



# Violence Prediction Estimation in Surveillance Cameras Using CNN with GAMMA Correction

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(Received 24 June 2024; Revised 14 October 2024; Accepted 10 November 2024; Published 1 September 2025)

<https://doi.org/10.22153/kei.2025.11.004>

## Abstract

In recent years, the deployment of surveillance cameras has significantly increased to enhance security in public and private spaces. Numerous businesses continue to employ individuals to monitor these cameras. However, unusual and suspicious activities in the video feeds are often overlooked due to the potential for human error. Consequently, manual monitoring of security cameras can be time-consuming and inefficient. This study investigates the application of deep learning techniques, particularly convolutional neural networks (CNNs) and support vector machines (SVMs), to predict violence in surveillance video streams. The proposed CNN model is optimised through the utilisation of gamma correction as a preprocessing step to extract essential spatial features from video frames, significantly enhancing the accuracy of violence detection. This study leverages the real-time capabilities of surveillance data by utilising the RLV dataset, which comprises a range of violent and non-violent scenarios. The CNN–SVM hybrid model developed in this study achieved an impressive 99% accuracy, outperforming traditional methods and demonstrating strong spatial feature extraction capabilities. Furthermore, this study addresses the challenges of real-time video surveillance by ensuring scalability and practical applicability, providing a robust solution for enhancing security measures in public and private spaces.

**Keywords:** anomaly detection; surveillance cameras; Convolutional Neural Network (CNN); Deep Learning; Violence detection; Support Vector Machine.

## 1. Introduction

The use of surveillance cameras to monitor public situations is becoming increasingly common due to the growing issues in public administration, security and safety. The task of monitoring security camera footage to detect unusual behaviour, extract patterns and promptly respond may appear simple for humans. However, a person finds it difficult to simultaneously observe multiple signals due to the inherent limitations of human capabilities [1]. The process is time-consuming and costly, necessitating the involvement of people and a workplace. Consequently, an automatic detection system is crucial. Anomalous event identification is an

essential aspect of understanding human behavioural through surveillance cameras [2]. However, detecting such events in security footage presents several challenges: (1) A large database of anomalous events is difficult to obtain due to their rarity. The learning process may be adversely affected by the lack of data. (2) An ‘anomaly’ refers to anything that deviates from a pre-established pattern (or rule). We are unable to create a model specifically designed to handle uncommon events. (3) An activity may deem normal or abnormal depending on the situation. This notion suggests that a global anomalous event is likely to regularly occur in cases involving a gun club. Although this event is common in a shooting group, the practice

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of ‘shooting’ is often considered unusual. However, certain conduct may be considered an anomalous practice in a particular locale and context, referred to as a local abnormal event, even if it is not inherently anomalous. Varadarajan [3] characterised anomalous events as ‘actions that are performed in an unusual location, at an unusual time’. Anomalous behaviour, a significant and recognised classification of learning methods, can be categorised into three approaches from a learning perspective: supervised, unsupervised and semi-supervised. Specifically, single-model learning focuses solely on either normal or abnormal events for training. Meanwhile, multi-model learning involves training of normal and abnormal events. The methods used in the single model learning process to distinguish abnormal events from normal ones include the following: learning the definition of normality [4-6], constructing a multidimensional model of abnormal events within the space of normal events [7-10] and learning rules that define abnormal events [11]. However, the multi-model learning strategy involves training each class either independently or in combination with other classes. This strategy is particularly effective when multiple groups of irregularities exist. In unsupervised learning, numerous clustering techniques assume that abnormal and normal events can be easily distinguished within the feature space [12-14]. Additionally, the semi-supervised method of detecting anomalous behaviour is not as accurate as unsupervised models and does not depend on pre-labelled data as the supervised approach does. However, anomalous behaviour detection is regarded as an unsupervised learning problem. The evolution of violence detection in video surveillance began with traditional methods that relied on handcrafted features and basic classifiers [15]. This approach was later enhanced by the integration of machine learning algorithms, which improved the classification of violent events by combining spatial and temporal features [16]. Finally, deep learning models, particularly convolutional neural networks (CNNs), have significantly improved the accuracy of violence detection in large-scale datasets and paved the way for highly sophisticated neural network architectures [17]. In this study, anomalous behaviour is considered a multiple-scene issue

under a supervised learning scheme. The classification of numerous erratic behaviours in the real world as anomalies is based on the definition of an anomalous event. In this study, we focus on the dataset [18] that contains numerous anomalous, illegal and violent behaviours captured on video in public areas. These behaviours have a serious influence on individuals and the general public. Our proposed model utilised VGG16 as a CNN for feature extraction. Given the nature of the video dataset, we augment the model with an SVM, which can effectively handle this type of data. This methodology enhances the ability to detect irreversible damage whilst reducing the need for human labour and financial resources. Moreover, this strategy is of great importance to governments and the public because it can significantly reduce emergency response times. A summary of the primary contributions of the proposed method is provided below.

