# Prediction of Ultimate Soil Bearing Capacity for Shallow Strip Foundation on Sandy Soils Using (ANN) Technique

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#### ABSTRACT

Bearing capacity of soil is an important factor in designing shallow foundations. It is directly related to foundation dimensions and consequently its performance.

The calculations for obtaining the bearing capacity of a soil needs many varying parameters, for example soil type, depth of foundation, unit weight of soil, etc. which makes these calculation very variable–parameter dependent.

This paper presents the results of comparison between the theoretical equation stated by Terzaghi and the Artificial Neural Networks (ANN) technique to estimate the ultimate bearing capacity of the strip shallow footing on sandy soils. The results show a very good agreement between the theoretical solution and the ANN technique.

Results revealed that using ANN gave a very high correlation factor associated with the results obtained from Terzagih's equation, besides little computation time needed compared with computation time needed when applying Terzagih's equation.

#### <u>الخلاصة</u>

قابلية تحمل التربة للأحمال من العوامل المهمة التي نحتاجها في تصميم الأسس الضحلة لما لها من تأثير على أبعاد التصميم وبالتالي على أدائه بشكل مباشر. ان عملية احتساب تحمل التربة تحتاج إلى عدة عوامل وتشمل متغيرات كثيرة مثل نوع التربة، عمق الأساس، وحدة الوزن للتربة، ...الخ. مما يجعل احتساب تحمل التربة من المقادير المتغيرة بشكل كبير تبعا للعوامل المذكورة. لهذا تم تصميم موديل باستخدام الشبكات العصبية لحساب قابلية تحمل التربة يغني عن اجراء الحسابات المعقدة وتمت المقارنة بين نتائجها والنتائج المستحصلة من استخدام المعادلات النظرية حيث اظهرت النتائج توافق كبير جدا فيما بينها يضاف الى ذلك التوفير الكبير في الوقت اللازم لاجراء الحسابات باستخدام طريقة الشبكات العصبية مقارنة مع الطرق التقليدية.

Keyword: Soil Bearing capacity, Artificial Neural Network, shallow foundation.

#### **1. INTRODUCTION**

The ultimate bearing capacity for a soil  $q_u$  is defined as the least pressure which would cause shear failure of the supporting soil immediately below and adjacent to a foundation.

The ultimate bearing capacity can be determine either experimentally or by calculations using analytical and / or empirical formulae.

Artificial Neural Network (ANN) technique became a powerful tool that can be used to solve the civil engineering problems (Jeng, et al., 2003), and a more effective tool for engineering applications, thus this study was undertaken in order to predict the ultimate bearing capacity of shallow strip footing over sandy soil by using artificial neural networks technique.

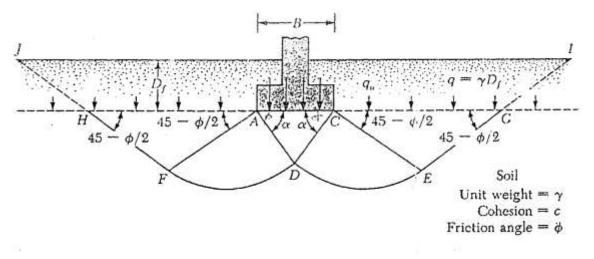
A set of varying conditions are studied and the results obtained by implementing the artificial neural network technique are then compared to the results obtained by implementing Terzaghi's equation, results revealed a very high correlation factor between answers obtained from implementing the ANN technique and the answers obtained by implementing Terzagi's equation.

#### 2. Theory

The ultimate bearing capacity of the soil under shallow strip footing can be expressed by the following general equation, Terzaghi (1943).See Figure (1).

where c = Cohesion of soil.  $\gamma = Unit weight of soil.$  D = Footing depth. B = Footing width.  $N_c, N_q, N_\gamma = bearing capacity factors depending only on (<math>\phi$ )  $N_c = (N_q - 1) \cot \phi$  ......(2)  $N_q = e^{(\pi \tan \phi)} \tan^2 \left( 45 + \frac{\phi}{2} \right)$  .....(3)  $N_\gamma = 2 (N_q + 1) \tan \phi$  .....(4)  $\phi = Angle of internal friction of the soil.$ 

Eq.(2) for  $N_c$  was originally derived by Prandtl (1921),and Eq.(3) for  $N_q$  was presented by Reissner (1924). Caquot and Kerisel (1953) and Vesic (1973) gave the relation for  $N_{\gamma}$  (Eq.(4)).



