

The Determination of 3D Multiwavelet Transform

W. A. Mahmoud*

M. S. AbdulWahab**

H. N. AL-Taai**

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Abstract

The relatively new field of multiwavelets shows promise in removing some of the limitations of wavelets. Multiwavelets offer more design options and hence can combine all desirable transform features. In this paper several new algorithms for computing advance transforms are proposed. Firstly a fast procedure for computing of 1-D and 2-D multiwavelet transforms is introduced. Secondly, for the first time, a complete new procedure for computing of 3-D multiwavelet transforms is given. Thirdly, the inverse procedures of all the above transform for multi-dimensional cases are verified. In addition to the mathematical prove, all these new algorithms were verified also using illustrated example.

الخلاصة

يقدم متعدد الموجيات (multiwavelets) امكانية اداء فائق لتطبيقات معالجة الصور وذلك قياسا بالموجيات القياسية، ومع ذلك تبقى هناك مساحات لبحوث متعدد الموجيات التي تتطلب دراسات اخرى لغرض البلوغ الى تطبيقات افضل، ولعل من تلك المساحات البحثية محاولة ايجاد نظام حل مبسط الذي من شأنه تسهيل حساب معاملات متعدد الموجيات المنفصلة. لذا فان هذا البحث يقدم اولاً، طريقة سريعة في حساب تحويل متعدد الموجيات المنفصلة بالنسبة للاشارات ذات البعد الواحد والبعدين. ثانياً، ولأول مرة، يتم تقديم طريقة جديدة لحساب تحويل متعدد الموجيات المنفصلة بالنسبة للاشارات ثلاثية الابعاد. ثالثاً، الاجراءات المعكوسة (اعادة بناء) لجميع التحويلات اعلاه تم تحقيقها. بالاضافة الى برهناتها رياضياً، فان جميع هذه الخوارزميات الجديدة حققت باستخدام امثلة. تكمن اهمية الطرق المقترحة في تبسيطها عملية حساب معاملات متعدد الموجيات لعمليتي التحويل واعادة البناء وبلاضافة الى استرجاع الصورة المثالي بعد عملية اعادة البناء والذي يتم توضيحه من خلال الفحوصات على احدى الصور كمثال تطبيقي على الطرق.

Keywords

3-D Discrete Multiwavelet Transform (DMWT), 3-D Inverse Discrete Multiwavelet Transform (IDMWT), Oversampled Scheme of Preprocessing.

1-Introduction

The fundamental idea behind wavelets is to analyze the signal at different scales or resolutions, which is called multiresolution analysis. Wavelets are a class of functions used to localize a given signal in both space and scaling domains. A family of wavelets can be constructed from a mother wavelet. Compared to Windowed analysis, a mother wavelet is stretched or compressed to change the size of the

windows. The wavelet transform is suited for nonstationary signals, such as very brief signals and signals with interesting components at different scales.

For best performance in some applications, wavelet transform require filters that combine a number of desirable properties, such as orthogonality and symmetry. The relatively new field of multiwavelets shows promise in removing some of the

* Dept.of Electrical Eng., University of Baghdad, Baghdad-IRAQ.

** Dept.of Electrical Eng., University of Technology, Baghdad-IRAQ.

limitations of wavelets. Multiwavelets offer more design options and hence can combine all desirable transform features.

Over the past decade, the success of wavelets in solving many difficult problems has contributed to its unprecedented popularity among many research and development communities, ranging from mathematics and computer science to physics and engineering. Multiwavelets, as an extension to wavelets with only one basis, have also generated significant interest as they promise the potential to construct better multifilters with desirable properties and lower computation complexity. The challenge still remains as what constitutes good multiwavelets and how they can be constructed and applied easily.

Multiwavelets are new addition to the body of wavelet theory. The study of multiwavelets was initiated by Goodman, Lee and Tang in [1]. Then Goodman and Lee in [2] discovered the characterization of scaling functions wavelets. In [3], Jia constructed a class of continuous orthogonal double wavelets with symmetry, short support, and orthogonality. The special case of [3] with multiplicity 2 and support [0,2], was studied by Chui and Lian [4]. Generally, after the presentation of prefilter technique, multiwavelets with multiplicity 2 can be applied in image compression application successfully [5-8].

2-Preliminaries of Multiwavelets

The wavelet transform is a type of signal transform that is commonly used in image compression. A newer alternative to the wavelet transform is the multiwavelet transform. Multiwavelets are very similar to wavelets but have some important differences. In particular, whereas wavelets have an

associated scaling function $\phi(t)$ and wavelet function $\psi(t)$, multiwavelets have two or more scaling and wavelet functions. For notational convenience, the set of scaling functions can be written using the vector notation $\Phi(t) = [\phi_1(t) \ \phi_2(t) \ \dots \ \phi_r(t)]^T$, where $\Phi(t)$ is called the multiscaling function. Likewise, the multiwavelet function is defined from the set of wavelet functions as $\Psi(t) = [\psi_1(t) \ \psi_2(t) \ \dots \ \psi_r(t)]^T$. When $n = 1$, $\Psi(t)$ is called a scalar wavelet, or simply wavelet. While in principle n can be arbitrarily large, the multiwavelets studied to date are primarily for $n=2$. The multiwavelet two-scale equations resemble those for scalar wavelets [9]:

$$\Phi(t) = \sqrt{2} \sum_{k=-\infty}^{\infty} H_k \Phi(2t-k) \quad \dots (1)$$

$$\Psi(t) = \sqrt{2} \sum_{k=-\infty}^{\infty} G_k \Phi(2t-k) \quad \dots (2)$$

However, that H_k and G_k are *matrix* filters, i.e H_k and G_k are $n \times n$ matrices instead of scalars. The matrix elements in these filters provide more degrees of freedom than a traditional scalar wavelet. These extra degrees of freedom can be used to incorporate useful properties into the multiwavelet filters, such as orthogonality, symmetry, and high order of approximation. The key, then, is to figure out how to make the best use of these extra degrees of freedom. Multifilter construction methods are already being developed to exploit them. However, the multi-channel nature of multiwavelets also means that the subband structure resulting from passing a signal through a multifilter bank is different. Sufficiently different, in fact, so that established quantization methods do not perform as

well with multiwavelets as they do with wavelets [10]. A very important multiwavelet filter is the GHM filter proposed by Geronimo, Hardian, and Massopust [11]. The GHM basis

offers a combination of orthogonality,

$$H_0 = \begin{bmatrix} 3 & 4 \\ 5\sqrt{2} & 5 \\ -1 & 3 \\ -20 & -10\sqrt{2} \end{bmatrix}, H_1 = \begin{bmatrix} 3 & 0 \\ 5\sqrt{2} & 0 \\ 9 & 1 \\ 20 & \sqrt{2} \end{bmatrix}, H_2 = \begin{bmatrix} 0 & 0 \\ 9 & -\frac{3}{10\sqrt{2}} \end{bmatrix}, H_3 = \begin{bmatrix} 0 & 0 \\ -\frac{1}{20} & 0 \end{bmatrix} \dots (3)$$

also, G_k for GHM system are four wavelet matrices $G_0, G_1, G_2,$ and G_3 :

$$G_0 = \begin{bmatrix} -\frac{1}{20} & -\frac{3}{10\sqrt{2}} \\ 1 & 3 \\ 10\sqrt{2} & 10 \end{bmatrix}, G_1 = \begin{bmatrix} 9 & -\frac{1}{\sqrt{2}} \\ 20 & -\frac{1}{\sqrt{2}} \\ -9 & 0 \\ -10\sqrt{2} & 0 \end{bmatrix}, G_2 = \begin{bmatrix} 9 & -\frac{3}{10\sqrt{2}} \\ 20 & -\frac{3}{10\sqrt{2}} \\ 9 & -\frac{3}{10\sqrt{2}} \\ 10\sqrt{2} & -\frac{3}{10} \end{bmatrix}, G_3 = \begin{bmatrix} -\frac{1}{20} & 0 \\ 20 & 0 \\ -1 & 0 \\ -10\sqrt{2} & 0 \end{bmatrix} \dots (4)$$

The low pass filter H_k and high pass filter G_k consist of coefficients corresponding to the dilation equation (1) and wavelet equation (2). However in the multiwavelet setting these coefficients are n by n matrices, and during the convolution step they must multiply vectors (instead of scalars). This means that multifilter banks need n input rows. The most obvious way to get input rows from a given signal is to repeat the signal. Two identical rows go into the multifilter bank. This procedure is called ‘‘Repeated row’’ which introduces oversampling of the data by a factor of two.