1. We gather the essential data necessary to identify violence, including human bodies and their interactions, to minimise the complexity of the model’s input. This approach facilitates the development of a real-time infrastructure for crime detection.
2. We uniquely combine features derived from human interactions with temporal changes in body postures to fully utilise both information sources.
3. We recommend the effective use of a support vector machine (SVM) in two-stream models designed for violent behaviour detection. This approach facilitates real-time operation whilst still maintaining accuracy.

Figure 1 presents a flow chart that illustrates the steps involved in implementing a video-based violence detection scheme. The first phase involves inputting a collection of movies that include violent and non-violent scenes. The second phase is key frame extraction, although not all methods utilise it. This process focuses on selecting frames that depict violent content, aiming to avoid the processing of large volumes of video, minimising the computational burden. In the third phase, the information is transformed to serve as an input for the violent behaviour detection algorithm; the type of input is based on the desired features.

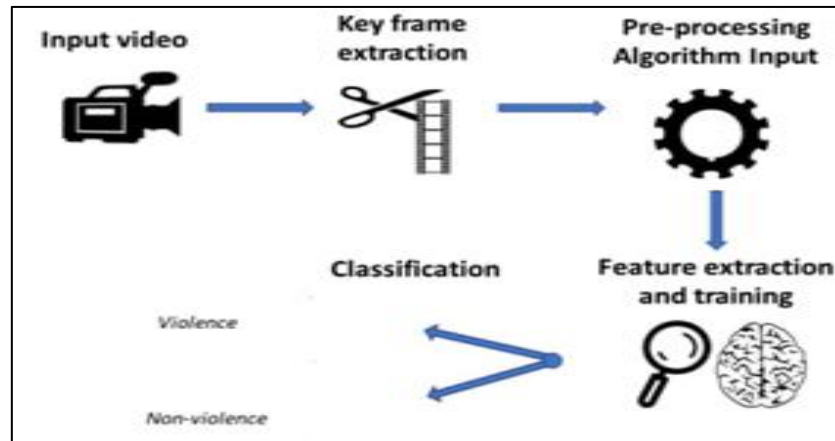


Fig. 1. Basic steps in the application of an algorithm for video violence detection

The remainder of this study discusses related projects that utilise different models and sub-models based on the overall concept of detecting anomalous behaviour in security camera footage. Section 2 presents an overview, followed by a detailed discussion of the proposed methodology in Section 3. Section 4 explores the findings from various experiments. Section 5 concludes the study with final remarks and future project directions.

## 2. Literature Review

Liu et al. [19] reviewed several experiments, including one by reference [20], which proposes an unsupervised deep representation method for detecting abnormal behaviour in crowded areas. This method uses hybrid deep learning architectures and a two-channel framework to learn and generate anomaly ratings. The effectiveness of this method has been validated through experimental findings, such as training data and lighting condition tests. Sreenu et al. [21] highlighted live CCTV streaming videos as a valuable big data source for enhancing security in crowded public areas. The study provides a comprehensive review of deep learning techniques applied to several crowd video evaluation tasks, including features, action recognition and violence detection. Farroq et al. [22] aimed to recognise crowd divergence behaviour to prevent disasters, such as stampedes. Their work proposed an approach to crowd behaviour classification utilising motion-shaped images by a CNN. The methodology, which utilises a divergence localisation strategy, outperforms existing techniques in terms of accuracy. Additionally, the study offers new datasets for analysing typical and abnormal crowd behaviour in