Figure(1) Failure surface of shallow foundation

#### 3. Implementation of Neural Network

MatLab version R2008a was used in designing and implementation of the ANN (Demuth, et al., 2008). To find the most appropriate design and learning algorithm, the method of trial and error was used by choosing different learning algorithms, layers, and neurons, as follows (Zurada, 1992):

- 1. Ten different learning algorithms were used presented in Appendix (A) Table A–1.
- 2. Three different numbers of layers were used, 1 layer, 2 layers, and 3 layers.
- 3. Three different numbers of neurons were used, 10, 20, and 30 neurons per each layer.

First, Eq. (1) was used to calculate the ultimate bearing capacity for various soil properties, considering different values for the parameters needed to solve the equation, as follows:

- 1.  $\phi$  varying from 10° to 45°, steps of 2.5° was used.
- 2.  $\gamma$  varying from 14 kN/m<sup>3</sup> to 23 kN/m<sup>3</sup> steps of 1.0 kN/m<sup>3</sup> was used.
- 3. B varying from 0.5 m to 1.5 m, steps of 0.1 m was used.
- 4. D varying from 0.5 m to 1.5m, steps of 0.25 m was used.
- 5. c = 0 for sandy soil.

Practically, these values could represent and cover the actual range that may be needed in the analysis and design of real problems. The sum of 8250 cases were taken into consideration, each case represents a different design alternative and has a unique ultimate bearing capacity value. The ultimate bearing capacity was calculated for each case using Eq.1 as mentioned before.

All these cases and their parameters are considered as the input data for a special ANN designed to memorize each individual case and its calculated bearing capacity so that it could predict the ultimate bearing capacity later.

A procedure of trial and error was used to find the most appropriate number of layers, number of neurons per layer, and the most efficient learning algorithm among ten learning algorithms implemented in teaching the Neural Networks.

Another set of random data was prepared to verify the reliability and the consistency of the Neural Network, the data were totally different from the input data and there values were never shown in the input data.

This procedure was conducted to obtain the most efficient Neural Network which is considered to have:

- 1. maximum correlation ratio between the target data and the output data obtained,
- 2. maximum correlation ratio between verifying data and the output obtained, and
- 3. minimum time to reach solution.

### 4. Results and Discussion

Table A-2 represents a sample of the first 100 input data (Appendix-A), the total number of data inputs were 2640. The method of trial and error was used to find the most appropriate Neural Network that can reflect the most suitable design requirements (i.e. the correct ultimate bearing capacity  $q_u$  for the required design parameters,  $\phi$ , D, B,  $\gamma$ , and c).

Among ten learning algorithms, ten outputs were obtained, each output was obtained after teaching the Neural Network with the most representative number of neurons, and number of layers. A correlation factor was calculated for each output to show the reliability of the network.

Table(1) shows the algorithm name and the highest correlation factor that can be obtained after applying the learning rule for a variety of neuron numbers and layers.

No.	Algorithm name	Correlation Factor	Neuron numbers And Number of Layers		
1	GDA	0.995057444	10		
2	GDX	0.997960736	10 x 10		
3	RP	0.999956575	20		
4	CGF	0.999120732	10		
5	CGP	0.998901795	10 x 10		
6	LM	0.99999993	10		
7	BFG	0.997986589	10		
8	SCG	0.999295558	10		
9	CGB	0.996573746	10		
10	OSS	0.997773765	10		

Table 1 Algorithm name vs. correlation factor

As can be seen from Table 1, the most efficient algorithm that gave the highest correlation factor is no. 6 (LM learning rule) with 10 neurons (i.e. one layer which consist of 10 Neurons) with a correlation factor of 0.999999993.

Table 2 shows the verifying data that was used to test each algorithm and its corresponding Neural Network, the input data were chosen so that they were never taught to the Neural Network before (they were never shown in the input data that was used for teaching the network in the first step).

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No.	В	γ	D	¢	$\mathbf{q}_{\mathbf{u}}$	Output		
1	0.75	19.1	1.1	18	139.589	139.5673802		
2	0.8	22	0.87	29	484.899	484.7750421		
3	1.1	15.86	0.57	41	1803.897	1804.095986		
4	1.3	18.2	0.97	38	1786.895	1786.784995		
5	1.45	22.5	0.76	14	98.61363	98.64410774		
6	1.15	15.73	0.81	32	568.5862	568.6354125		
7	0.88	16.6	1.49	19	177.5926	177.4755966		
8	1.22	21.5	0.55	27	345.8494	345.9459282		
9	1.45	15.66	1.3	17	137.223	137.1086517		
10	1.55	19.24	0.73	42	3518.381	3518.516495		
11	0.22	14.3	0.56	34	300.3472	299.7223238		
12	0.38	20.1	1.44	22	253.5961	253.7477964		
13	1.11	17.8	0.61	44	3471.177	3471.39989		
14	0.93	20.5	0.88	11	62.64117	62.45822203		
15	0.67	21	0.59	37	997.4388	997.6196914		
16	0.4	13.5	1.45	19.8	136.9498	137.127496		
17	0.3	17.6	1.1	33.2	613.1835	612.9913123		
18	1.45	15	0.3	9.5	22.8533	22.84814129		
19	1	13	0.68	43.4	2235.155	2235.190448		
20	1.4	12	0.25	15.6	36.78086	36.3282789		