3-Discrete Multiwavelet Transform Computation for 1-D and 2-D Signals

By using an over-sampled scheme of preprocessing (repeated row), the discrete multiwavelet transform (DMWT) matrix is doubled in dimension compared with that of the input, which should be a square matrix $N \times N$ where N must be power of two. Transformation matrix dimension equal input signal dimension after preprocessing. To compute a single-level 1-D discrete

multiwavelet transform, the next steps should be followed:

- 1. Checking input dimensions: Input vector should be of length N , where N must be power of two.
- 2. Constructing a transformation matrix: using GHM low and high pass filters matrices given in (3) and (4), the transformation matrix can be written as follows:

$$W = \begin{bmatrix} H_0 & H_1 & H_2 & H_3 & 0 & 0 & \dots \\ G_0 & G_1 & G_2 & G_3 & 0 & 0 & \dots \\ 0 & 0 & H_0 & H_1 & H_2 & H_3 & \dots \\ 0 & 0 & G_0 & G_1 & G_2 & G_3 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \dots \end{bmatrix} \dots (5)$$

After substituting GHM matrix filter coefficients values as given by (5), a $2N \times 2N$ transformation matrix results.

- 3. Preprocessing the input signal by repeating the input stream with the same stream multiplied by a constant α . For GHM system functions $\alpha = 1/\sqrt{2}$.
- 4. Transformation of input vector which can be done as follows:
 - a. Apply matrix multiplication to the $2N \times 2N$ constructed

transformation matrix by the $2N$ preprocessing input vector.

b. Permute the resulting $2N \times 1$ matrix rows by arranging the row pairs 1,2 and 5,6 $2N-3,2N-2$ after each other at the upper half of the resulting matrix rows, then the row pairs 3,4 and 7,8,...., $2N-1,2N$ below them at the next half.

Finally, a $2N \times 1$ DMWT matrix results from the $N \times 1$ original matrix using repeated row.

To compute a single-level 2-D discrete multiwavelet transform, the next steps should be followed [13]:

1. Checking input dimensions: Input matrix should be a square matrix $N \times N$ matrix, where N must be power of two.

2. Constructing a transformation matrix W using GHM low and high pass filters matrices given in (3) and (4).

3. Preprocessing rows: doubles the number of the input matrix rows. So if the 2-D input is $N \times N$ matrix elements, after row preprocessing the result is $2N \times N$ matrix. The odd rows of the resultant matrix are the same original matrix rows values. While the even rows are the original signal rows values multiplied by α . For GHM system functions $\alpha = 1/\sqrt{2}$.

4. Transformation of input rows: can be done as follows:

a. Apply matrix multiplication to the $2N \times 2N$ constructed transformation matrix by the $2N \times N$ preprocessing input matrix.

b. Permute the resulting $2N \times N$ matrix rows by arranging the row pairs 1,2 and 5,6 $2N-3,2N-2$ after each other at the upper half of the resulting matrix rows, then the row pairs 3,4 and 7,8,...., $2N-1,2N$ below them at the next half.

5. Preprocess columns: to repeat the same procedure used in preprocessing rows

a. Transpose the row transformed $2N \times N$ matrix resulting from step 4.

b. Repeat step 3 to the $N \times 2N$ matrix (transpose of the row transformed $2N \times N$ matrix) which results in $2N \times 2N$ column preprocessed matrix.

6. Transformation of input columns: is applied next to the $2N \times 2N$ column preprocessed matrix as follows:

a. Apply matrix multiplication to the $2N \times 2N$ constructed transformation matrix by the $2N \times 2N$ column preprocessed matrix.

b. Permute the resulting $2N \times 2N$ matrix rows.

7. To get the final transformed matrix:

a. Transpose the resulting matrix from column transformation step.

b. Apply coefficients permutation to the resulting transpose matrix. Coefficient permutation is applied to each of the basic four subbands of the resulting transpose matrix so that each subband permute rows then permute columns.

Finally, a $2N \times 2N$ DMWT matrix results from the $N \times N$ original matrix using repeated row.

A general example for computing 1-D and 2-D DMWT using an over sampled scheme of preprocessing involves the following steps:

1. Let 8-component vector be the input 1-D signal, $X = [x_0 \ x_1 \ x_2 \ x_3 \ x_4 \ x_5 \ x_6 \ x_7]$

2. For an 8×1 input 1-D signal, X , construct a 8×8 transformation matrix, W , using GHM low and high pass filters,

$$W = \begin{bmatrix} H_0 & H_1 & H_2 & H_3 & 0 & 0 & 0 & 0 \\ G_0 & G_1 & G_2 & G_3 & 0 & 0 & 0 & 0 \\ 0 & 0 & H_0 & H_1 & H_2 & H_3 & 0 & 0 \\ 0 & 0 & G_0 & G_1 & G_2 & G_3 & 0 & 0 \\ 0 & 0 & 0 & 0 & H_0 & H_1 & H_2 & H_3 \\ 0 & 0 & 0 & 0 & G_0 & G_1 & G_2 & G_3 \\ H_2 & H_3 & 0 & 0 & 0 & 0 & H_0 & H_1 \\ G_2 & G_3 & 0 & 0 & 0 & 0 & G_0 & G_1 \end{bmatrix}$$

As GHM filters, H 's and G 's are 2×2 matrices, the transformation matrix, W , dimension after substituting filters coefficients value will be 16×16 matrix with same dimension of the input matrix

after repeated-row preprocessing.

3. Apply repeated row preprocessing to the input X , which results in P matrix.

$$P = [x_0 \ \alpha x_0 \ x_1 \ \alpha x_1 \ x_2 \ \alpha x_2 \ x_3 \ \alpha x_3 \ x_4 \ \alpha x_4 \ x_5 \ \alpha x_5 \ x_6 \ \alpha x_6 \ x_7 \ \alpha x_7]$$

4. Transformation of input vector which can be done as follows:

a. Let $[Z] = [W] \times [P]^T$

$$Z = [z_0 \ z_1 \ z_2 \ z_3 \ z_4 \ z_5 \ z_6 \ z_7 \ z_8 \ z_9 \ z_{10} \ z_{11} \ z_{12} \ z_{13} \ z_{14} \ z_{15}]$$

b. Permute Z which results in A matrix,

$$A = [z_0 \ z_1 \ z_4 \ z_5 \ z_8 \ z_9 \ z_{12} \ z_{13} \ z_2 \ z_3 \ z_6 \ z_7 \ z_{10} \ z_{11} \ z_{14} \ z_{15}]$$

numerical example:

$$X = \begin{bmatrix} 5 \\ 16 \\ 3 \\ 7 \end{bmatrix} \Rightarrow P = \begin{bmatrix} 5 \\ 3.5355 \\ 16 \\ 11.3137 \\ 3 \\ 2.1213 \\ 7 \\ 4.9497 \end{bmatrix} \Rightarrow Z = W.P^t = \begin{bmatrix} 11.738 \\ 14.75 \\ -1.25 \\ -7.9903 \\ 5.9397 \\ 6.75 \\ -0.25 \\ -2.6163 \end{bmatrix} \Rightarrow A = \begin{bmatrix} 11.738 \\ 14.75 \\ 5.9397 \\ 6.75 \\ -1.25 \\ -7.9903 \\ -0.25 \\ -2.6163 \end{bmatrix}$$