high-density settings. Behera et al. [23] proposed a deep learning method called PIDLNet, which combines 3D convolutional features with physics-based properties, to explain crowd dynamics. Varghese et al. [24] proposed a method that combines cognitive deep learning frameworks with a fuzzy computational model based on sentiments, behavioural variables and visual inspection. This approach aims to detect and predict various collective crowd actions in intelligent monitoring devices for efficient crowd management. B. Peixoto et al. [25] proposed a novel approach to violence detection that utilises two deep neural network frameworks directly applied to raw image data. The two networks used are a CNN–LSTM, which incorporates long short-term memory, and the 3D-based CNN (C3D). Rather than separately training each network, the authors fused C3D and CNN–LSTM to directly train the model for the violence detection task. This approach yielded an accuracy of 56% for the C3D and CNN–LSTM networks, compared with 63% and 61% for their proposed methods in each network, respectively. Soliman et al. [26] proposed a novel model that takes a short movie, extracts its RGB frames and feeds them into a deep neural network for end-to-end processing. A sequence of fully connected layers was utilised for classification. Meanwhile, a pre-trained VGG-16 on ImageNet was used for the spatial feature extractor, whilst an LSTM was utilised for the temporal feature extractor. RealLife Violence Situations is a newly developed dataset consisting of 2000 videos, depicting either aggressive or peaceful scenarios. The proposed model was enhanced using this dataset, thereby increasing its accuracy to 88.2%. Abdali et al. [27] demonstrated a real-time violence detector based on deep learning models, with the CNN component serving as the spatial feature extractor and the LSTM component as the temporal

feature extractor. The proposed model achieved a success rate of 98% at 131 frames per second, outperforming the current state-of-the-art methods. They created individual verification data for each of the three datasets, achieving 100% accuracy on the movie dataset, 96.33% on the hockey battle dataset and 85.71% on the violent flow dataset. To train and fine-tune the Inception-ResNetV2 architecture proposed by Jain et al. [28], a (CNN) framework was utilised. The model was configured to capture and analyse motion patterns for the purpose of detecting aggressive behaviour. Initially, RGB video sequences were transformed into dynamic images (DIs) using a temporal averaging technique that compresses the video into a single frame by averaging background pixels and static regions over time. These DIs effectively highlight motion-related features while suppressing irrelevant background information. The resulting DIs were then input into the Inception-ResNetV2 model, which extracted motion characteristics and performed classification to determine the presence or absence of aggression. The testing accuracy achieved is 86.78% for the violent real-life scenario dataset, 100% for the movie dataset and 93.33% for the hockey fight dataset. Sernani et al. [29] proposed three models for violent behaviour detection to evaluate the degree to which harmless gestures, such as claps, small hits or high fives, are considered violent (i.e. to reduce false positive values). These models were tested on the AIRTLab dataset, which was designed to assess the susceptibility of algorithms to false positives. When contrasted with 2D CNNs, Kang et al. [30] proposed a more advanced model that integrates LSTM and requires lower computational power than existing 3D-CNN-based methods.

Specifically, the proposed models for MobileNetV3 and EfficientNet-B0 achieved tremendous success on six different violent datasets. Gadelkarim et al. [31] proposed two models for the recognition and categorisation of violence, which helps in preventing daily violence. The models were developed using the following datasets: XD-Violence, LAD2000 and UCF-Crime. Similar to the XD-Violence dataset, their research benefitted from transfer learning, which reduced the training period and improved accuracy. Islam et al. [32] proposed an effective two-stream deep learning architecture, with the first stream incorporating a pre-trained MobileNet and the second stream comprising a separate convolutional LSTM that processes frame content. They utilised three different fusion methods across three different datasets to combine the output maps from two streams. Their model demonstrated excellent performance using the RWF-2000 dataset, which is the most challenging among larger datasets, achieving over a 2% increase in accuracy compared with smaller datasets. Honarjoo et al. [33] proposed a convolutional-based approach with limited complexity and a series of frames with effective feature vectors. This approach successfully processed the violent waterfalls and hockey disputes. Guedes et al. [34] developed a method that utilised the DI approach to recognise violent activities that involve physical confrontations in video games. This method used handcrafted images processed through CNNs and an SVM, and it was successful when applied to the following datasets: 99.8% for movies, 97.5% for hockey games and 93.4% for crowd datasets. A summary of the papers is shown in Table 1.