Table 2 Verifying Data Used to Test Reliability of Neural Network

The output was then compared to the calculated values using the same formula (Eq. 1) and a correlation factor is evaluated the see the most efficient algorithm that gave the highest correlation factor for the test data. Results are shown in Table 3.

No.	Algorithm Name	<b>Correlation Factor</b>				
1	GDA	0.997409464				
2	GDX	0.998322484				
3	RP	0.999934347				
4	CGF	0.999094581				
5	CGP	0.999188115				
6	LM	0.999999984				
7	BFG	0.998235235				
8	SCG	0.997448906				
9	CGB	0.993152833				
10	OSS	0.997531545				

 Table 3 Correlation Factor Obtained for Each Learning Algorithm

As could be seen from Table 3 that the algorithm that gave the best correlation factor is no. 6 (LM) with a correlation factor of 0.999999984.

Figure 2 shows the performance of the Neural Network reflected by showing the Mean Squared error (MSE) of value less than 0.01.

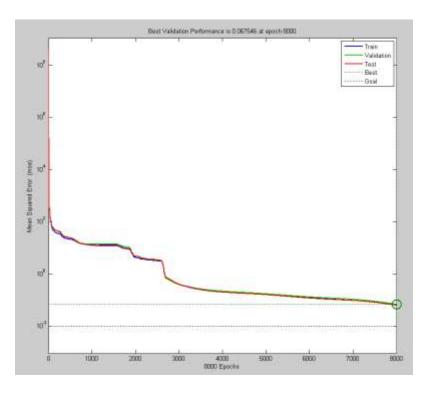


Figure (2) Performance of the trained Neural Network

Where Figure. 3 shows the regression value obtained after training the Neural Network which shows a value of (1) which means that the output obtained have a very strong relation to the target values desired.

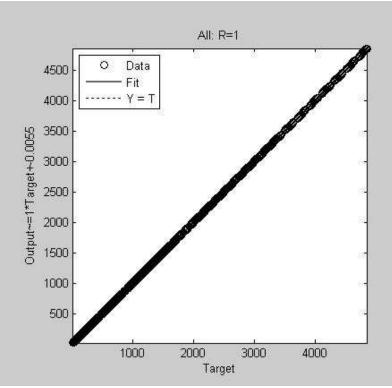


Figure (3) Regression Value of Neural Network Between Input Data and Target Data

#### 5. Conclusions and recommendations

The calculation of bearing capacity of shallow foundation is a many parameter dependant process, and it has many pre calculations till we can implement the Terzaghi's equation (Eq. 1), these calculations include the bearing capacity factors  $N_q$ ,  $N_\gamma$ , and  $N_c$ . Another alternative is to use the charts which could lead to some approximations.

Using an Artificial Neural Network can facilitate these calculations to a great extent. The Neural Network can remember the parameters that were used as an input (B, D,  $\phi$ , c, and  $\gamma$ ) and the calculated values of the ultimate bearing capacity  $q_u$ , and this operation has to be done only once, then the network can be used to predict the bearing capacity for any input values and give the bearing capacity value as was done here by using the verifying data.

The advantage of using the Artificial Neural Network comes mainly from saving calculation time of the parameters and the ultimate bearing capacity, and once the network was ready, the same network can be used as many times as desired with no further need for teaching or modifying, besides, the calculation needed when using the Neural Network are simple compared to the calculations needed to obtain the results in the original equation.

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# <u>Appendix A</u>

Symbol	Algorithm Name
GDA	Backpropagation training with an adaptive learning rate
GDX	adaptive learning rate with momentum training
RP	Resilient Backpropagation
CGF	Fletcher-Powell Conjugate Gradient
CGP	Polak-Ribiére Conjugate Gradient
LM	Levenberg-Marquardt
BFG	BFGS Quasi-Newton
SCG	Scaled Conjugate Gradient
CGB	Conjugate Gradient with Powell/Beale Restarts
OSS	One Step Secant

# Table A–1 Training Algorithms Names and Symbols

## Table A-2 Sample of 100 Input Data and Output Data

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