For a 2-D signal the following steps will be involved:

$$W = \begin{bmatrix} H_0 & H_1 & H_2 & H_3 \\ G_0 & G_1 & G_2 & G_3 \\ H_2 & H_3 & H_0 & H_1 \\ G_2 & G_3 & G_0 & G_1 \end{bmatrix}_{2N \times 2N}$$

1. Let 4×4 matrix be the input 2-D signal,

$$X = \begin{bmatrix} x_{0,0} & x_{0,1} & x_{0,2} & x_{0,3} \\ x_{1,0} & x_{1,1} & x_{1,2} & x_{1,3} \\ x_{2,0} & x_{2,1} & x_{2,2} & x_{2,3} \\ x_{3,0} & x_{3,1} & x_{3,2} & x_{3,3} \end{bmatrix}_{N \times N}$$

2. For an 4×4 matrix input 2-D signal, X , construct a 4×4 transformation matrix, W , using GHM low and high pass filters,

As GHM filters, H 's and G 's are 2×2 matrices, the transformation matrix, W , dimension after substituting filters coefficients value will be 8×8 matrix with same dimension of the input matrix after repeated-row preprocessing.

3. Apply row preprocessing to the input matrix X , using repeated row preprocessing which results in PR matrix.

$$X = \begin{bmatrix} x_{0,0} & x_{0,1} & x_{0,2} & x_{0,3} \\ x_{1,0} & x_{1,1} & x_{1,2} & x_{1,3} \\ x_{2,0} & x_{2,1} & x_{2,2} & x_{2,3} \\ x_{3,0} & x_{3,1} & x_{3,2} & x_{3,3} \end{bmatrix}_{N \times N} \Rightarrow PR = \begin{bmatrix} x_{0,0} & x_{0,1} & x_{0,2} & x_{0,3} \\ \alpha x_{0,0} & \alpha x_{0,1} & \alpha x_{0,2} & \alpha x_{0,3} \\ x_{1,0} & x_{1,1} & x_{1,2} & x_{1,3} \\ \alpha x_{1,0} & \alpha x_{1,1} & \alpha x_{1,2} & \alpha x_{1,3} \\ x_{2,0} & x_{2,1} & x_{2,2} & x_{2,3} \\ \alpha x_{2,0} & \alpha x_{2,1} & \alpha x_{2,2} & \alpha x_{2,3} \\ x_{3,0} & x_{3,1} & x_{3,2} & x_{3,3} \\ \alpha x_{3,0} & \alpha x_{3,1} & \alpha x_{3,2} & \alpha x_{3,3} \end{bmatrix}_{2N \times N}$$

4. Apply row transformation
 a. Let $[Z] = [W] \times [PR]$
 b. Permute Z which results in P matrix,

$$Z = \begin{bmatrix} z_{0,0} & z_{0,1} & z_{0,2} & z_{0,3} \\ z_{1,0} & z_{1,1} & z_{1,2} & z_{1,3} \\ z_{2,0} & z_{2,1} & z_{2,2} & z_{2,3} \\ z_{3,0} & z_{3,1} & z_{3,2} & z_{3,3} \\ z_{4,0} & z_{4,1} & z_{4,2} & z_{4,3} \\ z_{5,0} & z_{5,1} & z_{5,2} & z_{5,3} \\ z_{6,0} & z_{6,1} & z_{6,2} & z_{6,3} \\ z_{7,0} & z_{7,1} & z_{7,2} & z_{7,3} \end{bmatrix}_{2N \times N} \Rightarrow P = \begin{bmatrix} z_{0,0} & z_{0,1} & z_{0,2} & z_{0,3} \\ z_{1,0} & z_{1,1} & z_{1,2} & z_{1,3} \\ z_{4,0} & z_{4,1} & z_{4,2} & z_{4,3} \\ z_{5,0} & z_{5,1} & z_{5,2} & z_{5,3} \\ z_{2,0} & z_{2,1} & z_{2,2} & z_{2,3} \\ z_{3,0} & z_{3,1} & z_{3,2} & z_{3,3} \\ z_{6,0} & z_{6,1} & z_{6,2} & z_{6,3} \\ z_{7,0} & z_{7,1} & z_{7,2} & z_{7,3} \end{bmatrix}_{2N \times N}$$

5. Apply columns preprocessing
 a. Transpose $[P]$ matrix,

$$[P]^t = \begin{bmatrix} z_{0,0} & z_{0,1} & z_{0,2} & z_{0,3} & z_{4,0} & z_{5,0} & z_{2,0} & z_{3,0} \\ z_{1,0} & z_{1,1} & z_{1,2} & z_{1,3} & z_{4,1} & z_{5,1} & z_{2,1} & z_{3,1} \\ z_{2,0} & z_{2,1} & z_{2,2} & z_{2,3} & z_{4,2} & z_{5,2} & z_{2,2} & z_{3,2} \\ z_{3,0} & z_{3,1} & z_{3,2} & z_{3,3} & z_{4,3} & z_{5,3} & z_{2,3} & z_{3,3} \end{bmatrix}_{N \times 2N}$$

- b. Preprocess $[P]^t$ which results in $2N \times 2N$ column preprocessed matrix $[PC]$.

$$PC = \begin{bmatrix} z_{0,0} & z_{1,0} & z_{2,0} & z_{3,0} & z_{4,0} & z_{5,0} & z_{6,0} & z_{7,0} \\ \alpha z_{0,0} & \alpha z_{1,0} & \alpha z_{2,0} & \alpha z_{3,0} & \alpha z_{4,0} & \alpha z_{5,0} & \alpha z_{6,0} & \alpha z_{7,0} \\ z_{0,1} & z_{1,1} & z_{2,1} & z_{3,1} & z_{4,1} & z_{5,1} & z_{6,1} & z_{7,1} \\ \alpha z_{0,1} & \alpha z_{1,1} & \alpha z_{2,1} & \alpha z_{3,1} & \alpha z_{4,1} & \alpha z_{5,1} & \alpha z_{6,1} & \alpha z_{7,1} \\ z_{0,2} & z_{1,2} & z_{2,2} & z_{3,2} & z_{4,2} & z_{5,2} & z_{6,2} & z_{7,2} \\ \alpha z_{0,2} & \alpha z_{1,2} & \alpha z_{2,2} & \alpha z_{3,2} & \alpha z_{4,2} & \alpha z_{5,2} & \alpha z_{6,2} & \alpha z_{7,2} \\ z_{0,3} & z_{1,3} & z_{2,3} & z_{3,3} & z_{4,3} & z_{5,3} & z_{6,3} & z_{7,3} \\ \alpha z_{0,3} & \alpha z_{1,3} & \alpha z_{2,3} & \alpha z_{3,3} & \alpha z_{4,3} & \alpha z_{5,3} & \alpha z_{6,3} & \alpha z_{7,3} \end{bmatrix}_{2N \times 2N}$$