**Table 1,**  
**Literature survey of all the referred papers**

| Year | Author               | Point of Selecting the Research  |
|------|----------------------|--|
| 2019 | Liu et al. [19]      | Explored hybrid deep learning methods for anomaly detection in crowded areas using unsupervised methods.               |
| 2020 | Sreenu et al. [21]   | Presented live CCTV streaming videos as a key big data source for security in crowded areas.                           |
| 2020 | Farroq et al. [22]   | Proposed CNN-based approach to detect crowd divergence behavior and prevent stampedes, outperforming other techniques. |
| 2020 | Behera et al. [23]   | Suggested PIDLNet, combining 3D convolutional features with physics-based properties for crowd action prediction       |
| 2020 | Varghese et al. [24] | Developed a model combining deep learning and fuzzy logic for crowd behavior management                                |

|      |                        |  |
|------|------------------------|--|
| 2021 | Peixoto et al. [25]    | Presented CNN-LSTM and C3D neural networks for violence detection, achieving 56% accuracy.   |
| 2021 | Soliman et al. [26]    | Used CNN-LSTM approach for violence detection, reaching 88.2% accuracy on the RealLife Violence Situations dataset.                        |
| 2021 | Abdali et al. [27]     | Developed a real-time violence detector with 98% accuracy at 131 fps   |
| 2021 | Jain et al. [28]       | Utilized Inception ResNetV2 to transform RGB videos into dynamic images for motion recognition, achieving up to 100% accuracy.             |
| 2021 | Sernani et al. [29]    | Focused on reducing false positives in violent behavior detection models   |
| 2021 | Kang et al. [30]       | Proposed MobileNetV3 and EfficientNet-B0 architecture with less computational power than existing 3D-CNNs.                                 |
| 2021 | Gadelkarim et al. [31] | Proposed models for violence detection benefiting from transfer learning, achieving higher accuracy on XD-Violence and UCF-Crime datasets. |
| 2021 | Islam et al. [32]      | Proposed two-stream deep learning model with significant performance on RWF-2000 dataset.  |
| 2021 | Honarjoo et al. [33]   | Used convolutional-based approach to process violent datasets with feature vectors.  |
| 2021 | Guedes et al. [34]     | Developed method using dynamic images with CNN and SVM, achieving high accuracy in various datasets, including movies and crowd violence.  |

### 3. Methodology

Section 3 presents an overview of the study's methodologies, including dataset acquisition, data pre-processing techniques (such as gamma correction) and the design of the CNN model for violence prediction. Moreover, this section explains the training, evaluation and performance metrics of these models, including the hybrid model (CNN–SVM) for feature extraction.

#### 3.1 Datasets

The Real-Life Violence Situations dataset [35] contains a total of 2000 videos, comprising 1000 violence videos and 1000 non-violence videos collected from YouTube. Each video is 50–150 frames, and the violent and non-violent videos are taken from real-life, everyday situations. Several pictures from the movies are displayed in Fig. 2, with the first row displaying violent scenes and the second row depicting non-violent ones.



**Fig. 2. RLVS dataset samples for (a) violence and (b) non-violence.**



### 3.2 Proposed Approach

The block diagram provides a quick summary of all the procedures and stages involved in our methodology (Fig. 3). This diagram is divided into three phases: dataset preprocessing, model training and testing and validation. The initial stage, known as preprocessing, involves gathering raw data, cleaning it and adapting it for compatibility with a machine learning model. Thereafter, the models are trained for a specific task using either newly collected data or pre-trained modules. After the models have learned the fundamentals, they are tested across various applications to evaluate their performance in real-world scenarios. Each procedure is discussed in detail below.

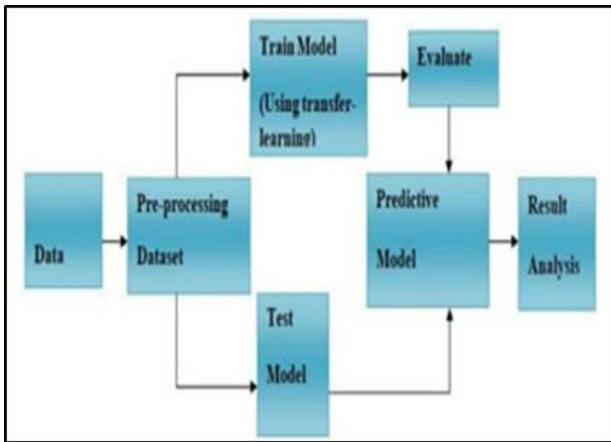


Fig. 3. Proposed model's block diagram

#### 3.2.1 Data Pre-processing

Inaccuracies and missing values are common in real-world data, and improper formatting can prevent machine learning models from effectively using them. Data pre-processing can enhance a dataset's accuracy and quality by eliminating missing or inconsistent data values caused by human or computer error, thereby improving its reliability. The data are guaranteed to be consistent. When presenting the suggested architecture, inadequate skeletal detection can result in information loss. Two pre-processing techniques, namely, histogram equalisation and gamma correction, are evaluated on the videos. Specifically, the contrast-limited adaptive histogram equalisation developed by Open CV (Open CV, 2022) is used to compute histogram equalisation, and  $\gamma = 1.5$  is utilised for gamma correction. The performance is significantly increased with gamma correction. The results are shown in Fig. 4. The gamma correction

