_t = \lambda y_{t-1} + a_t$, under the following assumptions:

- 1) The initial value y_0 equal to zero .
- 2) The values of Markov model parameter λ are taken to be 0.5 (to generate stationary process) , 1 (to generate random walk process , i.e. a process has a boundary value problem) and 1.1 (to generate non stationary process).

Nasir concluded that almost all time , the null hypothesis is accepted and that the statistics \mathcal{G}_{BP} , \mathcal{G}_{LB} , \mathcal{G}_M and \mathcal{G}_{MK} have nearly the same performances at large sample sizes .

II- Another point of view

Since a white noise process has a flat spectral density function $f_a(w)$ as in (7) , we can simply represent the problem under consideration by the hypothesis ,

$$\left. \begin{array}{l} H_0 : \hat{f}_a(w) = f_a(w) \\ \text{vs} \\ H_1 : \hat{f}_a(w) \neq f_a(w) \end{array} \right\} \quad \text{--- (9)}$$

where

$$\hat{f}_a(w) = \frac{1}{2\pi} \sum_{v=-M}^M \hat{r}_v k_M(v) \cos(vw) \quad , \quad -\pi \leq w \leq \pi \quad \text{--- (10)}$$

is a consistent estimator of $f_a(w)$, i.e. the frequencies obtained from the actual performance of an experiments .

where M is the truncation point parameter , $k_M(v)$ is the lag window and \hat{r}_v is the sample autocorrelation function , defined as in (2) .

Since , the hypothesis tested is how good the observed frequencies $\hat{f}_a(w_i)$ fit a given pattern $f_a(w_i) = 1/2\pi$, we can rewrite the hypothesis in (9) in terms of cumulative spectrum as follows :

$$\left. \begin{array}{l} H_0 : \hat{F}_a(w) = F_a(w) \\ \text{vs} \\ H_1 : \hat{F}_a(w) \neq F_a(w) \end{array} \right\} \quad \text{--- (11)}$$

are replaced by the sample autocorrelations of the squared data , \tilde{r}_k , giving ,

$$\mathcal{G}_{ML} = T(T+2) \sum_{k=1}^m (T-k)^{-1} \tilde{r}_k^2 \quad \text{--- -- (5)}$$

The hypothesis of *iid* data is then rejected at level α if the observed value of \mathcal{G}_{ML} is larger than the $1-\alpha$ quantile of the χ^2_{m-p-q} distribution .

Monti 1994 [7] proposed another portmanteau test , based on the partial autocorrelation function of residuals ,

$$\mathcal{G}_M = T(T+2) \sum_{k=1}^m (T-k)^{-1} \hat{\phi}_{kk} \quad \text{--- -- (6)}$$

The \mathcal{G}_M statistic is asymptotically distributed as χ^2_{m-p-q} also .

Since each frequency in the spectrum of white noise process contributes equally to the variance of the process , then the white noise process has a flat spectral density function

$$f_a(w) = 1/2\pi \quad , \quad -\pi \leq w \leq \pi \quad \text{--- -- (7)}$$

Mokkadem 1994 [9] derived another portmanteau test statistic based on the hypothesis $H_0: f_a(w) = c$ vs $H_1: f_a(w) \neq c$, where c is any constant . The formula of Mokkadem statistic is :

$$\begin{aligned} \mathcal{G}_{MK} &= Ln \left(\frac{\hat{R}_a}{2\pi} \right) - \frac{1}{2\pi} \int_{-\pi}^{\pi} Ln |\hat{f}_a(w)| dw \\ &\cong \sum_{k=1}^m \hat{r}_k^2 \quad \text{--- -- (8)} \end{aligned}$$

Al-Nasir 2000 [1] , generated sets of observations from the markov process for comparison among test statistics \mathcal{G}_{BP} , \mathcal{G}_{LB} , \mathcal{G}_M and \mathcal{G}_{MK} . Al-

$$\hat{r}_v = \frac{\sum_{t=v+1}^T \hat{a}_t \hat{a}_{t-v}}{\sum_{t=1}^T \hat{a}_t^2}, \quad k=1,2,\dots \quad \text{-----(2)}$$

Box and Pierce 1970 [2] show that , under the correct model specification

(null hypothesis) provided that m is moderately large , the statistic

$$\mathcal{G}_{BP} = T \sum_{k=1}^m \hat{r}_k^2 \quad \text{-----(3)}$$

is asymptotically distributed as χ^2 with $(m-q-p)$ degrees of freedom . Tests of model adequacy based on this statistic are generally called portmanteau tests .

It has been shown by David , Triggs and Newbold 1977 [5] that , for sample sizes commonly found in practice , the actual significance levels of \mathcal{G}_{BP} can be considered lower than those predicted by asymptotic theory . However , a simple modification , studied by Ljung and Box 1978 [6]

$$\mathcal{G}_{LB} = T(T+2) \sum_{k=1}^m (T-k)^{-1} \hat{r}_k^2 \quad \text{-----(4)}$$

appears to have a distribution very much closer to the asymptotic χ^2 with $(m-p-q)$ degrees of freedom .

Davis and Newbold 1979 [4] concentrated on the behavior of the modified statistic \mathcal{G}_{LB} , and in particular investigated the frequency with which it detects misspecification , relating this to the increase in forecast error variance resulting from use of the incorrect model .

Another portmanteau , formulated by Mcleod and Li 1983 [8] , can be used as a farther test for the *iid* hypothesis , since if the data are *iid* , then the squared data are also *iid* . It is based on the same statistic used for the Ljung and Box test , except that the sample autocorrelations of the data

On The Lack Of Fit In Time Series Models

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Summary

In this paper, we present another test for lack of fit in time series models . A simulation study was conducted to compare among model adequacy tests . Our conclusion is that the proposed statistic achieves a high level of success to detect time series model misspecification, at all situations considered .

I- Introduction

Consider a discrete time series $\{y_t\}$ generated by a stationary autoregressive-moving average process

$$y_t = \lambda_1 y_{t-1} + \dots + \lambda_p y_{t-p} + a_t - \beta_1 a_{t-1} - \dots - \beta_q a_{t-q} \quad \dots \dots (1)$$

and $\{a_t\}$ is a sequence of zero mean , finite variance , independent and identically distributed random deviates .

The y_t 's can in general represent the d-th difference or some other suitable transformation of a non stationary series $\{z_t\}$.

After a model of this form has been fitted to a series y_1, y_2, \dots, y_T , it is useful to study the adequacy of the fit by examining the residuals $\hat{a}_1, \hat{a}_2, \dots, \hat{a}_T$ and in particular , their autocorrelations