6. Transformation of input columns

a. Let $[B]=[W] \times [PR]$

$$B = \begin{bmatrix} b_{0,0} & b_{0,1} & b_{0,2} & b_{0,3} & b_{0,4} & b_{0,5} & b_{0,6} & b_{0,7} \\ b_{1,0} & b_{1,1} & b_{1,2} & b_{1,3} & b_{1,4} & b_{1,5} & b_{1,6} & b_{1,7} \\ b_{2,0} & b_{2,1} & b_{2,2} & b_{2,3} & b_{2,4} & b_{2,5} & b_{2,6} & b_{2,7} \\ b_{3,0} & b_{3,1} & b_{3,2} & b_{3,3} & b_{3,4} & b_{3,5} & b_{3,6} & b_{3,7} \\ b_{4,0} & b_{4,1} & b_{4,2} & b_{4,3} & b_{4,4} & b_{4,5} & b_{4,6} & b_{4,7} \\ b_{5,0} & b_{5,1} & b_{5,2} & b_{5,3} & b_{5,4} & b_{5,5} & b_{5,6} & b_{5,7} \\ b_{6,0} & b_{6,1} & b_{6,2} & b_{6,3} & b_{6,4} & b_{6,5} & b_{6,6} & b_{6,7} \\ b_{7,0} & b_{7,1} & b_{7,2} & b_{7,3} & b_{7,4} & b_{7,5} & b_{7,6} & b_{7,7} \end{bmatrix} \Rightarrow BB = \begin{bmatrix} b_{0,0} & b_{0,1} & b_{0,2} & b_{0,3} & b_{0,4} & b_{0,5} & b_{0,6} & b_{0,7} \\ b_{1,0} & b_{1,1} & b_{1,2} & b_{1,3} & b_{1,4} & b_{1,5} & b_{1,6} & b_{1,7} \\ b_{4,0} & b_{4,1} & b_{4,2} & b_{4,3} & b_{4,4} & b_{4,5} & b_{4,6} & b_{4,7} \\ b_{5,0} & b_{5,1} & b_{5,2} & b_{5,3} & b_{5,4} & b_{5,5} & b_{5,6} & b_{5,7} \\ b_{2,0} & b_{2,1} & b_{2,2} & b_{2,3} & b_{2,4} & b_{2,5} & b_{2,6} & b_{2,7} \\ b_{3,0} & b_{3,1} & b_{3,2} & b_{3,3} & b_{3,4} & b_{3,5} & b_{3,6} & b_{3,7} \\ b_{6,0} & b_{6,1} & b_{6,2} & b_{6,3} & b_{6,4} & b_{6,5} & b_{6,6} & b_{6,7} \\ b_{7,0} & b_{7,1} & b_{7,2} & b_{7,3} & b_{7,4} & b_{7,5} & b_{7,6} & b_{7,7} \end{bmatrix}$$

b. Permute the resulting $2N \times 2N$ matrix to get $[BB]$ matrix.

7. To get the final transformed matrix:

a. Transpose $[BB]$ to get $[Y]$.

$$Y = \begin{bmatrix} y_{0,0} & y_{0,1} & y_{0,2} & y_{0,3} & \vdots & y_{0,4} & y_{0,5} & y_{0,6} & y_{0,7} \\ y_{1,0} & y_{1,1} & y_{1,2} & y_{1,3} & \vdots & y_{1,4} & y_{1,5} & y_{1,6} & y_{1,7} \\ y_{2,0} & y_{2,1} & y_{2,2} & y_{2,3} & \vdots & y_{2,4} & y_{2,5} & y_{2,6} & y_{2,7} \\ y_{3,0} & y_{3,1} & y_{3,2} & y_{3,3} & \vdots & y_{3,4} & y_{3,5} & y_{3,6} & y_{3,7} \\ \dots & \dots & \dots & \dots & \vdots & \dots & \dots & \dots & \dots \\ y_{4,0} & y_{4,1} & y_{4,2} & y_{4,3} & \vdots & y_{4,4} & y_{4,5} & y_{4,6} & y_{4,7} \\ y_{5,0} & y_{5,1} & y_{5,2} & y_{5,3} & \vdots & y_{5,4} & y_{5,5} & y_{5,6} & y_{5,7} \\ y_{6,0} & y_{6,1} & y_{6,2} & y_{6,3} & \vdots & y_{6,4} & y_{6,5} & y_{6,6} & y_{6,7} \\ y_{7,0} & y_{7,1} & y_{7,2} & y_{7,3} & \vdots & y_{7,4} & y_{7,5} & y_{7,6} & y_{7,7} \end{bmatrix} \Rightarrow YY = \begin{bmatrix} y_{0,0} & y_{0,2} & y_{0,1} & y_{0,3} & \vdots & y_{0,4} & y_{0,6} & y_{0,5} & y_{0,7} \\ y_{2,0} & y_{2,2} & y_{2,1} & y_{2,3} & \vdots & y_{2,4} & y_{2,6} & y_{2,5} & y_{2,7} \\ y_{1,0} & y_{1,2} & y_{1,1} & y_{1,3} & \vdots & y_{1,4} & y_{1,6} & y_{1,5} & y_{1,7} \\ y_{3,0} & y_{3,2} & y_{3,1} & y_{3,3} & \vdots & y_{3,4} & y_{3,6} & y_{3,5} & y_{3,7} \\ \dots & \dots & \dots & \dots & \vdots & \dots & \dots & \dots & \dots \\ y_{4,0} & y_{4,2} & y_{4,1} & y_{4,3} & \vdots & y_{4,4} & y_{4,6} & y_{4,5} & y_{4,7} \\ y_{6,0} & y_{6,2} & y_{6,1} & y_{6,3} & \vdots & y_{6,4} & y_{6,6} & y_{6,5} & y_{6,7} \\ y_{5,0} & y_{5,2} & y_{5,1} & y_{5,3} & \vdots & y_{5,4} & y_{5,6} & y_{5,5} & y_{5,7} \\ y_{7,0} & y_{7,2} & y_{7,1} & y_{7,3} & \vdots & y_{7,4} & y_{7,6} & y_{7,5} & y_{7,7} \end{bmatrix}$$

b. Apply coefficients permutation to the $[Y]$ matrix to get $[YY]$ matrix.

So, $[Y]$ is the final single-level 2-D DMWT matrix.

Numerical example:

$$X = \begin{bmatrix} 16 & 2 & 3 & 13 \\ 5 & 11 & 10 & 8 \\ 9 & 7 & 6 & 12 \\ 4 & 14 & 15 & 1 \end{bmatrix} \longrightarrow PR = \begin{bmatrix} 16 & 2 & 3 & 13 \\ 11.3137 & 1.414 & 2.1213 & 9.1924 \\ 5 & 11 & 10 & 8 \\ 3.5355 & 7.778 & 7.071 & 5.6569 \\ 9 & 7 & 6 & 12 \\ 6.364 & 4.9497 & 4.2426 & 8.4853 \\ 4 & 14 & 15 & 1 \\ 2.8284 & 9.8995 & 10.6066 & 0.7071 \end{bmatrix}$$

$$Z = \begin{bmatrix} 17.9605 & 6.6468 & 7.2125 & 16.2635 \\ 4.0500 & 11.4500 & 9.9500 & 8.5500 \\ -0.9500 & 0.4500 & -0.0500 & 0.5500 \\ 4.8790 & -4.4548 & -4.0305 & 3.6062 \\ 10.6066 & 12.8693 & 12.3037 & 12.3037 \\ 6.5500 & 11.9500 & 13.4500 & 2.0500 \\ 2.5500 & -2.0500 & -1.5500 & 1.0500 \\ 6.4347 & -6.8589 & -7.2832 & 7.7075 \end{bmatrix} \Rightarrow P = \begin{bmatrix} 17.9605 & 6.6468 & 7.2125 & 16.2635 \\ 4.0500 & 11.4500 & 9.9500 & 8.5500 \\ 10.6066 & 12.8693 & 12.3037 & 12.3037 \\ 6.5500 & 11.9500 & 13.4500 & 2.0500 \\ -0.9500 & 0.4500 & -0.0500 & 0.5500 \\ -0.9500 & -4.4548 & -4.0305 & 3.6062 \\ 2.5500 & -2.0500 & -1.5500 & 1.0500 \\ 6.4347 & -6.8589 & -7.2832 & 7.7075 \end{bmatrix}$$