for an image  $I$  where the pixel values fall between  $[0, 255]$  can be determined as follows:

$$I' = (I/255)^{\gamma} \times 255. \quad \dots(1)$$

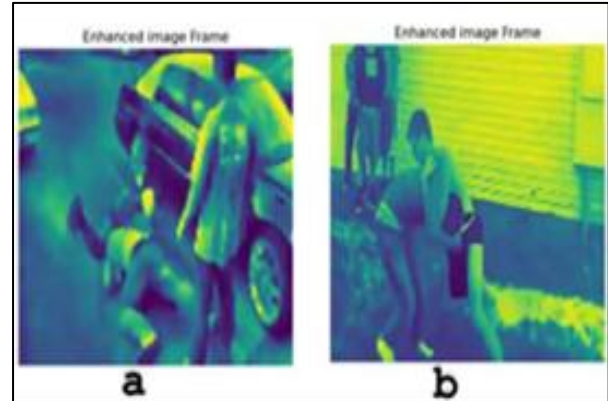


Fig. 4. a. Samples from the model with Gamma correction; b. Samples from the model without Gamma correction.

#### 3.2.2 Data Partitioning

The dataset is divided into testing and training sets, with the former comprising 20% of the photos and the latter consisting of the remaining 80%. The main difference between the two sets is that the training data have ground truth labels for every image, whilst the testing images do not. This situation allows us to evaluate the model, test it with previously unseen data and run tests according to our protocols.

#### 3.2.3 Training and Testing Models

The loss, cost function and accuracy are calculated during each epoch (going through all the training samples once) to train the proposed network layers at some epochs. The 'Sparse Categorical Cross entropy' cost function is utilised in this case to minimise overfitting. In VGG-16, a batch size of 32 is used for training to develop a head model with a fully connected layer for classification, utilising transfer learning techniques. After the evaluation of the training models, a classification report containing the precision, F1 score and recall values is generated. Validation is conducted on these models using datasets of real-world violent incidents to assess their performance.

### 4. Analysis of Results

Once the model is created, and the desired outcome is achieved, whether the model is

producing high-quality outcomes must be determined. A confusion matrix can be used to show the trained models' success rate to evaluate accuracy [36]. The variable value in Fig. 5 can be either positive or negative. The predicted data are shown in rows, and the actual data are presented in columns. True Positive: The actual data are positive and predicted as positive. Equation (2) can be used to determine the modelling accuracy. Equation (3) states that recall indicates the proportion of correctly predicted outcomes amongst all correctly predicted outcomes. The error rate (Equation (4)) indicates the percentage of the model's predictions that are erroneous. A low error rate indicates that the model effectively operates.

$$\text{Accuracy} = \frac{TP+TN}{TP+TN+FP+FN} \quad \dots(2)$$

$$\text{Recall} = \frac{TP}{TP+FN} \quad \dots(3)$$

$$\text{Error rate} = \frac{FP+FN}{FP+FN+TP+FP+TN+FN} \quad \dots(4)$$

|                  |              | Actual Values |              |
|------------------|--------------|---------------|--------------|
|                  |              | Positive (1)  | Negative (0) |
| Predicted Values | Positive (1) | TP            | FP           |
|                  | Negative (0) | FN            | TN           |

Fig. 5. Confusion matrix.

The method is evaluated by calculating the precision, recall and F1-score to illustrate how the proposed model worked on the dataset (Table 2).