$$\begin{aligned}
 [P]^T &= \begin{bmatrix} 17.9605 & 4.0500 & 10.6066 & 6.5500 & -0.9500 & 4.8790 & 2.5500 & 6.4347 \\ 6.6468 & 11.4500 & 12.8693 & 11.9500 & 0.4500 & -4.4548 & -2.0500 & -6.8589 \\ 7.2125 & 9.9500 & 12.3037 & 13.4500 & -0.0500 & -4.0305 & -1.5500 & -7.2832 \\ 16.2635 & 8.5500 & 12.3037 & 2.0500 & 0.5500 & 3.6062 & 1.0500 & 7.7075 \end{bmatrix} \\
 PC &= \begin{bmatrix} 17.9605 & 4.0500 & 10.6066 & 6.5500 & -0.9500 & 4.8790 & 2.5500 & 6.4347 \\ 12.7000 & 2.8638 & 7.5000 & 4.6315 & -0.6718 & 3.4500 & 1.8031 & 4.5500 \\ 6.6468 & 11.4500 & 12.8693 & 11.9500 & 0.4500 & -4.4548 & -2.0500 & -6.8589 \\ 4.7000 & 8.0964 & 9.1000 & 8.4499 & 0.3182 & -3.1500 & -1.4496 & -4.8500 \\ 7.2125 & 9.9500 & 12.3037 & 13.4500 & -0.0500 & -4.0305 & -1.5500 & -7.2832 \\ 5.1000 & 7.0357 & 8.7000 & 9.5106 & -0.0354 & -2.8500 & -1.0960 & -5.1500 \\ 16.2635 & 8.5500 & 12.3037 & 2.0500 & 0.5500 & 3.6062 & 1.0500 & 7.7075 \\ 11.5000 & 6.0458 & 8.7000 & 1.4496 & 0.3889 & 2.5500 & 0.7425 & 5.4500 \end{bmatrix} \\
 B &= \begin{bmatrix} 20.6000 & 8.8671 & 15.9600 & 11.5541 & -0.7495 & 2.9400 & 1.6546 & 3.4600 \\ 4.0729 & 12.6250 & 13.1805 & 13.9750 & 0.5750 & -6.5973 & -2.9750 & -10.3733 \\ -2.5739 & 1.1750 & 0.3111 & 2.0250 & 0.1250 & -2.1425 & -0.9250 & -3.5143 \\ 2.7600 & -2.5244 & -0.8400 & -0.1909 & -0.6152 & 2.2500 & 1.2940 & 2.5500 \\ 14.0400 & 13.4775 & 17.4000 & 14.1846 & 0.1838 & -2.4600 & -1.0889 & -3.9400 \\ 19.0636 & 6.7750 & 11.7663 & 0.6250 & 0.2250 & 5.9185 & 2.1750 & 11.0521 \\ 2.8001 & -1.7750 & -0.5374 & -1.4250 & -0.3250 & 2.3122 & 1.1250 & 3.3446 \\ -1.1600 & -1.7183 & -0.7600 & 4.4336 & -0.7990 & -1.0500 & 0.1202 & -3.7500 \end{bmatrix} \\
 BB &= \begin{bmatrix} 20.6000 & 8.8671 & 15.9600 & 11.5541 & -0.7495 & 2.9400 & 1.6546 & 3.4600 \\ 4.0729 & 12.6250 & 13.1805 & 13.9750 & 0.5750 & -6.5973 & -2.9750 & -10.3733 \\ 14.0400 & 13.4775 & 17.4000 & 14.1846 & 0.1838 & -2.4600 & -1.0889 & -3.9400 \\ 19.0636 & 6.7750 & 11.7663 & 0.6250 & 0.2250 & 5.9185 & 2.1750 & 11.0521 \\ -2.5739 & 1.1750 & 0.3111 & 2.0250 & 0.1250 & -2.1425 & -0.9250 & -3.5143 \\ 2.7600 & -2.5244 & -0.8400 & -0.1909 & -0.6152 & 2.2500 & 1.2940 & 2.5500 \\ 2.8001 & -1.7750 & -0.5374 & -1.4250 & -0.3250 & 2.3122 & 1.1250 & 3.3446 \\ -1.1600 & -1.7183 & -0.7600 & 4.4336 & -0.7990 & -1.0500 & 0.1202 & -3.7500 \end{bmatrix} \\
 Y &= \begin{bmatrix} 20.6000 & 4.0729 & 14.0400 & 19.0636 & -2.5739 & 2.7600 & 2.8001 & -1.1600 \\ 8.8671 & 12.6250 & 13.4775 & 6.7750 & 1.1750 & -2.5244 & -1.7750 & -1.7183 \\ 15.9600 & 13.1805 & 17.4000 & 11.7663 & 0.3111 & -0.8400 & -0.5374 & -0.7600 \\ 11.5541 & 13.9750 & 14.1846 & 0.6250 & 2.0250 & -0.1909 & -1.4250 & 4.4336 \\ -0.7495 & 0.5750 & 0.1838 & 0.2250 & 0.1250 & -0.6152 & -0.3250 & -0.7990 \\ 2.9400 & -6.5973 & -2.4600 & 5.9185 & -2.1425 & 2.2500 & 2.3122 & -1.0500 \\ 1.6546 & -2.9750 & -1.0889 & 2.1750 & -0.9250 & 1.2940 & 1.1250 & 0.1202 \\ 3.4600 & -10.3733 & -3.9400 & 11.0521 & -3.5143 & 2.5500 & 3.3446 & -3.7500 \end{bmatrix} \\
 YY &= \begin{bmatrix} 20.6000 & 14.0400 & 4.0729 & 19.0636 & -2.5739 & 2.8001 & 2.7600 & -1.1600 \\ 15.9600 & 17.4000 & 13.1805 & 11.7663 & 0.3111 & -0.5374 & -0.8400 & -0.7600 \\ 8.8671 & 13.4775 & 12.6250 & 6.7750 & 1.1750 & -1.7750 & -2.5244 & -1.7183 \\ 11.5541 & 14.1846 & 13.9750 & 0.6250 & 2.0250 & -1.4250 & -0.1909 & 4.4336 \\ -0.7495 & 0.1838 & 0.5750 & 0.2250 & 0.1250 & -0.3250 & -0.6152 & -0.7990 \\ 1.6546 & -1.0889 & -2.9750 & 2.1750 & -0.9250 & 1.1250 & 1.2940 & 0.1202 \\ 2.9400 & -2.4600 & -6.5973 & 5.9185 & -2.1425 & 2.3122 & 2.2500 & -1.0500 \\ 3.4600 & -3.9400 & -10.3733 & 11.0521 & -3.5143 & 3.3446 & 2.5500 & -3.7500 \end{bmatrix}
 \end{aligned}$$

A general computer program computing a single-level DMWT using an over-sampled scheme of preprocessing (repeated row preprocessing) is written using MATLAB v.6.5 for a general NxN 2-D

signal (or image). As shown in Fig.(1-a), the original “Lena” image dimensions is 512x512 (NxN). After a single-level of multiwavelets decomposition using an over-sampled scheme of preprocessing, image dimensions will be a matrix of

1024x1024 (2Nx2N) as shown in Fig. (1-b).The upper-left most, L1L1, subband of 256x256 dimension, is zoomed in as in Fig. (1-c).