**Table 2,**  
**Evaluation for classification on the RLV-Crime dataset.**

| Evaluation Metric | (Values%) |
|-------------------|-----------|
| Precision         | 0.69      |
| Recall            | 0.50      |
| F1-score          | 0.58      |

Table 3 presents a comparison of the training and validation accuracy for both models. The CNN model with gamma correction achieves a training accuracy of 99.4% and a validation accuracy of 99.74%. Meanwhile, the model without gamma correction achieves a training accuracy of 97.5% and a validation accuracy of 97.13%. These results demonstrate that gamma correction enhances the model's overall performance, particularly in validation accuracy, which is critical for assessing how well the model generalises to new, unseen data. Furthermore, these results underscore the

effectiveness of gamma correction in improving the robustness and reliability of the CNN model for violence detection.

**Table 3,**  
**The values of both train accuracy and validation accuracy for the RLV with CNN.**

| Model                        | Train accuracy | Validation accuracy |
|------------------------------|----------------|---------------------|
| CNN with Gamma correction    | 99.4 %         | 99.74 %             |
| CNN without Gamma correction | 97.5 %         | 97.13 %             |

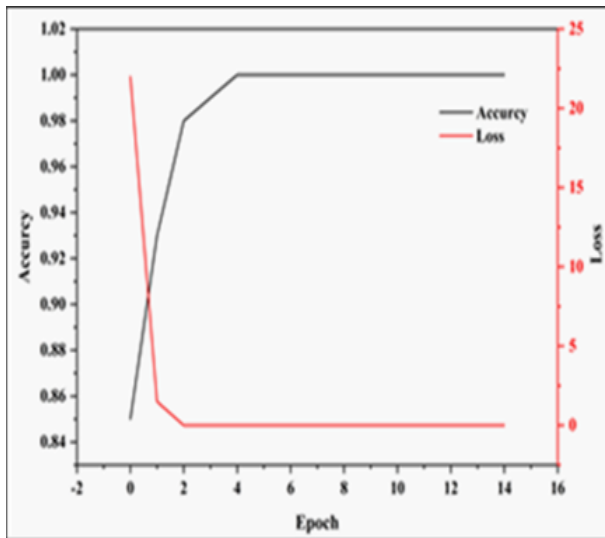
The proposed method is compared with a 3D convolutional network using accuracy (Acc) as the assessment parameter. Table 4 compares the Acc values for binary classification using our proposed method (CNN-SVM) with the different models for anomaly detection. We categorise all abnormal events as 'Anomaly' and non-anomalous data as 'Normal'. The test classifier displays the likelihood of a proper categorisation for aberrant events. Thus, our model outperformed the prior techniques (Table 4).

**Table 4,**  
**Acc for binary classification on the RLV-Crime dataset.**

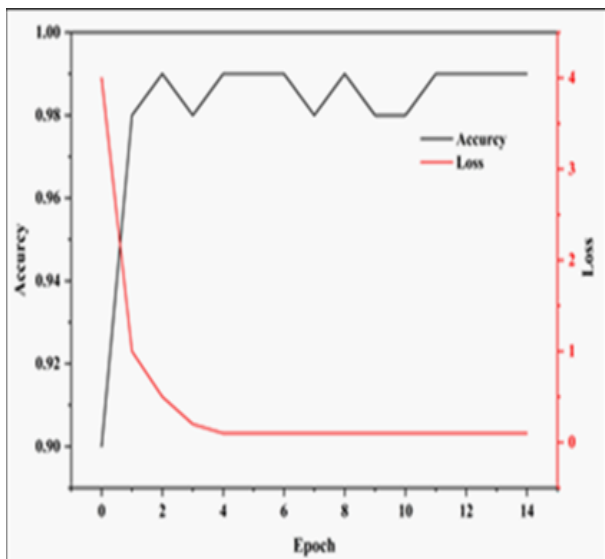
| Model  | Acc (%) |
|--|---------|
| SVM Baseline                                   | 50.0    |
| Zhong et al. (C3D) [37]                        | 81.08   |
| Sultani et al. (loss without constraints) [38] | 74.4    |
| our proposed model                             | 99.7    |

Fig. 6(a) shows the training curve for binary classification in terms of accuracy and loss value using our suggested technique with gamma correction. Fig. 6(b) depicts the training curve for binary classification without gamma correction. The diagram illustrates the training curves of the CNN with an SVM classifier, comparing performance with and without gamma correction. In both cases, the model shows a rapid decrease in loss and a sharp increase in accuracy during the initial epochs, indicating effective learning. However, the gamma-corrected model (Fig. 6(a)) more quickly achieves lower loss and higher accuracy and stabilises at a slightly better performance level compared with the model without gamma correction (Fig. 6(b)). This notion suggests that gamma correction enhances the model's ability to learn and generalise from the training data, resulting in improved overall performance. The live detection system is applied,

where a streaming video, either from the source camera or the web camera, will be converted into data frames and predicted (Fig. 7).