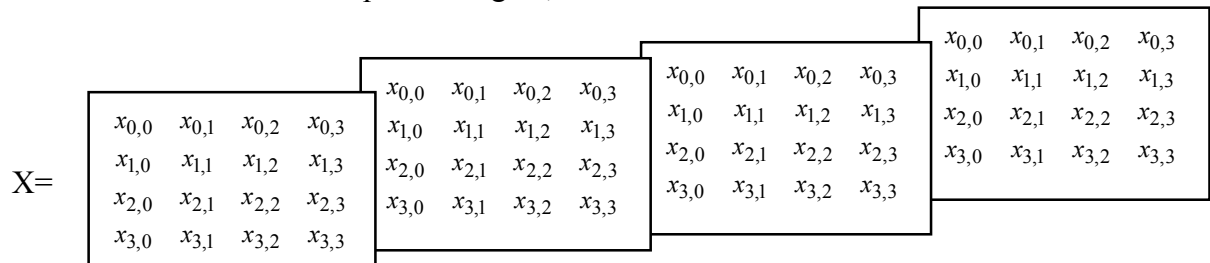
4- 3-D Discrete Multiwavelet Transformation Algorithm

This transformation is a useful one that changes information from the spatial domain into a local frequency domain. In the discrete case, the integrals can be reduced to simple arithmetic operations. This applies to a one-dimensional signal as well as to the 2-D, 3-D, or higher-dimensional case. This simple 1-D scheme can be lifted to higher dimensional cases. For a 2-D multiwavelet transformation, the algorithm is applied in *x*-direction first, and then in *y*-direction. Similarly, in 3-D multiwavelet transformation the structures are defined in 3-D and the transformation algorithm is applied in *x*-, *y*- and *z*-direction successively. One *cycle* for an *n*-dimensional data set is defined as the completion of the algorithm for all *n* directions.

To apply this hierarchical scheme to volume data sets (Fig 2-a), a 3-D multiwavelet transformation must be implemented. Therefore, the 2-D scheme

as described in the example given above is extended into the *z*-direction. The size of the array must be a power of two in each dimension. Unused areas can be filled with zeros. If we apply this algorithm to data set (*ctbrain.vols*) shown in Fig. (3) [14], which consists of 512 x 512 x 231 elements, we need to scale the size of the array to the closest powers of two, i.e., 512 x 512 x 256. The algorithm is initially run in *x*-direction, row by row for all 231 slices. The algorithm splits the volume into two halves, the left half representing the low-frequency coefficients while the right half represents the detail coefficients, as shown in Fig. (2-b). In the second stage of the algorithm, the entire volume is then again transformed in *y*-direction splitting the volume into four quadrants as shown in Fig. (2-c). For the final run, the volume is transformed in *z*-direction splitting the volume into eight octants. The upper left front octant contains the low-frequency coefficients that are initially transmitted over the network. A general example for computing 3-D DMWT using an over sampled scheme of preprocessing involves the following steps:

1. Let NxNxM be the input 3-D signal,



pairs 1,2 and 5,6 ...,2M-3,2M-2 after each other at the upper half of the resulting matrix rows, then the row pairs 3,4 and 7,8,..., 2M-1, 2M below them at the next half.

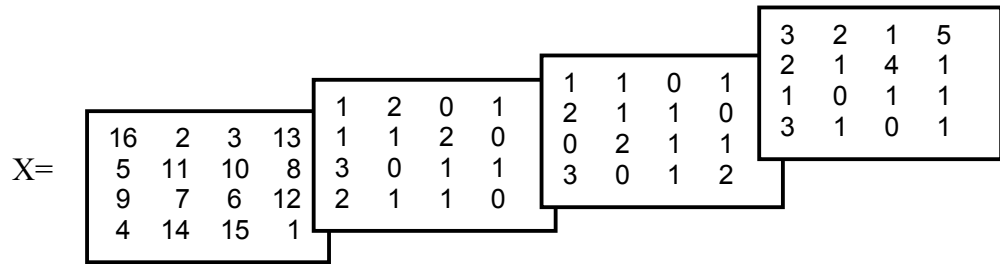
4. Repeat step 3 for all i, j .
5. Finally, a $2N \times 2N \times 2M$ DMW matrix result from the $N \times N \times M$ original matrix using repeated row preprocessing.

A general computer program computing a single-level 3-D DMWT using an over-sampled scheme of preprocessing (repeated row preprocessing) is written using MATLAB v.6.5 for a general $N \times N \times M$ 3-D signal (or image). An example test is applied to "Rubik's Cube sequence". In this image sequence a rubic's cube is rotating counterclock wise on a turn table. It consists of $256 \times 240 \times 4$ elements

as shown in Fig. (4-a). The size of array must be a power of two in each dimension. Unused area can be filled with zeros. The size of the array is scaled to the closest power of two i.e. $256 \times 256 \times 4$. The algorithm is initial run in 2-D for all 4 frames as shown in Fig.(4-a). Then a 1-D DMWT is applied in z-direction.

As shown in Fig.(4-a), the original "Rubic's Cube" image dimensions is $256 \times 256 \times 4$ ($N \times N \times M$). After a single-level 2-D of multiwavelets decomposition using an over-sampled scheme of preprocessing, image dimensions will be a matrix of $512 \times 512 \times 4$ ($2N \times 2N \times M$). After a single-level 1-D of multiwavelets decomposition using an over-sampled scheme of preprocessing, image dimensions will be a matrix of $512 \times 512 \times 8$ ($2N \times 2N \times 2M$) as shown in Fig. (4-b). The upper-left-front most subband of 256×256 dimensions is zoomed in as in Fig. (4-c).

Numerical example:



4.8000	4.9400	2.0577	5.5932	-0.3465	0.2192	0.3100	-1.2100
2.4200	1.5800	0.1768	1.8031	-0.2475	0.3889	0.6900	0.3100
1.6476	3.9457	1.3450	-0.1800	0.8450	-0.3800	1.7324	1.5556
4.0517	0.8344	0.5950	3.0700	-0.9050	0.8700	-0.1768	-0.0707
-0.7566	-0.4384	-0.3550	-0.8800	0.1450	-0.0800	0.1768	0.2828
0.6576	0.4101	0.2950	1.2700	-0.2050	0.0700	-0.3182	-0.6364
-0.2700	-1.3400	-0.7000	1.3859	-0.5586	0.2546	-0.8300	-1.3200
-0.4300	1.1400	0.2758	1.3718	0.1344	-0.3253	-0.1700	-1.1800

2.4200	0.8400	1.0536	1.3364	-0.3606	0.3465	-0.2700	0.1700
2.1000	2.1800	1.9587	1.7466	-0.0212	-0.0919	-0.4300	-0.3700
2.1072	1.1879	1.3325	0.1575	-0.0175	0.1575	0.0884	0.9016
2.9557	1.5415	-0.6425	2.6825	-0.4925	0.6825	1.1137	0.2298
-0.2970	0.1980	0.4825	-0.1925	0.1325	-0.1925	-0.2652	-0.1591
-0.0141	-0.2970	-0.2425	0.0825	-0.0925	0.0825	-0.0177	-0.0530
-0.9800	-0.0400	0.5975	0.2086	0.1025	-0.3571	-0.8150	-0.9850
-1.2200	-0.6600	1.0996	-0.9864	0.1803	-0.4207	-1.1850	-0.5150

2.4200	1.2600	2.2062	1.0748	-0.1980	0.0849	-0.8400	0.0400
3.9600	1.8200	0.0141	1.7819	-0.4101	0.7920	1.3400	1.3600
1.7466	2.1708	0.8050	0.1050	0.3050	0.0050	1.0253	1.1667
2.1708	0.6859	1.3050	0.3550	-0.1950	0.2550	-0.2475	0.6718
0.3323	0.1909	-0.5450	0.2550	-0.0450	0.1550	0.5303	0.2475
-0.2333	-0.3041	0.4550	0.0050	-0.0450	-0.0950	-0.6010	-0.3889
0.7100	-0.6100	-0.6010	1.0960	-0.4596	0.3889	-0.1300	-0.3700
-0.0100	-0.1900	-0.0354	0.7425	-0.1768	0.0354	-0.3700	-0.6300

Y=

20.6000	14.0400	4.0729	19.0636	-2.5739	2.8001	2.7600	-1.1600
15.9600	17.4000	13.1805	11.7663	0.3111	-0.5374	-0.8400	-0.7600
8.8671	13.4775	12.6250	6.7750	1.1750	-1.7750	-2.5244	-1.7183
11.5541	14.1846	13.9750	0.6250	2.0250	-1.4250	-0.1909	4.4336
-0.7495	0.1838	0.5750	0.2250	0.1250	-0.3250	-0.6152	-0.7990
1.6546	-1.0889	-2.9750	2.1750	-0.9250	1.1250	1.2940	0.1202
2.9400	-2.4600	-6.5973	5.9185	-2.1425	2.3122	2.2500	-1.0500
3.4600	-3.9400	-10.3733	11.0521	-3.5143	3.3446	2.5500	-3.7500

YY(:, :, 1) =

21.4197	14.4335	4.9680	19.3280	-2.6320	2.8080	2.3759	-1.1314
17.4797	17.9973	13.0540	12.4040	0.1340	-0.1960	-0.2630	-0.1754
9.5190	14.2630	12.8396	6.7515	1.2926	-1.7550	-2.0640	-1.2060
12.3590	14.3330	14.3882	0.7693	1.9219	-1.3025	-0.2940	4.6740
-0.6010	0.2630	0.3380	0.3309	0.1047	-0.2560	-0.3840	-0.6860
1.5390	-1.2070	-2.7521	2.1553	-0.9348	1.0734	1.0260	-0.0460
3.2117	-2.6941	-6.7860	6.3240	-2.3160	2.4540	2.1722	-1.1964
3.4210	-3.9810	-10.2840	11.2560	-3.5540	3.3260	2.3674	-3.9796

YY(:, :, 2) =

-1.3350	-1.6060	1.4945	-2.6704	0.2358	-0.3864	-1.4465	0.3815
1.0790	-1.1760	-2.0439	-0.2266	-0.4458	0.8128	1.2775	1.3175
0.4356	-0.4741	-1.4277	-1.1990	0.0072	0.4260	1.4188	1.6447
0.4356	-1.7646	-1.7777	0.8635	-0.6927	0.6885	0.1460	-0.1761
0.4144	0.2259	-0.4702	0.1835	-0.0353	0.1585	0.5385	0.3330
-0.5897	-0.1807	0.9397	-0.4690	0.1247	-0.2940	-0.8192	-0.3776

```

-0.1940  -0.0325  0.9627  -0.1492  0.0506  -0.2128  -0.7765  -0.3710
-1.0460  0.3525  2.3571  -1.8696  0.5823  -0.7453  -1.2085  0.0560

YY(:, :, 3) =
4.4321  2.9274  1.9160  3.6960  -0.5040  0.4360  -0.1358  -0.3451
3.1056  2.8284  2.0140  2.4940  -0.1260  0.0740  -0.1329  -0.2348
2.7850  2.8500  1.8897  0.0795  0.3412  -0.0053  0.8225  1.5525
4.6450  1.8800  -0.3836  3.9580  -0.8715  1.0448  1.0275  0.1975
-0.6150  0.0100  0.3270  -0.5639  0.1927  -0.2245  -0.1875  -0.0375
0.2650  -0.1200  -0.1149  0.6205  -0.1785  0.1114  -0.1525  -0.3225
-1.0847  -0.6081  0.2945  0.7945  -0.1355  -0.2455  -1.1589  -1.5351
-1.3902  -0.1697  1.2055  -0.3945  0.2355  -0.5545  -1.2452  -1.0105

YY(:, :, 4) =
10.1350  8.6740  2.8557  10.7116  -1.0193  0.9747  1.2185  -1.5335
6.4690  6.1940  3.7296  4.8044  -0.1170  0.1870  0.4225  0.0725
3.7166  7.4455  4.7585  1.8247  1.1435  -0.9252  0.8195  0.7237
6.6157  4.7054  4.8210  2.5498  -0.1440  0.2498  -0.4356  1.1833
-0.9009  -0.4105  -0.2340  -0.7427  0.1510  -0.1428  0.0099  0.0484
1.1356  0.1375  -0.5865  1.8423  -0.4515  0.3923  0.1195  -0.5385
0.7860  -1.9725  -2.7337  2.9957  -1.1710  0.9875  0.0560  -1.3535
0.8740  0.0425  -3.0681  4.7790  -0.9539  0.7768  0.8590  -2.1115

YY(:, :, 5) =
-3.7550  -2.8660  -0.7117  -3.7452  0.4338  -0.4713  -0.6065  0.3415
-2.8810  -2.9960  -2.0580  -2.0085  -0.0357  0.0209  -0.0625  -0.0425
-1.3110  -2.6449  -2.2327  -1.3040  -0.2978  0.4210  0.3935  0.4780
-1.7352  -2.4505  -3.0827  0.5085  -0.4978  0.4335  0.3935  -0.8478
0.0820  0.0350  0.0747  -0.0715  0.0097  0.0035  0.0081  0.0856
-0.3564  0.1234  0.4847  -0.4740  0.1697  -0.1990  -0.2181  0.0113
-0.9040  0.5775  1.5638  -1.2452  0.5102  -0.6017  -0.6465  -0.0010
-1.0360  0.5425  2.3925  -2.6121  0.7591  -0.7806  -0.8385  0.6860

YY(:, :, 6) =
4.9738  3.1763  0.0495  4.8795  -0.7305  0.8695  1.1787  -0.1959
2.7139  4.5764  4.5375  2.8075  0.3575  -0.7225  -1.3216  -1.2594
2.1740  2.6555  3.5288  1.9290  0.0711  -0.4115  -1.4515  -0.9560
2.8540  4.1705  2.8076  0.8719  0.5519  -0.3373  0.5885  0.9290
-0.4960  0.0455  0.7393  -0.1181  0.1100  -0.2666  -0.6365  -0.4710
0.5640  -0.2695  -1.2548  0.5572  -0.2577  0.4087  0.7635  0.3040
-0.0170  -0.2298  -1.1805  0.9670  -0.2305  0.2370  0.4320  -0.3861
0.4978  -1.3541  -2.4645  2.1380  -0.8145  0.7680  0.4660  -0.7948

YY(:, :, 7) =
5.3350  3.7340  0.7980  5.1184  -0.6728  0.7555  0.9085  -0.3235
4.0490  4.6140  3.5529  3.0013  0.1305  -0.2019  -0.2675  -0.2375
2.0690  3.4998  3.4135  2.0047  0.2985  -0.5452  -0.9129  -0.8319
2.5640  3.8711  4.2260  -0.5202  0.7610  -0.6202  -0.2588  1.2541
-0.1442  0.0279  0.1210  0.1373  0.0060  -0.0628  -0.1669  -0.2344
0.4780  -0.2726  -0.8815  0.5723  -0.2465  0.3222  0.4377  0.0979
1.0560  -0.6325  -2.0336  1.6097  -0.6124  0.7329  0.8860  -0.0335
1.3040  -1.0975  -3.3439  3.4072  -1.0882  1.1020  1.0290  -0.9315

YY(:, :, 8) =
6.1985  2.9614  0.5605  4.8305  -0.9595  1.1405  0.9567  0.3231
5.5451  6.8646  6.0325  4.2125  0.3125  -0.5575  -1.0119  -0.7205
3.1860  3.3895  4.8203  3.0261  -0.0658  -0.4670  -2.2210  -1.5465
3.0060  5.8745  5.2764  -0.9549  1.3096  -0.9832  0.3640  1.9435
0.0560  0.3995  0.6449  0.5830  0.0014  -0.1524  -0.4860  -0.5815
0.2960  -0.7855  -1.5507  0.1375  -0.2850  0.4628  0.7890  0.4685
1.0918  -0.1591  -2.1420  1.6105  -0.4920  0.6905  1.2615  0.1421
1.3972  -2.5703  -4.2630  3.4845  -1.5130  1.5045  0.8811  -0.9412