(a)

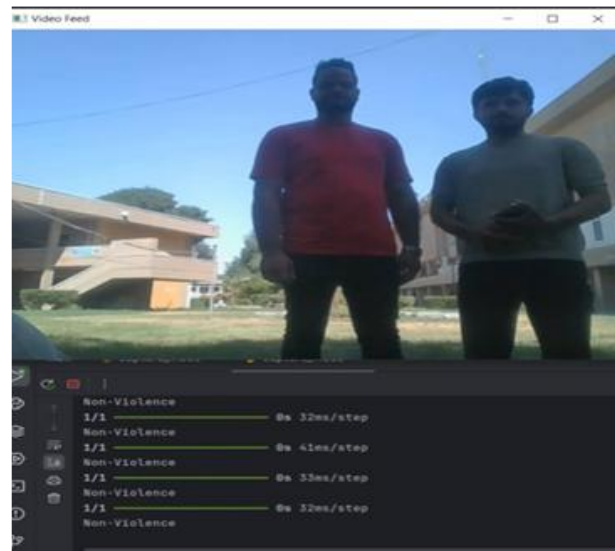


(b)

Fig. 6. Training curve for binary classification of RLV dataset with 2DCNN (a) with gamma correction, (b) without gamma correction.



(a)



(b)

Fig. 7. Output of the proposed method, for (a) violent, (b) nonviolence.

## 5. Conclusion

This study shows that deep learning methods, particularly CNN models combined with gamma correction, provide an effective method for identifying violent activities in surveillance footage. The model achieved a remarkable accuracy of 99% on the RLV dataset by leveraging the advantages of CNN's spatial feature extraction and integrating SVM for classification. The gamma correction step further enhances the quality of feature extraction, improving the model's reliability under varying lighting conditions. By contrast, traditional methods that rely on hand-crafted datasets and basic machine learning techniques exhibit low performance and limited generalisability. The model's ability to



handle real-time data and its computational cost efficiency make it a promising solution for real-world applications. Future research may explore additional datasets from various video sources to further enhance the model's generalisability. Another potential direction involves integrating more advanced deep learning models, such as ResNet or LSTM, to improve the detection of spatial and temporal features.

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## تقدير التنبؤ بالعنف في كاميرات المراقبة باستخدام CNN مع تصحيح جاما

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## المستخلص

شهدت السنوات الأخيرة ارتفاعاً كبيراً في نشر كاميرات المراقبة لتعزيز الأمن في كلٍّ من الأماكن العامة والخاصة. لا تزال الكثير من الشركات تستأجر شخصاً لمراقبة الكاميرات، ولكن نظراً لحدوث خطأ بشري في بعض الأحيان، فمن الراجح أن يتغاضى الفرد المستأجر عن بعض الأحداث الغريبة في موجزات الفيديو. وبالتالي قد يكون من غير المجدي قضاء الوقت والجهد في تتبع كاميرات المراقبة. في هذه الدراسة أبحث في تطبيق تقنيات التعلم العميق، وخاصة الشبكات العصبية التلافيفية (CNNs) وآلات الدعم المتجهة (SVMs)، للتنبؤ بالعنف في تدفقات فيديو المراقبة. من خلال استخدام تصحيح جاما كخطوة للمعالجة المسبقة، تم تحسين نموذج CNN المقترح لاستخراج السمات المكانية الأساسية من إطارات الفيديو، مما يعزز بشكل كبير دقة اكتشاف العنف. تستفيد الدراسة من قدرات الوقت الفعلي لبيانات المراقبة، مع التركيز على مجموعة بيانات RLV، والتي تشمل مجموعة من السيناريوهات العنيفة وغير العنيفة. وحقق نموذج CNN-SVM الهجين الذي تم تطويره في هذا البحث دقة مذهلة بنسبة ٩٩٪، متفوقاً على الطرق التقليدية ومظهراً قدرات استخراج السمات المكانية القوية. فضلاً عن ذلك، يتناول هذا البحث تحديات المراقبة بالفيديو في الوقت الفعلي من خلال ضمان قابلية التوسع والتطبيق العملي، مما يوفر حلاً قوياً لتعزيز تدابير الأمن في الأماكن العامة والخاصة.