```

5- Inverse Discrete Multiwavelet Transform Computation for 1-D and 2-D Signals

To reconstruct the original signal from the discrete multiwavelets transformed signal, the inverse discrete multiwavelets transform (IDMWT) should be used. Reconstruction matrix which is the inverse (or transpose) of the transformation matrix (5) of GHM four multifilters matrices (3) and (4) can be used for computing IDMWT. An over-sampled scheme of post-processing should be used in computing IDMWT

To compute a single level 1-D Inverse discrete multiwavelets transform using over-sampled scheme of post-processing, the following steps should be followed:

1. Apply shuffling by arranging the row pairs 1, 2, and 3, 4, ..., N-1, N of the $2N \times 1$ matrix to be the row pairs 1, 2 and 5, 6, ..., 2N-1, 2N-2 of the resulting matrix and arranging the row pairs N+1, N+2 and N+3, N+4, ..., 2N-1, 2N of the $2N \times 1$ matrix to be the row pairs 3, 4, and 7, 8, ..., 2N-1, 2N of the resulting matrix.
2. Multiply a $2N \times 2N$ reconstruction matrix ($2N \times 2N$ transformation matrix (5) transpose) with the resulting $2N \times 1$ shuffled matrix.
3. Apply postprocessing by discarding the even rows 2, 4, ..., 2N from the row reconstructed $2N \times 1$ matrix to have an $N \times 1$ original reconstructed 1-D signal matrix.

To compute a single level 2-D Inverse discrete multiwavelets transform using over-sampled scheme of post-processing, the following steps should be followed:

1. Coefficients shuffling, which is applied to the DMWT $2N \times 2N$ matrix four basic subbands

individually? For each subband, coefficients shuffling, shuffles the columns first then shuffles the rows.

2. Column reconstruction:
 - a. Transpose the postprocessed $2N \times 2N$ resultant matrix.
 - b. Apply Shuffling by arranging the row pairs 1, 2, and 3, 4, ..., N-1, N of the coefficients shuffled $2N \times 2N$ matrix transpose to be the row pairs 1, 2 and 5, 6, ..., 2N-1, 2N-2 of the resulting matrix and arranging the row pairs N+1, N+2 and N+3, N+4, ..., 2N-1, 2N of the $2N \times 2N$ postprocessed resultant matrix transpose to be the row pairs 3, 4, and 7, 8, ..., 2N-1, 2N of the resulting matrix.
 - c. Multiply a $2N \times 2N$ reconstruction matrix ($2N \times 2N$ transformation matrix (5) transpose) with the resulting $2N \times 2N$ shuffled matrix.
3. Apply postprocessing by discarding the even rows 2, 4, ..., 2N from the column reconstructed $2N \times 2N$ matrix to have an $N \times 2N$ resultant matrix.
4. Row reconstruction
 - a. Transpose the postprocessed $N \times 2N$ resultant matrix.
 - b. Apply Shuffling by arranging the row pairs 1, 2, and 3, 4, ..., N-1, N of the $2N \times N$ postprocessed resultant matrix transpose to be the row pairs 1, 2 and 5, 6, ..., 2N-1, 2N-2 of the resulting matrix and arranging the row pairs N+1, N+2 and N+3, N+4, ..., 2N-1, 2N of the $2N \times N$ postprocessed resultant matrix transpose to be the row pairs 3, 4, and 7, 8, ..., 2N-1, 2N of the resulting matrix.

- c. Multiply a $2N \times 2N$ reconstruction matrix ($2N \times 2N$ transformation matrix (5) transpose) with the resulting $2N \times N$ shuffled matrix.
5. Postprocessing, an over-sampled scheme of postprocessing can be done by discarding the even rows 2, 4, ..., $2N$ from the column reconstructed $2N \times N$ matrix to have an $N \times N$ original reconstructed 2-D signal matrix.

A general computer program computing a single-level IDMWT using an over-sampled scheme of preprocessing (repeated row preprocessing) is written using MATLAB v.6.5 for a general $N \times N$ 2-D decomposed image.

An example test is applied to the decomposed Lena image shown in Fig. (1-b) to reconstruct the original "Lena" image by using this computer program of the method of computing inverse discrete multiwavelets transform using an over-sampled scheme of postprocessing and the result is shown in Fig. (5).

6- Inverse Discrete Multiwavelet Transform Computation for 3-D Signals

1. Apply 2-D IDMWT algorithm to each resultant matrix from 3-D DMWT.
2. Apply 1-D IDMWT algorithm to each element in all resultant matrices from 1 in z-direction.

A general computer program computing a single-level 3-D IDMWT using an over-sampled scheme of preprocessing (repeated row preprocessing) is written using MATLAB v.6.5 for a general $N \times N \times M$ 3-D decomposed image.

An example test is applied to the decomposed Rubic's cube image shown

in Fig. (4-b) to reconstruct the original "Rubic's cube" image by using this computer program of the method of computing inverse discrete multiwavelets transform using an over-sampled scheme of postprocessing and the result is shown in Fig. (6).

7- Conclusion

This paper presents a new 3-D multiwavelets transform computation methods that verify the potential benefits of multiwavelets and gain a much improvement in terms of low computational complexity. The general procedures with illustrated numerical examples are described in details. The verification of the new and developed methods using a computational aspect was also developed. Following are some concluding remarks obtained:

1. A single level decomposition in the multiwavelet domain is equivalent to two scalar wavelet decompositions. Thus although computation complexity is double for DMWT compared to DWT, the levels of computation are less by half to get the same image quality.
2. Multiwavelets filter banks require a vector-valued input signal. This is another issue which is addressed when multiwavelets are used in the transform process. A scalar-valued input signal must somehow be converted into a suitable vector-valued signal. This conversion is called preprocessing.
3. The most obvious way to get two input rows from a given signal is to repeat the signal using repeated row

- preprocessing (over-sampled scheme).
4. Using repeated row preprocessing introduces an oversampling of data by a factor of 2 which doubles the original image dimensions. In the same time the upper-left most subband (L_1L_1) of the decomposed image, which usually the 2nd, 3rd, ... level of decompositions are applied to it, has half dimensions of the original.
 5. Discrete multiwavelet transform computation algorithm using repeated row preprocessing should be applied to a matrix with a size at least to 4×4 .
 6. Transformation matrix dimensions used in computing DMWT algorithms should equal the dimensions of the input image after preprocessing.

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